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## ANVCE DESIGN SUMMARY REPORT (NEAR TERM) (U)

FINAL TECHNICAL REPORT

15 November 1976

Prepared Under CONTRACT ND. N00024-74-C-0924 MODIFICATION NO. P00017 DATA ITEM 0004

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#### ABSTRACT

(U)

Mula give and The report describes the point design of a 3000-long ton (29,892 kilo-Newton) Surface Effect Ship (SES) that meets the near term requirements of the Office of Advanced Naval Vehicle Concepts Evaluation (ANVCE). The point design is a **weaponized** testship, a concept that is a step toward a new class of fully combatant SES's and that is a logical progession from today's technology.

- (U) The SES point design is described in overall terms of General Description, Vehicle Performance, Maneuvering, Range, Payload, Weights, Volumes, Stability, Geometric-Form, and Ride Quality. Subsystems further described are Structures; Propulsion; Electrical; Command, Control, and Communications; Auxiliary; Outfitting and Furnishings; and Combat System. The report **also** includes sections addressing Logistic Considerations; Survivability and Vulnerability; and Technical Risk.
- (U) The near term point design SES is shown to be a cost-effective, minimum risk, and high performance means of satisfying ANVCE requirements.

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1/ INTRODUCTION

- (U) This report describes the point design of a near term (1980) Advanced No WM Naval Vehicle Concept Evaluation (ANVCE) Study 3,080 LT (29,892.1 kN) Surface Effect Ship (SES). The point design has been developed in accordance with Modification PO0017 to Contract N00024-74-C-0924 for the SES Project Office (PMS-304).
- (U) The data in this report are for a weaponized test ship and were originally submitted in response to RFP N00024-76-5342(S). The SES was developed in accordance with 'Large Surface Effect Ship (LSES) Top Level Requirements (U)", Chief of Naval Operations, 28 May 1976, Rohr Document No. CDC-C-76-076 CONFIDENTIAL.
- (U) The design was documented in Rohr Industries, Inc., 'Technical Proposal for Design and Construction of a Large Surface Effect Ship," in five (5) volumes tonsisting of 34 books and 16 appendices, dated 19 July 1976, CONFIDENTIAL, as amended by "Rest and Final Proposal for the Design and Construction of a 3,000-Ton Surface Effect Ship, Volume I - Management and Technical Change Summary," dated 12 October 1976 (with four (4) appendices). The near term SES design is not a combatant ship.

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(U) The near term SES design is presented In the format specified in the Office of Advanced Naval Vehicle Concept Evaluation (ANVCE) document WP-005A, "Point Design Description,' dated 13 August 1976. The terms ."3K", "near term ANVCE point design", and "1980 point design" SES are used synomously throughout the report to refer to the same design concept.

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- (U) The near term point design is described in English, as well as in SI (metric) units of measurement. The point design was developed with -English units as the primary standard of measurement. SX conversions shown in the text within parentheses conform to American National Standard Z210.1-1973, "Metric Practice Guide", 15 March 1973, American Society for Testing and Materials, which has been approved by the Department of Defense and its use stipulated by the ANVCE Project Office.
- (U) The near term SES performance data for range and speed were developed in accordance with the ANVCE design guidelines with the following exceptions:
  - \*Lightship margins were not computed on the basis of a 15% reservation including service life but rather on a 7% reservation plus a fixed 25 LT (249.1 **kN)** service life allowance.
  - SWBS Croup-410, 440, 450, 460, 470, and 480, as well as 700 and military payload related variable loads, were not drawn from the near term "ANVCE Combat System Data Sheets for AAW, ASW, SSW (U)", Vol I and II, dated 30 June 1976, but were developed in accordance with 3KSES TLR specifications and government-furnished information received in the course of the performance of phase IIA 2000-ton SES program activities,
  - The tail pipe (trapped fuel) allowance was adjusted to reflect ANVCE guidelines (2% deep tank, 5% flat tanks). In addition, range and payload data were presented on the basis of the ANVCE definition of payload contained in "Definition of Terms" ANVCE WP-002 dated 2 April 1976. Appendix A, Subsection A.2.11.1 contains a more detailed discussion of these areas,
  - The marine fouling allowance was taken as that corresponding to a 1.0 mil (25.4 µm) surface finish.

- (U) No engineering effort was expended to generate data for a near term SES point design report section or subsection where that information was not developed for the 3KSES in response to RFP NO0024-76-5342(S).
- (U) In addition, no engineering effort was expended where near term point design data existed, or where ANVCE format or design/environmental standards required a <u>major</u> effort in reformating for compatibility with ANVCE standards. Data in those instances are furnished in the formats used to meet 3KSES development specifications with appropriate notations delineating the assumptions and criteria utilized.
- (U) This report contains the following major sections (subsections are delineated in more **detail** in the table of contents):

<u>Section No,</u>	Content
1/	Introduction
1/	Incroduction
2/	Vehicle General Description
2.1	Principal Characteristics
2.2	Vehicle Performance
2.3	Ship Subsystem Descriptions
2.4	Survivability and Vulnerability
3/	Logistic Considerations
3.1	Reliability and Availability
3.2	Maintenance Concept8
3.3	Overhaul Concept
3.4	Supply Support Concept
3.5	Human Engineering
3.6	System Safety
4/	Technical Risk Assessment

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Appendices
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(U)

A	Design	Proces	S
В	Drawings	and	Diagrams
С	Equipmen	t Lis	ts

- (U) Finally, the LSES TLR of 28 May 1976 defined ship displacements in the following terms:
  - o Full Load Displacement (FLD) would be approximately
     3000 long tons (29,892.05 kN) and would characterize
     a ship complete and ready for service in every respect.
  - o Light Ship Displacement would be a complete and empty ship with all operating fluids less fuel (SWBS Groups 100 through 700 plus margins).
  - o Mean operating Displacement (MOD) would be characterterized for two conditions:
    - o MOD-50; A complete and loaded ship ready for service in every respect with not more than 50% usable fuel.,
    - o MOD-10; A minimum loading condition for maximum speed operation in any sea state where the ship was complete and ready for service in every respect for service in every respect with not less than 10% usable fuel.
  - o Capacity Load Displacement would be a complete and loaded ship with all fuel tanks filled to maximum operating capacity and ready for service in every respect.

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(U) A variety of performance and **design** data were developed in relation to these displacement definitions and for the near term SES point design they have been referenced in a number of the subsections that follow.

2/ VEHICLE GENERAL DESCRIPTION

#### (U) 2.1 PRINCIPAL CHARACTERISTICS

- (U) 2.1.1 SUMMARY -- The Near Term Point Design SES illustrated in Figure 2.1-1 is a weaponized testship, is designed for high speed operation in an open ocean environment, has an extended range capability, and carries a military payload. Primary missions are SES concept evaluation, demonstration of weapon system compatibility, and determination of potential military value. Characteristics are summarized in Table 2.1-1.
- (U) The following subsections describe the ANVCE near term point design SES in detail -- Section 2.2 outlines Vehicle Performance, Section 2.3 contains ship subsystem descriptions, and Section 2.4 addresses survivability and vulnerability.
- (U) The point design, in the on-cushion mode, operates on the captured air bubble principle to reduce hydrodynamic drag and achieve high speeds. In the off-cushion mode, it operates as a displacement hull. The ship is capable of maneuvering in both modes including turning, accelerating, decelerating, and backing, and can also hover in the on-cushion mode.

(U) The principal ship dimensions ore shown in Figure 2.1-2. The 266.25 feet (81.15 m) length overall and 108 feet (32.92 m) maximum beam satisfy the volumetric and performance requirements. The maximum beam permits transiting the Panama and Suez Canals. Effective cushion dimensions are 221 feet (67.36 m) length and 85 feet (25.91 m) beam. A cushion height of 18 feet (5.49 m) was selected to ease ship motions and structural loads in Sea State 6. The full load displacement is approximately 3,000 long tons (29,892.05 kN) including all contract margins and mission fuel load. Table 2.1-1 shows the principal characteristics of the design.

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# Table 2.1-1 (C). Principal Characteristics of the Near Term 3000 Ton Point Design SES **(U)**

OPENATION:	Weaponized testship with primary missions of SES concept validation, demonstration of weapon system compatibility and evaluation of military utility.
DIMENSIONS:	
a Length Overall <b>(LOA)</b> Ft. <b>(m)</b>	
🛭 Maximum Beam, Ft. (m)	
Wet Deck Height (above baseline - ABL), Ft.	(m)
• Cushion Area, $F_{L}^{2}(\mathfrak{m}^{2})$ .	
Effective Cushion Length, Ft. ( <b>m).</b>	
• Main Deck Height (ABL), Fe. (m)	
Sidehull Fence Depth (BBL), FT. (m)	3.33 (1.02)
• Stabilizer Fin Depth (BBL), Ft. (m),	
• Hullborne Design Waterline (ABL), Ft. (m)	•
• Maximum Navigating Draft, Ft. (m)	
POWER PLANIS :	
Propulsion Engines	Four (4) General Electric (CE) LM-2500 or four (4) Turbo Marine FT-9A-2A
• Propulsors	. Four (4) Aerojet Liquid Racket Co. (ALRC) Wateriet Pumps
• Lift Engines	. Two (2) C.E. LM 2500's
• Lift Fans	. Six (6) <b>ALRC</b> Centrifugal, Variable Geometry
CREW AND COMPLEMENT :	
a Vehicle . , , . ,	8 Officer, 8 CPO, 49 Enlisted
• Secondary Vehielaa (Helicopters/RPV's)	. 4 Officer, 1 CPO, 14 Enlisted
SYSTEMS:	
. Structures	All aluminum <b>(5456)</b> , welded <b>structure consisting</b> of longitudinally stiffened plate supported by transverse <b>web</b> frames.
. Electrical ,	. Independent 60 kz and 400 Hz subsystems, each powered by three (3) 375 kW Gas Turbine cenerator Sets interconnected by a ring bus.
• Steering	Thrust vectoring, differential thrust, and thrust reversal with the outboard waterjet pumps only.
• Propulsion	Dual <b>vate:jet propulsors</b> in each sidehull, <b>driven</b> by in-line gas <b>turbines</b> through separate reduction gear trains. Pump feed in each <b>sidehull</b> is with a <b>single</b> semi-flush inlet with variable roof ramp.
• Lift	Three (3) centrifugal. <b>variable geometry</b> fans in each <b>sidehull,</b> driven by a single <b>gas turbine</b> through reduction gear.



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Table 2.1-1 (C)(Cont'd)

• Seal. , . , , , ,	Advanced, two-dimensional, planing bow and • tatu seals, enclosed between sidebulls.		
a Ship Integrated Control , ,	Closed loop lift system fans and/ci of • uriliaz systems, c. integrated Control for steering, propulsion, and succmatic control of ride (lift valve). Performance monitoring scric plant, and discribution integrated Crol for steering, propulsion, and succmatic control of ride (lift valve). Performance monitoring scric plant, and discribution integrated Crol for steering, propulsion, and succmatic control of ride (lift valve). Performance monitoring scric plant, and discribution scric plant, and scrip scrip scrip script script script script script script sc		
• Outfit and <b>Furnishings.</b> , , , .	Hull compart: facion, access and safety con- forming to Navy scandards with generous habit- ability provisions.		
e Auxiliaries:	- extr		
<ul> <li>Heating, Ventilating and Air Conditioning (HVAC).</li> </ul>	400 Hz powered, axial flow fan, packaged air conditioning (A/C) plants with dual-duct mixing boxes.		
• Refrigeration , ,	Two (2) $400$ Hz, powered centrifugal, packaged refrigeration plants.		
• Firemain end Auxiliary Seawator	Open bop, horizontal system capable of 1600 gpm (0.10 m3/s) at 125 ps1 (861.84 kPa).		
• Scupper and Deck Drains	Standard gravity drainage system utilizing glass reinforced plastic (GPR) piping.		
<ul> <li>Plumbing Drains (Soil and Waste)</li> </ul>	Vacuum assisted collection discharged overboard or to holding tank.		
. Main Drain	Combines pumps and eductars for main machinery space dewayering and bilge water removal.		
• Secondary Drain ,	Seawater actuated eductora for miscellaneous drainage of <b>spaces</b> not <b>served</b> by main drain system		
• Potable and Brash <b>Water.</b> . ,	Standard shipboard system operated to minimize storage with GRP piping used extensively.		
<b>9 Cooling Water</b> and Auxiliary Fresh Water Cooling	Two (2) systems (Freon and sea Water cooled) are provided. Closed loop design meeting Navy standar		
• Fuel Cil	Provides for filling, storage transfer and puri- fication of JP-5 fuel for ship use.		
● ∛�೫©♦೫□■ Fuel	$T_{\mbox{\scriptsize vo}}$ (2) JP-5 fuel service tanks. filled from ships storage through filter coalescerr for helicopter service.		
• Compressed Air , , ,	Low pressure sir from engine bleed and hieh pressur air from 3,000 psig (20.68 mPa) compressor are provided.		
• Nitrogen	Charging system is capable of supplying 70 to 3.000 paig (0.48 to 20.68 MPa) of oil free nit rogen.		
Fire Extinguishing	Consists of high capacity AFFF, fixed flooding halon and high expansion foam.		
• Hydraulic	Closed 3,000 psig (20.68 MPa) system capable of delivering 274 gpm $(0.017 \text{ m}^3/\text{m})$ .		

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Auviliaries (Cont'd.)		•		
. Replenishment at Sea (RAS)	VERTREP fuel, pot conveyor	area, port/starboa able <b>vater</b> static are <b>provided.</b>	rd alongside ons, <b>and vert</b> :	RAS for ical flow
Anchoring	Utilizes and assoc	a 3,000 Lb. (13.) iated cable <b>winc</b>	34 <b>kN) Denfor</b> h.	th anchor
. Mooring and Towing	Comprised chocks, ar	of <b>three (3)</b> cap nd towing <b>padeye</b>	pstans, as we s.	ll as bits.
• Boat Handling and Scowage	Six (6) 2! driven, ir davit.	<b>i-man</b> life rafts a flatable rescue	nd an outboa craft with ክ	urd motor andling
WEIGHTS :	LM	2500	F T	- 9
● Full Load Displacement (FLD) (LT: kN)	3,000.0	(29,892.10)	3.000.0	(29,892.10)
<ul> <li>Empty Weight (Lightship + Margins) (LT: kN)</li> </ul>	1,661.2	(16,552.40)	1,699.3	(16,932.60)
• Fuel Weight (Capacity) (LT; kN)	1,838.9	(18,323.80)	1,838.9	(18,323.80)
• Usable Fuel at FLD (LT; kN)	1,179.9	(11,756.50)	1,141.6	(11,374.90)
• Unusable Fuel <sup>(1)</sup> at FLD (LT; kN)	64.6	(643.68)	64.6	(643.68)
• Other Load (LT;kN)	91.8	(914.70)	91.8	(914.70)
. Fuel Volume (Capacity) (Ft <sup>3</sup> ; m <sup>3</sup> )	80,985.00	(2,293.2)	80,985.0	(2,293.00)
MOBILITY/PERFORMANCE SUMMARY:	lm 2500 <b>FT-9</b>		-9	
Cushion Pressure (psf, kPa)	342.0	(16.38)	342.0	(16.38)
<ul> <li>Maximum Speed in Caim Water (kts; km/hr) at MCP and MOD-50</li> </ul>	66.0	(122.0)	92.0	(170.0)
<ul> <li>Maximum Speed at 3.94 Ft. (1.20 m) Signifi- cant Wave Reight and MOD-50 (knots; km/hr)</li> </ul>	64.0	(119.0)	85.0	(157.0)
Hump Margin at 3.94 Ft. (1.20 m) Signifi- cant Wave Height, MOD-SO and MIP (X)	28%	(287)	72%	(722)
Best Range Speed, Calm Water (Kts; kM/Hr)	66.0	(122.01	90.0	(148 .0)
<ul> <li>Best Range Speed at 3.94 (1.20 m) Signifi- cant Wave Height (Kts; km/Br)</li> </ul>	64.0	(119.0)	76.0	(141.0)
. <b>Time</b> co <b>Accelerate</b> to Cruise Speed in Calm Water (Sec)	330,0	(330.0)	120.0	(120.0)
• Time to Accelerate to Max Speed in Calm Water (Sac) (2)	330.0	(330.0)	260.0	(260.0)
<ul> <li>Time Co Decelerate from Max Speed to 0 in Calm Water (Sac)</li> </ul>	32.0	(32.0)	31.0	(31.0)
<pre>§ Stopping Distance (Pt; km)</pre>	1,400.0	(0.43)	1.920.0	(0.59)
<ul> <li>Turn Radius at 40 Knots (20.58 m/s) spec (Ft: km)</li> </ul>	4.009.0	(1.22)	3,200.0	(0.98)
• Range (nm; &con	2,950.0	(5,472.0)	3.000.0	(5,565,0)

Table 2.1-1 (C) (Cont'd)

(1) Per ANVCE Specification (2% deep tank, 5% flat tank.)

(2) MIP applied in last minute of acceleration to avoid an asymptotic approach to maximum speed.





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Table 2.1-1 (C) (Cont'd)

	SI2IEM:	Qty	System
	Armament	1	MK92/3 FC5
		1	STIR (Space and Weight)
		1	Harpoon FCS
			Torpedo Fire Control Panel MK309
		1	UWYCS (MK48 Torpedo) (Space and Weight)
		8	Vertical Missile Launchers
		a a	Standard Missile (RIM-66B Mod, No Reloads) Harpoon Launchers
		а	Harpoon Missile (RCM-84-1, No Reloads)
		2	Torpedo Tube MK25/1 (Space and Weight)
		2	MK48 Torpedo (Space and Weight)
		2	Torpedo Tube MK32/5
		6	MK46/1 Torpedo (No Reloads)
		2	Close-In Weapons System MK16/0 (Space & Weight
_ I	Underwater, Surface and Air		
	Serveillance and EW	1	Air Search Radar AN/APS-125
			Surface Search Radar AN/SPS-55
		1	DPEWS AN/SLQ-31(V-2) or AN/ SLQ-32(V-2)
			TACTASS AN/SQR-19
		ï	Localization Sonar AN/AQS=13D
		1	CHF Telem Receiving Set AN/SKR-3A
		1	Sonar Receiving Set AN/UQR-1 (Mod)
		80	DIFAR Sonobuoy AN/SSO-53
		S 0	DICASS Sonobuoy AN/SSQ- 62
	Identification and Classification (IFF)	2	Interrogation Set AN/UPX-25(U)
		1	Transponder Set AN/UPX-28(U)
. (	Command and Control	1	computer AN/UYK-7 (V) <sup>(3)</sup>
		-	Display Croup AN/UYA-4 (V) (4)
		1	LinkTT
٠	Secondary Sub-Vehicles		
	. Sub-Vehicles	2	Helicopters SH-3H or 1 XV-8B VSTOL
		10	Mini-RPV (Space)
			m 1 11/6/1

(3) Growth for an additional AN/UYK-7(V) Computer.

(4) Includes three (3) 0J-194(V)3 PPI Consoles with growth for two (2) additional consoles.





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2ND BECK 31'-0" (9.45 ● ① ABL 3RD DECK 18'-0" (6.71 m) ABL WET DECK 18'-0" (5.49 . ) ML 1ST PLATFORM 10'-0" (3.05 . JABL

STABILIZER 10'-4 5/8" (3.1 ) BBL

3'-4" (1.02 m) BBL

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LONG BHD 14"-8" (33.53 m) OFF g ...

PLAN VIEW 03 LEVEL 68'-6" (20.88 ■ ) ML -02 LEVEL 60'-0" (18.29 =) ABL 01 LEVEL 49"-0" (14.94 m) ABL MAIN DECK 40"-0" (12.19 m) ABL .

**BUD 56** 

+-1-4





LOA 266' - 3" (81.15 m)

BID 28

-1-4-1-4-4-4-4

**BIED 14** 

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E SHIP

BIID 42

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Figure 2.1-2 (U): Near Term Point Design SES Configuration (U)

- (U) 2.1.2 GENERAL ARRANGEMENT DRAWINGS -- The general arrangement drawings of the ship are contained in Appendix B. Topside combat system locations are shown on the drawings. The drawings are:
  - Outboard Profile
  - Inboard **Profile**
  - 01 Level and Above
  - Main Deck

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- Second Deck
- Third Deck
- Wet Deck
- Transverse Section
- Sldehull Inboard Profile
- Bow and Stern Views
- . Tank Arrangements and Tank Capacities
- (U) The drawings are grouped in Appenxlx B, Section B.1, for consistency of report format and the benefit of the reader. These drawings are completely up to date and definitive in those cases where minor discrepancies may be found in supporting drawings used elsewhere in this report.

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- (U) 2.1.3 COMBAT SYSTEM DRAWINGS -- Weapons and sensor coverage on the near term SES are shown on drawings contained in Appendix B, Section B.2. The drawings illustrate coverage for:
  - Air Surveillance Radar (AN/APS-125)
  - Surface Search Radar (AN/SPS-55)
  - Collision Avoidance Radar
  - MK92 Fire Control System (CAS)
  - \*STIR (MK54/0)

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- . MK16/0 Close-In-Weapon-System
- AN/SLQ-31 (V2) EW System 1R Sensor
- (U) The drawings are grouped in Appendix B for consistency of report format and the benefit of the reader.

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- (U) 2.1.4 SHIP INTERFACES -- The near term SES is designed to functionally interface with other U. S. Navy ships, craft, shore commands and aircraft during operational deployment, and with Navy and other logistic facilities for support. The primary interface characteristics of the ship are:
  - \*Vertical underway replenishment (VETREP) with the capability for rapid strike down.
  - Underway alongside fuel and water replenishment (CONTREP)
  - . In-flight refuleing of helicopters (HIFR)
  - · Capability of being towed
  - Capability of receiving support services, including power, water, fuel and replenishment stores, when secured to a shore facility.
  - \*Capability for precision anchoring in depths not exceeding 40 fathoms (73.15 m)
  - Mooring system to provide means for mooring alongside a pier or ship.
  - . Provide fuel and oil to helicopter and VTOL aircraft
  - \*Capability of maintaining visual and radio communication with other ships, aircraft, and shore facilities

#### (U) 2.2 VEHICLE PERFORMANCE

- (U) 2.2.1 THRIJST, DRAG, AND POWER -- The predicted drag/displacement ratios for the near.term SES, as a function of ship speed and significant wave height at FLD, are shown in Figure 2.2.1-1, Performance is shown with the ride control system off, and with the ride control system operating at a level sufficient to meet or better the Rohr ride criteria shown in Figure 2.2.1-2. Comparable data at the MOD-50 condition are shown in Figure 2.2.1-3. In addition, a plot illustrating the speed dependent character of the drag components is presented in Figure 2.2.1-4. These data are based on analytic predictions which have been validated and enhanced by correlation with model test data. While no allowance was made for marine fouling, a 1.0 mil surface finish was assumed for all hydrodynamically wetted surfaces.
- (U) Figure 2.2.1-5 presents the propulsion system efficiency of the near term SES vs. speed and significant wave height. These data are based on the assumption that the propulsion power could be set at that level necessary to maintain a constant speed.
- (U) The transport efficiency of the near term SES as a function of speed and significant wave height is shown in Figure 2.2.1-5. In accordance with the definitions presented in ANVCE WP-002, dated April 2, 1976, transport efficiency was defined by:

```
Full Load Displacement (3000 LT; 29,892.1 kN) x Speed-(Independent Variable
Total Power Required at Half Fuel (2400 LT; 23,913.6 kN) Condition
```

(U) Figure 2.2.1-7 presents the maximum speed performance vs. significant wave height for the half fuel (MOD-50) condition. These predictions are based on the ride-control-off data, Figures 2.2.1-1 and 2.2.1-5 through 2.2.1-7 and the available 'thrust plotted in Figure 2.2.1-8.



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Figure 2.2.1-2 (U): Rohr SES Ride Criteria (U)



Figure 2.2.1-3 (C): 3KSES Drag/Weight Ratio Versus Speed and Significant Wave Height

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Figure 2.2.1-4 (C): Near Term SES Drag Breakdown (U)

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Figure 2.2.1-5 (C): Near Term SES Propulsive Efficiency Versus Speed and Significant Wave Height (U)

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Figure 2.2.1-6 (U): Near Term SES Transport Efficiency Versus Speed (U)

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Figure 2.2.1-7 (C): Near Term SES Maximum Speed Versus Significant Wave Height (U)

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Figure 2.2.1-a (3): Near Term SES Available Thrust Versus Speed (U)

- (U) 2.2.2 MANEUVERING -- The steady state on-cushion turn performance of the near term SES configured with P&W FT-9 propulsion engines, in calm water and at an 83 percent fuel condition (2800 LT; 27,899.2 kN), is shown in Figures 2.2.2-1 and 2.2.2-2. After deceleration to a speed of 45 knots (23.15 m/s) for turns initiated at higher speeds, all four (4) waterjet pump nozzles are deflected an amount sufficient for the desired turn. The data shod the steady state turn performance characteristics after the initial lateral transient motions have decayed.
- (U) Figures 2.2.2-3 and 2.2.2-4 present the acceleration times from a standing start as a function of speed and **significant** wave height for LM-2500 and FT-9 engines, respectively. These maneuvers were computed on the basis that both the lift and propulsion engines are set at MCP and that the bow seal is partly retracted through hump transition. At low speeds, however, the power levels were limited to those imposed by cavitation limits of the **waterjet** inlets or pumps. The use of MIP during the last minute of the acceleration maneuver avoids an asymptotic approach to the maximum speed.
- (U) Figures 2.2.2-5 and 2.2.2-6 present the emergency deceleration performance as a function of speed and significant wave height for LM-2500 and FT-9 engines, respectively, as shown in Figures 2.2.2-7 and 2.2.2-8. Corresponding distances are shown in Figures 2.2.2-7 and 2.2.2-8. These maneuvers were accomplished by:
  - Engaging the thrust reversers,
  - Applying maximum continuous power to the outboard propulsion engines,
  - Reducing the inboard engine power to "idle", and
    @Retracting the stern seal by setting the stern seal fan variable geometry valves to "shut off."

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(U) These procedures cause the ship to decelerate in a bow up attitude and avoid the possibility of undesirable pitch motions. Engagement of the thrust reversers requires 3.0 seconds. The remaining emergency stopping procedures are effected during this time interval.

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Figure 2.2.2-2 (C): Near Term Steady State Turn Rate Versus Speed (U)









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Figure 2.2.2-S (C): Near Term SES Time to Stop Versus Speed with LM2500 Engines (U)

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Figure 2.2.2-6 (C): Near Term SES Time to Stop Versus Speed with FT-9 Engines **(U)** 

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Figure 2.2.2-7 (C): Near Term SES Stopping Distance Versus **Speed** with **LM2500** Engines **(U)** 

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Figure 2.2.2-8 (C): Near Term SES Stopping Distance Versus Speed with FT-9 Engines (U)

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- (U) 2.2.3 RANGE AND PAYLOAD The near term ANVCE SES exceeds the required range by about 10 percent with FT-9 engines and nearly attains the goal with LM2500 engines. Range is computed by integrating speed and fuel rate over the interval from full load displacement (FLD) to the near empty weight of lightship displacement plus unusable fuel.
- (U) The range and endurance characteristics are presented in Figures 2.2.3-1 through 2.2.3-3, as influenced by speed, significant wave height and payload. The characteristics are shown with the ride control. system off and with the ride control system operating at a level sufficient to meet or better the ANVCE ride criteria. These data are based on the resistance data presented in Figures 2.2.1-1 and 2.2.1-3 and the propulsion system efficiencies reflected in the fuel consumption characteristics of FT-9 marine gas turbine engines presented in Figure 2.2.3-4.

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Figure 2.2.3-1(C) Range vs. Payload at Full Load Displacement for Head Seas with Winds **(U)** 

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- (U) 2.2.4 WEIGHT AND VOLUME SUMMARY -- A summary of the light ship weight, variable load, contract margins and full load weight of the ANVCE near term SES is presented in Table 2.2.4-1. The ANVCE near term SES ship weights are identical to those of the Rohr **3KSES**. The summary represents the results of parametric studies, design iterations, and trade-off investigations performed during the **ANVCE** near term SES design effort.
- (U) Table 2.2.4-2 is a summary of weights for a similar ship with FT-9 engines installed in place of the baselined LM 2500 engines for propulsion. The propulsion plant weight and contract margins were adjusted to reflect this substitution. The fuel weight was then reduced to arrive at a full load displacement of 3000 long tons (29,892.1 kN). The ship volume summary is presented in Table 2.2.4-3.
- (U) The design light ship, the total of SWBS groups 100 through 700, is. the displacement of the ship ready for sea in every respect, but excluding all variable load items such as crew, stores, ordnance, and fuel. Operating fluids such as lube oil, hydraulic fluid, and entrained water in the inlet and propulsor are included in the design light ship. The variable load items include the 125 man crew; provisions and effects, stores and spares for a 15-day mission; ordnance; both ship and aircraft fuel; and fresh water for the ship when operating at FLD.

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			WEI	GHT	
GROUP		LONG TONS	SHORT TONS	METRIC TONS (1)	KILONEWTONS
100:	HUI, J. STRUCTUKE	805.0	901.6	817. 9	<u> </u>
200 :	PROPUR.SION PLANT	<b>190.</b> 5	213. 3	193. 5	1897.3
300 :	EI.ECTRICAL PLANT	61.8	69. 3	62.9	616.2
400:	COMMAND 6 SURVEILLANCE	67.0	75. 0	68. 0	667. 3
500:	AUXILIARY SYSTEM	196.6	220.2	199.7	1958.8
	567: Lift System	96.8	3 10	<b>8.4</b> 98	964.3
600	OUTFIT AND FURNISHINGS	156.9	175. 7	159.4	1563.0
700	ARMAMENT	51.4	57.6	52. 3	512.6
DESIG	IN AND BUILDERS MARGIN	132.0	147.9	134. 2	1315.6
EMPTY	WEIGHT (LIGHT SHIP)	1661.2	1860.6	1687. 9	3. 6552. 4
FOO:	LOADS: Crews Provisions <b>Stores</b> Fresh Water Ordnance Main Vehicle Sub-Vehicle Sub-Vehicle Fuel	14. 7 5. 8 5. 8 18. 6 17. 2 6. 6 23, 1 1246. 9	16. 6. 20. 19. 7. 25. 1396.	5       15.0         5       5.9         5       5.9         8       18.9         3       17.5         4       6.7         8       23.4         6       1267.0	146. 7 57. 8 57. 8 185. 2 171.9 66.0 229. 7 12424.6
1FULL	LOAD WEIGHT	3000.0	3360.0	3048.2	29892.1

## TABLE 2.2.4-1 (U): WEIGHT SUMMARY WITH LM2500 ENGINES (U)

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SWBS		WEIG	IT	
GROUP	LONG TONS	SHORT TONS	METRIC TONS (1)	KILONEWTONS
100: HULL STRUCTURE	805.0	901.6	817.9	8021.0
200 : PROPULSION	226.0	253.1	229.6	2251.7
300 : ELECTRICAL	61.8	69.2	62.8	615.6
400: COMMAND & SURVEILLANCE	67.0	75.0	68.1	667.2
500: AUXILIARIES	196.6	220.2	199.8	1959.0
567: Lift System	<b>9</b> 6.8	108	98.4 98.4	964.4
600 OUTFIT AND FURNISHINGS	156.9	175.7	159.4	1563.1
7 0 0 ARMAMENT	51.5	57.7	52.3	513.3
DESIGN AND BUILDERS MARGIN	134.5	150.6	136.7	1339.8
EMPTY WEIGHT (LIGHT SHIP)	1699.3	1903.2	1726.6	16931.6
FOO: LOADS:				
<b>Crews</b> Provisions Stores Fresh Water Ordnance Main Vehicle Sub-Vehicle Sub-Vehicle Fuel	14.7 5.8 5.8 18.6 17.2 6.6 23.1 1208.6	16. 6. 20. 19. 7. 25. 1353.6	5       14.9         5       5.9         5       5.9         8       18.9         3       17.5         4       6.7         9       23.5         5       1228.0	146.7 57.8 57.8 185.2 171.9 66.0 229.7 12042.2
FULL LOAD WEIGHT	3000.0	3360.0	3048.1	29892.1

TABLE 2.2.4-2.(U): WEIGHT SUMMARY WITH FT-9 ENGINES (U)

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(1)<sub>Non-ST Units</sub>

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TABLE 2.2.4-3 (U): VOLUME SUMMARY (U)

	INTERNAL	VOLUME <sup>(1)</sup>
FUNCTION	CUBIC FEET	CUBIC METERS
Main Propulsion (including main machinery box, uptakes, shafting)	119,034	3,371
Lift System	109,881	3,112
Personnel (including living, messing and all personnel support and storage)	104,454	2,958
Auxiliary and Electrical (machinery spaces other than main propulsion and lift outside main machinery box)	100,962	2,859
Payload (internal volume only)	150,955	4,275
Other (including passageways, maintenance spaces and all other <b>spaces</b> not include <b>d</b> in above)	147,663	4,182
TOTAL ENCLOSED VOLUME	732,949	20,758

(1) Total enclosed volume does not include tanks and other innerbottom spaces below third deck, or **helo** landing and any weather decks.

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diameter.

- (U) 2.2.5 STABILITY -- The stability of the near term SES was addressed for both zero speed and underway conditions. The results show that the SES has adequate stability to meet the required operating ranges of speed, sea state and displacement.
- (U) 2.2.5.1 Stability at Zero Forward Speed -- The hullborne stability at zero speed of the near term 3KSES has been evaluated in accordance with the Navy criteria of acceptability<sup>(1)</sup>. Two operating conditions that represent full,-load and **minimum** conditions were evaluated with:
  - A beam wind of 100 knots (185.2 km/hr), combined with rolling.
  - b. Topside icing

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- c. Crowding of personnel to one side
- d. High speed turning for roll stability (per Navy criteria<sup>(1)</sup>)
- (U) The intact stability at the MOD-10 condition with a beam wind of 100 knots (195.32 km/hr) combined with rolling produced the critical condition but with adequate stability as shown in Figures 2.2.5-1 and 2.2.5-2.
- (U) 2.2.5.1.1 <u>Static Stability in Hullborne Intact Condition</u> -- The static stability at zero speed was addressed by development of cross-curves of stability for a suitable range of ship displacement and for a range of heel angles from 0 through 90 degrees. The SES has a positive range of stability from 0 to 80 degrees as shown in Figure 2.2.5-3 and in Tables 2.2.5-1 and 2.2.5-2.
- (U) 2.2.5.1.2 <u>Stability in Damaged Condition</u> -- The fundamental adequacy of the SES with respect to reserve buoyancy and stability under conditions of hull damage in an open ocean environment has been addressed for the
  - (1) "Stability and Reserve Buoyancy of U.S. Naval Surface Ships", DDS079-1, dated 1 August 1975, Department of the Navy, Naval Ship Engineering Center,

- (U) full load and MOD-10 conditions per the Navy criteria and summarized for the following critical conditions:
  - a, Shell-to-shell flooding in compartments **II** and III, with the longitudinal extent of damage equivalent to 15 percent **LOA.** This produced the least freeboard as indicated in Figures 2.2.5-4 and 2.2.5-5. The criteria of acceptability **is** satisfied.
  - b. Unsymmetrical flooding with penetration up to the centerline and with a longitudinal extent equivalent to 15 percent LOA was investigated throughout the length of the hull. The worst case was found to be with the damage in compartment IV and V. The maximum heel in this case was 7.48 degrees. Figures 2.2.5-6 and 2.2.5-7 show this condition, Requirements of the criteria were satisfied.
  - c. Unsymmetrical flooding with penetration to the first longitudinal bulkhead (not less than 10 percent maximum beam) and a longitudinal extend equivalent to 50 percent LOA was investigated throughout the length of the hull. The worst case was found to be for compartments III and IV and V and VI flooded. However, the requirements of the criteria were satisfied. Figures 2.2.5-8 and 2.2.5-9 depict this condition.
- (U) In summary, the ANVCE near term SES meets and exceeds the stability requirements at zero speed and the reserve buoyancy criteria for Large Surface Effect Ships of the U. S. Navy,

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TACT STAPILITY ANALYSIS

DATE IJUN 28-76 CCMPUTER GFFSET NO ILSESPOOL CALG. NO. I N/A

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### 3KSES

LAP 1 240.00 FEFT

SEAM : 108.00 FEET NG. OF STATIONS : 51

SEAP WIND COMPINED WITH ROLLING & MEAN OPERATING (MOD-18) CONDITION +

HYDROSTATIC CHARACTERISTICS AT JFRO HEEL ANGLE

SEA WATER GISPLACFUPAT LONGITUGINAL CB (LCG) VERTICAL CG (FG) PAJIUM FREF-SURFACE TRANSU-RETACTRINE (MMT) TRANSUESE CB (TCD) PRIM (FUE 1 AFTWARD) CRAFT AT AP (MA)		1916.40 TONS 123.00 PT AFT PP 27.51 PT AFV 8954 238.08 TON-PT 235.47 PT AFV 8854 -6.61 PT FAM PAVL -1.52 PT 18.31 PT ABV 8844	LOAGITUMIAAL CO LOAGITUDIAAL C7 VEATICAL C0 VEATICAL C.0. LOAG. METACENTER ,	(LCG) = (LCF) = (AP) = (AG) =	ı	123.08 FT AFT FP 134.25 FT AFT FP 12.04 FT APV AFAL 27.74 FT APV AFAL 594.27 TON-FT/FICH 18.65 FT APV AFAL 18.65 FT APV RFAL
---	--	--	---	--	---	--

ATCHTING ARMS -VS- WEELS IN INTACT CONDITION

### WINC SPEED - 100.00 HNOTS

Y#\$H 1 -8.	.806		-3.459	-1.571	-3.441	-+	-14.333	-12.359	-14.107	-14.434	-16.204	1571
62 1 -32,	.413 -	23.024	-13.634	**.0**	12.472	23.350	39,451	33+171	29.115	23.849	10.533	FEFT

APEA A1 = 30383.43 TON-FT PETWEEN 8.4463 AND 48.6000 DEGREES AREA A2 = 10113.17 TON-FT BETWEEN -14.5537 AND 8.4463 DEGREES

#### AATIC AL/AE = 3.0343 PHI=C = 0.4463 NEGPELS RA=C = 1.2140 FT

### CRITERIA SATISFIED

NOTE & GZ VALUES INCLUDES COMMECTION TERM & COSIMEEL TO ACCOUNT FOR UNKNOWN UNSYMMETAICAL MOMENT The Dynamic Starility is eased of maximum positive meel angle of 44.88 degrees



Figure 2.2.5-1 (U): 3KSES Hullborne Intact Stability (English Units) (U)

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ATE OFFICE NO	1/0V 03-76	INTACT	STABILITY	ANALYSIS	ΡλΟΣ
931'G 10.	1 N/A		3KSES	LDP + 73.15 H LOA + 81.15 H	BEAM 1 J2.92 H NO. OF STATIONS : \$1

BENA WIND CONSINED WITH MOLLING . MEAN OPPRATING (MOD\_-10) CONDITION

.

HYDROGTATIC CHARACTERISTICS AT IERO HEEL ANGLE

SEA WATER DISPLACEMENT		1901.90 CU+II	LARGITHDINAL CG (LCG) -	17.52 N APT FD
MUSTRUDIAL CB (LC3)	-	37.52 H APT PP	LOUGITUDINAL CP (LCP) -	AL. S. D. APT FP
VERTICAL CG (SG)		8.39 H ABY HEER	VERTICAL CD (KB) -	3.67 A NIV REAL
MULTING FREE-SURFACE		1330.16 85-14	VERTICAL C.G. (KG) -	B. S. H ABV BARL
TRADEV. METACHINER (MITT)		71.83 N ABV RRAL	Loug. Metacenter (XML) .	277.59 H ANV RRGL
TPANEWERSE CB (TCB)		0.00 H PAN RAVL	HOHENT TO ALTER TRIN (HTI) -	71.21 H+4/CH
TRI'! (+VT + AFTIARD)	•	-0.46 2	urapt at LCP (II) =	1.76 il AJV RR L
DRAFT AT AP	-	5.58 H ABV RIGHL	draft at FP (IIF) =	6. 04 11 ADV RANL
•	•			

AIGUIDING ARMS -VO- HERLS IN INTACT CONDITION

### WIND SPEED - 185.32 KH/HR

illect e	-15.000	-10.000	-5.000	0.0	1.000	10.000	20,000	10.000	40.000	50.000	60.000 DZCR	ŒES
OPAPTI	4.496	5.093	5.580	5.780	5,576	I. 097	1.629	1,349 -	1.172	-3,919	-6,460 M	
1 225T	-2.684	-1 ,972	- 1. 176	-0.465	-1,049	-1.976	-3.150	- 2. 767	-4.300	- 4. 400	-5,122 8	
7Z 1	- 9. 531	- 7. 111	-4.157	+0.002	4,167	7.180	10.806	10,111	6. 871	7. 266	5.649 11	
125.201	0. 972	0. 711	0.522	0.186	0. 111	0.731	1,233	1.813	2. 111	a. 979	3.488 <u>4</u>	
				DYN.	ANIC :	STABI						

#### ARCA A1 = 92271.00 KI-M DETWEEN 0.0463 AND 40.0000 DEGREES ARCA A2 = 30409.00 KK-M DETWEEN -14.5517 AND 0.4463 DEGREES

ZATIO	<b>λ1/λ2</b>	•	1.0343	
PILI+C			0,4463	DEGREES
RA-C			0. 3702	X

NOTE : SEA WATER DEDRITY = 1.025 MITRIC TOUS/CU-H





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Figure 2.2.5-3 (U): Cross Curves of Stability in Intact Hullborne Condition (U)

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CPWG. NO	••••	16PT:890-801-23

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LAP :	240. 00	FEFT	REAM	11	08.00 FE	E 1	ſ
LOA :	266.25	FFFT	NC.	OF	STATIONS	:	51

### COMPUTATION IS BASEC O & ASSUMED K C : IN INITIAL UPRIGHT CONDITION = 26.00 FT ABOVE RALL

3KSES

PHI : 0.0 DEGREES	DISFLACEMENT :	1900.00	2100.00	2300.00	<b>2500.00</b>	2700.00	5900.00	3100.00	3300.00 L.TCNS
	FIGHTING ARM I	-0.00	-0.01	-0.01	- <b>0.61</b>	-0.01	-0.01	· -0.01	-0.01 FEET
	LCR FROM FP :	129.57	130.39	130.95	131.43	131.85	<b>132.33</b>	133.55	133.06 FEET
PHT : 10.00 DEGREES	DISFLACEMENT :	1900.00	2100.00	2340.00	2500.00	2760.00	2900. 00	3100.00	3300.60 L.TONS
	Pighting AMM :	75.45	24.67	73.90	23.14	22,38	21. 64	2F.92	20.71 FEET
	LCB FRGM EP :	136.65	136.96	137.12	137.73	137.32	137. 30	137.16	136.93 FFET
PHI : 20.00 DFGREFS	RISPLACEMENT :	1900.00	2100.00	2300.00 '	2500.00	2700.00	2500.00	3100.00	3300.00 L.TCNS
	Righting Amm I	38.13	37.30	35.45	35.15	34.46	33.74	32.91	' 32.70 FEET
	LCB FRCM FP :	143.75	143.83	141.83	141.29	141.24	141.11	}40.87	}40.50 FEET
\$ 30.00 CFGREES	DISPLACEMENT :	1900.00	2100.00	2300 <b>.00</b>	2500.00	2700.00	2900.00	3100.00	3300.00 L.TONS
	Righting arm :	36.33	35.43	35.16	34.18	32.96	33.70	33.41	33.10 FFET
	LCP FROM FP :	147.55	145.44	145.61	143.16	143.02	142.71	142.29	141.74 FFFT
PHI : 40.00 DEGREES	DISPLACEMENT :	1900.00	2100.00	2368,60	2500.00	<b>non. 00</b>	2500 . oo	3100.00	3300.00 L.TONS
	RIGHTING ARM :	33.14	32.69	37.31	31.64	30, 24	30. 49	30.24	29.95 FEET
	LCE FROM FP :	150.92	145.68	148,32	146.37	144. 31	143. 36	142.66	141.82 FEET
PHI : SO.ON CFCFEFS	DISPLACEMENT :	1900.00	2100.00	7360.00	2500. no	2760.00	2900.00	3100.00	3300.00 L.TONS
	RIGHTING ARM :	31.15	31.00	27.41	27.02	26.46	25 73	<i>25.60</i>	25.41 FFET
	LC5 FROM Fr :	161.20	160.45	149.03	147.58	145.54	142.96	142.18	141.25 FFET
PHI : CO. 00 CFGREES	CISPLACEMENT :	1900.00	2160.00	2300, no	2500.00	2700.00	2900.00	3100.00	3300.00 L.10N5
	Righting APM :	94.35	74.28	24.12	21.51	21.21	. 20.48	19.88	19.40 FEET
	LCR FROM EM 1	159.67	150.41	157.13	48. 7	146.78	144.02	141.63	340.41 FFET
PHI : 70.00 DEGREES	DISPLACEMENT :	)400.00	2100.00	2300+00	2500.00	2900.00	2900.00	3100.00	3300.00 L.TGNS
	RIGHT ING ARM :	11.42	12.65	14.77	15.10	15.41	13.54	13.40	13.43 FFET
	LCB FROM FP :	140.17	142.48	149+08	148.69	149.20	142.C3	141.06	140.46 FFET
PH1 : 20.00 CFGREES	CISPLACEMENT :	1900.60	2100.00	2304.00	2500.00	2700.00	2900.00	3100.00	3300.00 L.TCNS
	PIGNTING ARM :	3.81	4.54	5.10	5.55	5.90	6.19	6.42	6.59 FFFT
	LCB FROM FP :	138.44	135.79	135.18	139.51	139.79	140.04	140.25	140.12 FEET
PHI : 90.00 DEGREES -	DISPLACEMENT 1	1900.00	2100.00	2300.00	2500.00	2700, no	<b>2960.00</b>	3100.00	3300.00 L.TONS
	RIGHTING ARM :	-2.58	-3.14	- 3.51	-1.28	- 1.53	-1.14	- <b>0. 24</b>	0.03 FFET
	LCH FROM FM :	141.04	137.30	137.P2	141.5P	138.63	131.95	141.91	142.00 FEET

Table 2.2.5-1 (U): Intact Range of Stability (English Units) (U)

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	D7.	TE VDUTTU		#HOV 03-76	CROSS	CURVE	5 OF 5	TABIL	ITY			ра	GE
	11	STOTER	OFTGET NO	* N/A			acces						
			•	,					LUP : LOA :	73.15 % 81.15 M	BEAM I NO. OF	32.92 H STATIONS	1 5 : 51
			•	COMPUTATION IS	BASED OF ASSU	HRO KG IN	INITIM. UP	RIGHT COUD	1710:1 = 7	.92 M ABOVE	RRHL		
1+1: T		0.0	arcours					<b>3833 11</b>	5555 0.5	3036 14	2022 30	2220 60	(*1)
	•		111.110,000	MUSPING ADM +	1881.07	2081.29	2279.51	6477.72	20/3.94		3012.30	J210.00	с <del>с-</del> п 0 м
				LCB FROM FP :	39.49	39.74	39,91	40,06	40.19	40.33	40,71	40.80	M.
4i I	:	10.00	DEGREES	DISPLACINCUT +	1883.07	2081.29	2279.51	2477 72	2675 98	2874.16	3072.39	3270.60	CU-N
				RIGHTING ARM 1	1.77	7.52	7.28	1.05	6.82	6.60	6.38	8,96	6 3
				LCB FROM FP +	41.66	41.75	41.79	41.83	41.86	41,85	41.51	41.74	Ĩ
<b>1:1</b>	:	20.00	DECERES	DISPLACEMENT 1	1003.07	2081.29	2279.51	2477.72	2675.94	2874.16	3072.39	3270.60	CU-H
				RIGHTING ARE :	11.62	11.37	10,97	10,71	10.51	10,28	10,05	9.31	N.
				LCB FROM FP 1	43.82	43,84	43.23	43.07	43.05	43.01	42,94	42.32	М
'nΣ	ł	30.00	DEGREES	DISPLACEMENT :	1883.07	CE. 1662	2279.51	2477.72	2675.94	2874.16	3072.38	3270.60	£0-w
				RIGHTING ARE 1	11.07	10.80	10,72	10.42	10.35	10.27	10,18	IO . 09	М
				LCB FROM FP 1	44.97	44.39	44.38	43.64	43.59	43,50	43,37	43.20	E
HI	•	40.00	DEGRIES	DISPLACEMENT :	1883.07	2081.29	2279.51	2477.72	2675.94	2874.16	♦ <b>□</b> ⊠≈ ● 38	3270.60	CU-N
				RIGHTING ARH	10.10	9.96	9.82	9,61	9.40	9.29	9,22	9.13	H
				IACH FROM FP I	46.00	45.62	45.21	44,61	43.99	43.70	43,48	43.23	71
жт	2	50.00	DEGREES	DISPLACEMENT :	1683.07	62'1802'	2279.51	2477.72	2675.94	2874.16	3072.30	3270.60	CU-X
				RIGHTING ARM :	9.51	9.45	8.35	8.24	8.07	7.84	7.80	.7.74	M
				LC3 PROM PP 1	49,13	dO'81	45.42	44,98	44.30	43.57	43,34	43.05	a
нı	1	60,00	DEGREES	DISPLACEMENT :	1883.07	2081.29	2279.51	2477.72 .	2675.94	2874.16	3072.38	3270.60	CU-N
				RIGHTING ARM 1	7.43	7.40	7.35	6.56	6.46	6.24	6,06	6.04	М
				LCB FROM FP 1	48.73	48.28	47.09	45,16	44.74	43.90	43,17	42.92	м
111	: 1	70.00	DECREES	DISPLACEMENT :	1883.07	2081,29	2279.51	2477.72	2675.94	2874.16	3072,38	3270.60	CU-H
				RIGHTING ARM :	3.48	3.86	4.50	4,60	4.70	4.13	4.09	4.09	ĸ
				LCB PROM FP #	42.72	43.43	45,44	45.32	45,48	43.29	43.00	42.81	м
111	: 1	30.00	degrees	DISPLACIBURIT :	1883.07	2081.29	2279.51	2477.72	2675.94	2874.16	3072.38	3270.60	CU-11
				RIGHTING ARA 1	1,10	1.38	1.55	1.69	1.80	1.89	1,96	2.01	1
				LCB FROM FP :	42.20	42.30	42.42	42,52	42,61	42.69	42.75	42.71	· I
HI :	: 9	0.00	DEGREES	DISPLACEMENT :	1883.07	2081.29	2279.51	2477.72	2675.91	2874.16	3072.38	3270.60	CU-H
				REGITING ARE :	-0.91	+0.90	-0.17	-0.39	-0.47	-0.32	+0.07	0.01	M
				LCH YROM PP 1	42.99	41.85	42.01	43.15	42.25	42.35	43.23	4.5.28	<b>F1</b>

Table 2.2.5-2 (U): Intact Range of Stability (SI Units) (U)

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DATE 1JUN-26-1976	<b>U V H V U</b>	< 1 X P 1 1 1 1 1		
CCMPUTER OFFSET NO ILSESTRAI DRWG. NO. : N/A		<b>3KSES</b>	1 PF : 240.00 FFF1 1 PA 1 246.25 FEF1	HFAM : 103.00 FEET NC. OF STATICNS : 51

### SHELL-TO-SHELL FLOCOING I FULL LOAD THIM FORWARD CONDITION

### COMPARTMENTS FLOODING 11+111 (FRAME 0-28)

#### SYMMENICAL FLOADING

### SHIP IN FINAL CONCITION

FINAL OPAFT LLCF) LCG IN FINAL CONDITION LCF IN FINAL CONDITION	= 24.1 = 117.4 = 112.6	3 FT АРУ, GANL 6 FT FEIW FP 8 FT F90W FP рат (рок) FP	FINAL DISPLATEVENT Loo in Final Condition Total Trim	* *	3000.60 117.20 -21.78	TONS FT FROM FP FT
LCST PUDVANCY VCE OF LOST PLOVANCY	= 1639.7	P TONS A FT ADV FEEL	LEG OF LOST PUCYANCY TEG OF LEST PUCYANCY	*	41.64 -0.62	FT FROM FP From Rrvl
FINAL GRAFT AT AF FINAL HFEL PG IN FINAL CONCITION	* }2.5 * 0.0 * 23.1	R FT APV FFWL Pegyfes 9 Ft Apv fful	FINAL OPAFT AT FP Före-Sumfiff Compection Namarf Bighting App (62)	8 8 5	34.36 2143.27 8.0	FT ABV RRWL Ton-FT FT
'RESIDIAL FREEFOARD	* 3-0 #8	1 FT EL TO PARCINLINF =	CISTANCE FROM F.M.	•	-24.25	FT

NOTE & MG VALUE INCLUEES ALLOWANCE FUE POPE-SUBFACE FEFECT FOR SLACH TANKS



Figure 2.2.5-4 (U) Reserve Buoyancy with Shell-to-Shell Flooding (English Units) (U)

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DATE COMPUTER OFFSET NO.	INOV	04~76 8001	DAHAGE	STABILITY	ANALYS	IS		PAGE	11	
DRHG. NO.	1	В/Л		jkses	112.	73 15 N	BEAM a	12.4	2 M	
					LON	81,15 H	NO. OF	STATION	6 1 5	1

#### SHELL-TO-SHELL FLOODING ( FULL LOAD TRIN FORMARD CONDITION

### COMPARTMENTS FLOODING II + III (FRAME 0-28)

#### SYNALTRICAL FLOODING

		SHIP	IN FINAL CONDITION		
PINAL DRAFT (LCF)		7 . 3 6 H ABV. RRHL	FINAL DISPLACEMENT	-	2973,60 CU-M
LCG IN FINAL CONDITION		35,74 I I PRONTP	LCH IN FINAL CONDITION		35.74 M PROH PP
LCF IN FINAL CONDITION	-	16.35 H FROM PP	TOTAL TRIN	-	-6.64 M
		D A T A <b>P O</b>	RLOSTDUOYANCY		
. Lost huoykicy	-	1624.36 CU-/1	LCG OF LOST BUOYNICY	-	12.69 M FROM FP
VCG OF LOST BUOYANCY		6.57 IS ARV RRHL	KC OF LOST BUOYN ICY		-0.01 TROM REAL
FI:IAL DRAFT AT AP	-	3.43 N ABY RRIL	FINAL DRAFT AT FP		10.47 M ABY REVL
FINAL HEEL	-	0.00 DEGREES	FREE-SURPACE CORRECTION		964.78 H++4
KG IN FINAL CONDITION	•	7 . 2 2 H ABV RRIL	DAMAGE RIGHTING ARM (GE)	•	0.00 M
RESIDUAL PREEBOARD	4	0.92 M	DISTANCE FROM F.P.		-0.00 🕅
		HEEL TO HARGINLINE	<b>3.96 DEGRUES</b> .		

NOTE : KE VALUE INCLUDES ALLOWANCE FOR FREE-SURFACE EFFECT FOR SLACK TANKS



Figure 2.2.5-5 (U) Reserve Buoyancy with Shell-to-Shell Flooding (SI Units) (U)

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5869, KQ.	8 h/4 .		3KSÉS		SKSES	. LP# 1 248.58 FEFT- L04 1 248.25 FEET 1			BEAM & 108.04 FEET NG. OF STATIGNS 1 51		
			159 LC	a ()a#aGE		NCPINAL					
		7100	DCING IN C	¢≈₽±₽Т#€₼	TS 14-4 PE	ETRATION	TO C.L. OF	SHIP			
	•			LASTPR	ETPICAL PL	001n6					
	•					1710-					
FINAL OPAFT (LCF) LCG IN FINAL CONDITION LCF IN FINAL CONDITION		23.13 23.22 11.19	FT ARY, B FT FROM F FT FROM F	#¥L #	•	FINAL LCM I IQTAL	NISPLACEPE M FINAL COM TRIM	n T 0 1 7 1 0 m	12 12	0.00 TONS 3.22 FT PI 2.94 FT	10# <i>FP</i>
				F 0 R		4 U C V		,			
LEST PUOVANCY VCG CF LOST RLOYANCY	• 17	10.64	TONS FT any PR	wi,		LCA 0 768 G	F LOST AUOV F LOST PUOV	44CY 44CT	• 13 • 3	7.44 <i>et e</i> i 8.85 F#Q#	PAVL
FINAL GRAFT AT AP Final PFEL Rg in Final Concition		21.54 7.4A 23.94	FT ARY RA Cerbres FT ARY AR	4L 4L		F 144L - FFEF- 04240	ORAFT AT F Simpace cor C Righting	# ##CTION ### (GZ)	a 343	1.45 FT 10 1.27 TON-1 1.6 FT	n annt L
RESIGUAL FREEMOARD	•	4.28	<b>#</b> T			01514		۶.	-1	5.00 FT	
_		HEEL	TO HAPGEN	LINE	•	8.44 G	EG#{/\$		•		
			ATCHTINE	1 <b>#</b> =5 -V5-	HERLS IN C	*****	N01710H				
FEEL 1 -15.008 -1 67 1 -38.475 -2	5.000 -5. 5.042 -17.	447	6.8 -8.874	5.000 -2.471	10.040 2.719	19.840 4.737	24.0A4 14.146	35.000 20.245	45.005	55.004 9.435	CERCES
NOTE I	GZ VALUES IN	CLUDES	COMPETIC			10	• •				

KE VALUE INCLUES ALLOWANCE FOR THEE-SURFACE EFFECT FOR SLAK TANKS



Figure 2.2.5-6 (U): Damaged Stability 15 Percent LOA Unsymmetrically Flooded (English Units) (U)

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DATE CC-PUTER CRESET NO DRVG. NG.	1JUN-7A-197A 1L9E5BUA1 6 K/A		3KSES	A 4 A L 7 \$ 3 3	P4GE 5
·				100 1 240,00 FFF	T - PEAM 1 104.00 FEET T F MG, OF STATIONS 1-51
		TEN LCA DAMAG		IAAL CONDITION	
	FLOCE	ING IN COMPARTMENTS		THATICH 16 29.33 LCAG. R	•8.
		UAS		•	
,		\$-1P	IN FINAL CONDITION	· .	
FTMAL 044FT (LCF)	•	79 FT 484, FRUL		FINAL DISPLACEMENT	. 3000.00 TONS
LCF IN FINAL CONDITION	r = 123. i = 114.	22 FT FBC+ FP +7 FT FBC+ FP		TOTAL THIM CONDITION	- 123.22° FT FBQH FP
		9 * Y * F C :			
LEST PURYSHEY VCB OF LOST PLOYAMET	• 1478. • 11	AD TONS . CE FT ANY BELL		LEG OF LOST PUDYANCY TER OF LOST PUDYANCY	• 144.21 FT FROM FP • 46.71 FROM RAVL
FIRAL OPAFT AT AP FIRAL OPAFT AT AP FIRAL OPAFT AT AP	- 23.	OL FT APU FRUL AS CLAMBES AR FT APU PAUL		FILM CHAFT AT PH PRFF-SIMPLOF CORFECTION NAMAGE -INPTING ARM (03)	= 22.56 FT ARY RAWL = 3034.27 TGA-FT = _0.0 FT
RESIGUAL FREEDARD	• 7.	49 57		DISTANCE FROM F.P.	- 240.00 FT
•	,	ELL TO PARGINUINF	• é.	75 CFA8(FS	
. <u>.</u>		-	VS- offly IN Pana	ef campitian .	
₩{{L 1 -13.000 -1 62 1 -32.366 -7	0.008 -5.000 9.035 -76.880	8.8 5.86 . ~12.686 -4.89	A 18.044 19 7 8.442 4	.476 24.848 25.668 .471 14.438 15.657	45.680 55.886 CEG4EES 17.431 5.650 FEFT
	02 VALUFS INCLU	OFS COMPECTICN TERM WE INCLUSES ALLANAA	0.09209(0475L) 70	- ACCOUNT FOR UNITION UNIT	IMMETEICAL FORENT



Figure 2.2.5-S (U): Damaged Stability 50 Percent LOA Unsymmetrically Flooded (English Units) (U)

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### (U) 2.2.5.2 Static Stability Underway

- (U) 2.2.5.2.1 Off-Cushion Stability Underway -- Predicted off-cushion static pitch and roll stability characteristics for the ANVCE near term SES are presented in Figures 2.2.5-10 and 2.2.5-11, respectively. The ship has positive static stability with pitch and roll restoring gradients of approximately 99 x  $10^6$  ft-lb/degree (134.23 x  $10^6$  N·m degree) and 22 x  $10^6$  ft-lb/degree (29.83 x  $10^6$  N·m/degree), respectively. In the off-cushion mode, the SES is statically unstable in yaw but dynamically stable, thus providing satisfactory course keeping characteristics as influenced by the ride control system in a seaway.
- (U) 2.2.5.2.2. On-Cushion Static Stability Underway -- The predicted oncushion static stability data presented next shows that the ANVCE near term SES has positive stability in roll, pitch and yaw. Roll and pitch stability are shown at 40, 60 and 80 knots (20.58, 30.87 and 41.16 m/s); yaw stability data for 60 and 80 knots (30.87 and 41.16 m/s) only. The stability characteristics shown are for a nominal displacement of 2800 LT (27,899.2 RN) which approximates the Full Load Displacement condition.
- (U) The positive on-cushion pitch stability of the SES at 40, 60 and 80 knots (20.58, 30.87 and 31.16 m/s) is shown in Figure 2.2.5-12. Predictions are plotted with zero moment occurring at the nominal pitch trim attitude for each speed (the ship is trimmed at the pitch attitude for minimum drag consistent with non-broaching operation). Speed variation at a constant weight primarily alters the minimum-drag pitch attitude. These predictions were derived by Froude scaling hydrodynamic model test data without other correction. Positive static stability is indicated by the degree of negative gradient of the moments with their corresponding attitudes.
- (U) The average pitch restoring moment is approximately 18 x 10<sup>b</sup> ft-lb/ degree (24.40 x 10<sup>6</sup> N·m/degree) for all speeds shown. The minimum gradient of about 8 x 10<sup>6</sup> ft-lb/degree (10.85 N·m/degree) occurs on the curve for 40 knots (20.58 m/s).

- (U) The yaw stability characteristics are shown in Figures 2.2.5-13 and 2.2.5-14 at speeds of 60 and 80 knots (30.87 and 41.16 M/S) for three (3) pitch attitudes (1, 0 and +1 degrees) and at two (2) angles of roll (0 and +2 degrees). Positive static yaw stability is shown for all conditions except the high speed, negative pitch case (80 knots (41.16 m/s) and -1 deg: . \*rim). However, extrapolation of the dynamic stability indicates that taw near term SES will be dynamically stable, in the directfonal sense, to bow down pitch angles as large as -2 degrees. In actual operation, a bow down trim attitude of this magnitude is difficult for the ship to achieve, and even more difficult to maintain. Strong pitch restoring moments ensure a rapid return to nominal attitudes even under failure mode conditions.
- (U) The positive on-cushion roll stability of the near term SES at 40, 60 and 80 knots (20.58, 30.87 and 41.16 m/s) is shown in Figures 2.2.5-15 through 2.2.5-19, respectively. **Predictions** are plotted for pitch attitudes of zero and plus and minus 1 degree and for yaw angles of zero, -2 and -4 degrees. The roll restoring moment gradients vary slightly with speed and ship attitude. The maximum gradient shown is approximately 4.3 x  $10^{6}$ ft-lb/degree (5.83 x  $10^{6}$  N·m/degree) (at 80 knots) (41.16 m/s); the minimum is about 2.6 x  $10^{6}$  ft-lb/degree (3.53 x  $10^{6}$  N·m/degree) which occurs at 40 knots (30.87 m/s) at a -4 degree yaw angle. The principal roll restoring moments are due to the **sidehull** design.
- (U) Two of the more significant features which contribute to the excellent stability characteristics of the ANVCE near term SES are the seal and sidehull designs, The Rohr advanced planing seals maintain their geometric integrity at all times, even in high sea states. The design precludes slope reversal in the pitch stability curve ("pitch clicks"), as exhibited

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on the **100B** testcraft. The design also precludes catastrophic plow-in characteristics exhibited by other type seal designs at bow down attitudes.

- (U) The mced plt ing seal design increases the effective cushion length as a direct function of bow immersion; as the bow goes down, the effective cushion length boundary moves forward, providing additional pitch and roll restoring moments.
- (U) The design stiffness of the seals is a careful balance between stability requirements and ride quality. The Rohr design provides a degree of stiffness which maintains adequate roll and pitch stability while providing good ride qualities.
- (U) The sidehull forward sections contribute additional pitch and roll restoring moments at bow down attitudes in the same way as the advanced planing bow seal. This effect is obtained by designing the bow stem to match the bow seal contour. In addition, the stem angle minimizes destabilizing moments at bow down attitudes. The low (45 degree) deadrise angle of the sidehull design provides better pitch and roll stability than higher deadrise sidehull configurations.





Figure 2.2.5-10 (U): 3KSES Static Pitch Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), Off Cushion (U)

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Figure 2.2.5-11 (U): 3KSES Static Roll Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), Off Cushion (U)



PITCH ATTITUDE (DEGREES)

Figure 2.2.5-12 (U): 3KSES Static Pitch Stability, 83 Percent Fuel Condition (2800 LT; 27, 899.2 kN), on Cushion (U)



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Figure 2.2.5-13 4: 3KSES Static Yaw Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), on Cushion (U)

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Figure 2.2.5-14 (U): 3KSES Static Roll Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 KN), On Cushion (U)

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Figure 2.2.5-15 (U): 3KSES Static Yaw Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), On Cushion (U)



Figure 2.2.5-16 (U): 3KSES Static Roll Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), On Cushion (U)





Figure 2.2.5-17 (U): 3KSES Static Roll Stability, 83 Percent Fuel Condition (2800 LT; 27,899.2 kN), On Cushion (U)

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(U) 2.2.5.3 Dynamic Stability -- The predicted on-cushion dynamic stability characteristics for the near term SES are presented in Table 2.2.5-3. The values shown in the table are for the ship without ride control. Nominal pitch trim angles are included in the table for reference, At 40 knots (20.58 m/s), the yaw (directional) mode is overdamped for the nominal pitch trim angle; responses in yaw may then be characterized as a first order system with a time constant of about 4 seconds.

AXIS	SPE KNOTS	ED m/s	NOMINAL TRIM DEGREES	FREQUENCY HZ	DAMPING RATIO
ROLL	4 0	20.58	2.2	0.17	0.15
	6 0	30.87	1.4	0.18	0.14
	8 0	41.16	0.9	0.19	0.13
PITCH	4 0	20.58	2.2	0.19	0.22
	6 0	30.87	1.4	0.20	0.20
	8 0	<b>41.16</b>	0.9	0.21	0.16
YAW	4 0	20.58	2.2	*	*
	6 0	30.87	1.4	0.15	0.80
	8 0	41.16	0.9	0.07	0.45
HEAVE	4 0	20.58	2.2	0.65	0.28
	6 0	30.87	1.4	0.66	0.29
	8 0	41.16	0.9	<b>0.68</b>	0.31

Table 2.2.5-3. (U) 3KSES Dynamic Stability Characteristics (U)

\*Overdamped,  $\tau = 4.0$  seconds

- (U) Figure 2.2.5-18 presents the significant pitch angle deviations as a function of speed and significant wave height. These data are based on analytic modeling of the ship's vertical plane dynamic characteristics as influenced by the ride control system in a seaway.
- (U) Figures 2.2.5-19 through 2.2.5-21 present the significant roll angle deviations with speed, significant wave height, and seaway heading.

(U) These data are based on hydrodynamic model test data collected in the DTNSRDC maneuvering basin.

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(U) Figure 2.2.5-22 presents the limit allowable drift angle as a function of speed. The angles are limited by propulsive control yaw moments available below hump and by operating boundaries (dictated by roll-yaw stability) above hump. The limit angles shown were derived from XR-1D testcraft model data and inlet broaching studies. (1)

(1) Barker, J., et al, "XR-1D Safety and Performance Prediction Report", Rohr Industries, Inc., Rept. No. RHR-75-266, 22 Aug. 1975 (Fig. 4-11 and 4-12).

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Figure 2.2.5-18 (U): 3KSES Pitch Deviation Versus Speed Head Seas (U)

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Seas from 30 Degrees Abaft the Starboard Beam



Figure 2.2.5-21(U): 3KSES Roll Deviation Versus Speed (U)

Full Load Displacement (3000 LT; 29,892.1 kN) Calm Water, On-Cushion



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- (U) 2.2.6 GEOMETRIC FORM -- The geometric form of near term SES is described by the hull lines and the control surface drawings of this section.
- (U) 2.2.6.1 Hull Geometry -- The selection of the hull form is based on judicious compromises between overall hullborne and cushionborne performance; structural strength; manufacturing economy; volumetric requirements; combat suite; safety, survivability and efficiency of ship operations. The net result is shown in the lines drawing, Figure 2.2.6-1.
- (U) The **sidehull** geometry is based on the effects of **deadrise** and ventilation cutouts on the overall hydrostatic and hydrodynamic performance parameters, bow seal interface, **waterjet** inlet configuration and structural atrength requirements. Hydrodynamic drag considerations have influenced the choice of a slender body **sidehull** concept.
- (U) The full-length sidehulls enclose the sides of the bow seal, decreasing seal vulnerability to damage as compared with exposed bag and finger seal systems on partial-length **sidehulls.** The full-length **sidehull** vertical inner face also permits a simple bow seal/sidehull interface and allows the use of a two dimensional, modularized bow seal system.
- (U) 2.2.6.2 Principal Dimensions -- The principal dimensions, as related to the proportions and form characteristics of the sidehulls

and the centerbody, are based on the following considerations:

- Provision for the required cushion area in conjunction with space requirements for main propulsion machineries and waterjet inlets. The Panama Canal transit requirement established the maximum beam of 108 feet (32.918 m). The trace of the maximum beam follows 4 feet (1.219 m) above the upper chine and is canted inboard to the main deck and 01 level. \*\*\*\*\* nominal tumblehome at Station 10 is 3 feet 7 inches (1.092 m).
- The overall length of 266 feet 3 inches (81.153 m) was established from the maximization of performance parameters as related to cushion length to beam ratio, bow and stern seal geometry design, overall utility, and volumetric requirements.
- The wet deck height was selected at 18 feet (5.486 m) above baseline to minimize wetdeck slamming and cushion induced dynamic response, The wet deck is horizontal except forward of Station 4 where it ramps upward to minimize pitch induced slam loads and to provide a flat interface with the forward seal in its retracted position,
- The selection of main deck height at 40 feet 0 inches (12,192 m) above baseline was based on requirements of hull girder strength, reserve buoyancy in damage situations, and overall volumetric and space demands. The high main deck also provides a drier environment for engine air intakes and for helicopter operation, relative to lower main deck configurations that were evaluated.
- (U) 2.2.6.3 Control Surfaces -- The baseline design of the near term ANVCE SES incorporates two stern-mounted stabilizing fins, port and starboard, canted 28 degrees inboard from the bottom of the fence, as shown in Figures 2.2.6-1 and 2.2.6-2. Fin section geometry is shown in Figure 2.2.6-3.

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1. PRINCIPAL HYDROSTATIC PARAMETERS (OFF CUSHION) BLOCK COEFFICIENT (C,), FULL LOAD = 0.1662 PRISMATIC COEFFICIENT (Pc), FULL LOAD = 0.8341 NETTED SURFACE, FULL LOAD  $= 18,440 \text{ FT}^2 (1713 \text{ m}^2)$ TRANSVERSE KM, FULL LOAD = 273.81 FT (83.45 m)VERTICAL CENTER OF BUOYANCY (KB) = 10.62 FT (3.24 m) TONS PER INCH IMMERSION (TPI) = 43.91 TONS/INCH (17.23 kN/m) LONGITUDINAL CENTER OF FLOTATION (LCF) = 137.11 FT (41.79 m) (FROM FP) 2. PRINCIPAL HYDRODYNAMIC PARAMETERS (ON CUSHION) ■ 221 FT (67.36 m) CUSHION LENGTH CUSHION BEAM ■ 85 FT (25.91 m) = 18 FT (5.48 m) CUSHION HEIGHT = 118 FT (35.89 m) LONGITUDINAL CENTER OF GRAVITY (FWD OF TRANSOM) = 2.60 CUSHION LENGTH/BEAM **a** 4.72 CUSHION BEAM/HEIGHT

 $(\rho_{SW} = 1.025 \text{ METRIC TON/CU m})$ 

Figure 2.2.6-1 (U): ANVCE-JES Hull Lines Drawing LL802009 (Sheet 2 of 2)



























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Figure 2.2.6-2 (U): Baseline Stabilizer Fin Geometry (U)









Figure 2.2.6-3 (U): Fin Section Geometry (U)

### (U) 2.2.7 RIDE QUALITY

2.2.7.1 Near Term SES Ride Criteria -- Near term SES high speed operation in high sea states can result in vertical vibration modes not previously sustained by man over long periods of time. While considerable data exist on vibratory effects upon man, the heave acceleration environment of the near term SES centers in a portion of the frequency regime for which characterizing data are sparse. Certain near term SES resonances are predicted between 0.1 Hz and 5 Hz in the **pricise** range where human performance capability is most affected; primarily because the human body resonates at about 5 Hz., and because sailors may become seasick when ship motions traverse 0.1 to 0.5 Hz at energy levels above 0.06 g's (**rms**).

- (U) The primary purpose of developing a ride criteria is to establish the motion limits that can be tolerated by operations, maintenance and off-duty crew for specific mission durations. The importance of these criteria is to ensure a reasonable level of operating efficiency if craft motions are maintained at or below the limits.
- (U) The curves illustrated in Figure 2.2.7-1 were established from a comprehensive literature search by overlaying graphical data representing human performance decrement studies. The search encompassed hundreds of previous motion studies, experiments and simulations related to the adverse effects of vibratory environments on human performance. These data form the data base for the ride criteria, categorized by specific task type and correlated by rms g's versus the center frequencies of the one-third octave band. Although considerable vibration data and criteria exist above 1 Hz, very little is available to describe the effects on humans between 0.1 and 1 Hz This influences the ride criteria since the predicted near term SES heave acceleration environment tends to center in this portion of frequency regime.

- (U) Although the data points cover vastly different conditions and show varying degrees of performance or motion sickness, trends were established for short term and long term conditions. Trend lines were compared with all other data points and with previously developed habitability criteria to establish firm ride criteria.
- (U) The present ride criteria represent 30 minute and 4 hour duration tolerance limits for adapted crews with ten to twenty percent expected performance decrement. In the frequency region of 0.1 to 0.5 Hz, ten percent of the crew could be expected to have some motion sickness. The actual task performance decrement of one of the ten percent displaying sickness might mean slower performance, increased errors or complete non-performance of assigned duties.
- (U) The identification of the kind and level of performance decrement expected must consider the specific tasks to be performed. The reduced tolerance between 1.0 and 10 Hz refers primarily to tracking tasks decrement. The operation of a decimal input device (with proper arm support and restraints) would suffer no performance decrement at motion levels near or even slightly above the ride criteria curves.

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- (U) 2.2.7.2 Near Term SES Ride Quality -- Figures 2.2.7-2 through 2.2.7-5 present the frequency spectra of the heave acceleration levels at an **amidship** station with the ride control system both on and off. The power expenditure to control the ride is tabulated in Figures 2.2.7-4 and 2.2.7-5.
- (U) The influence of the ride control. system on the RMS heave acceleration levels at a speed of 60 knots (30.87 m/s) and 6.9 feet (2.1 m) significant wave height is illustrated in Figure 2.2.7-6. Then in Figure 2.2.7-7 through 2.2.7-13, the RMS vertical plane acceleration levels near the bow, amidship, and at the stern are plotted versus seaway heading for a number of speeds and significant wave heights. These data are based on hydrodynamic model test data collected **in** the David Taylor Naval Ship Research and Development Center (DTNSRDC) **maneuv ing** basin.

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Figure 2.2.7-1 (U) The SES Controls Ship Vertical Motions (U)



Figure 2.2.7-2 (U): 3KSES Half Fuel Condition (MOD-SO) 2400 LT (23,913.6 kN), Uncontrolled Ride (U)

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Figure 2.2.7-3 (U): 3KSES Full Load Displacement, 3000 LT (29,892.1 kN) Uncontrolled Ride (U)



Figure 2.2.7-4 (U): 3KSES Half Fuel Condition (MOD-50) 2400 LT (23,913.6 kN), Controlled Ride (U)

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Figure 2.2.7-5 (U): 3KSES Half Fuel Condition (MOD-50) 2400 LT (23,913.5 kN), Controlled Ride (U)

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Figure 2.2.7-6 (U) 3KSES Variation in Vertical CG Acceleration with Heading at Full Load Displacement (U)

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Accelerations with Heading at 60 Knots (30.86 m/s) (U)

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Figure 2.2.7-9 (U): **3KSES** Variation of Bow, CG and Stern Vertical Plane Accelerations with Heading at 40 Knots (20.58 m/s) **(U)** 

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Figure 2.2.7-11 (U): 3KSES Variation of Bow, CC, and Stern Vertical Plane Accelerations with Heading at 32 Knots (16.46 m/s) (U)



۹**۲** ه نبر به Figure 2.2.7-12 (U): 3KSES Variation of Bow, CG, and Stern Accelerations with Heading at 29 Knots (14.92 m/s) (U)

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Figure 2.2.7-13 (U): 3KSES Variation of Bow, CG and Stern Accelerations with Heading at 26 Knots (13.38 m/s) (U)

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#### (U) 2.2.8 MANNING

- (U) The anning presented herein delineates the minimum quantitative and qualitative personnel essential to the operation, maintenance and support of the near term SES under stated missions and configurations. These requirements are termed Organizational Manning and were developed in general accordance with the "Guide to the Preparation of Ship Manning" document, OPNAV 10P-23.
- (U) The developed manpower requirements are sufficient for performing all operational, maintenance, administration and support tasks required for the near term SES under the following Readiness Conditions: Special Condition I (Battle Readiness) for Anti-submarine operations, Anti-air operations, and Surface operations, Condition IV (Peacetime Cruising Readiness) and Condition V (In-Port Readiness). Table 2.2.8-1 displays the manning requirements in the prescribed format.



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Table 2.2.8-1 (U): Manning (U)

VEHICLE		
OFFICERS	CPO	OTHER_ENLISTED
Commanding Officer	<b>B</b> MC	1 051
Executive Officer	DIC	1 <b>DS2</b>
Operations Officer	WCS	3 12/2
First Lieutenant	HMC	I EN]
Combat Systems Officer	ICC	1 EN2
Electronics Haterial Officer	QHC	1 EKPN
Engineer Officer	RHC	1 ET1
Damage Control Assistant	SKC	1 ETN2
		1 2783
		1 5%2
		1 FTM1
		1 FTM3
		1 GHH2
		1 G1913
		3 <b>CS1</b>
		I G\$3
		1 CSFN
		1 HT1
		1 HIFK
		1 <b>1C2</b>
		1 ICPN
		1 <b>KS1</b>
		1 1482
		2 HS3
		1 051
		1 0\$2
		1 <b>055N</b>
		I <b>071</b>
		1 <b>0T3</b>
		1 <b>5%2</b>
		3 (A 154) 1 mun
		1 8012
		1 503
		1 949
		1 n42
		1 1113 6 SN
		1 PN
08	08	<u></u>
	<b>\$</b> 0	
SECONDARY VEHICLE		
Halicopter Pilot	ADJC	1 ADJ1
Helicopter Pilot		1 AMH1
Helicopter Co-Pilot		1 AMH3
Helicopter Co-Pilot		1 ANSI
		1 <b>AT1</b>
		1 AT3
		1 AE1
		1 <b>AX2</b>
		2 AW2
		2 AW3
		1 A02
		1 AN
04	Q1	14
TOTAL COMPLEMENT		
12	09	64
	GRAND TOTAL	. 85

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2.3 SHIP SUBSYSTEM DESCRIPTIONS

2.3.1 STRUCTURE

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- (U) 2.3.1.1 Summary -- The twin, full cushion length sidehulls of the near term SES are designed to be aerodynamically and hydrodynamically clean, and to contribute to good stability, maneuverability and performance characteristics. The ship houses the required weapon suite within its three (3) major decks and provides an operational helicopter capability. The survivability and reliability of the structural system is designed for 20 year life across the **expected** profile.
- (U) The hull structure includes the shell plating, framing, structural bulkheads, decks, superstructure, structural closures, mast and foundations. The functional requirements of the hull structural system are: (1) to provide a watertight envelope which.houses all other subsystems, (2) to provide a structurally sound platform suitable to the performance goals of the craft, (3) to provide an envelope that can be conditioned for crew comfort and utility, and (4) to provide a platform for aircraft and weapon system operations.

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- (U) The hull structural configuration is a compromise between overall hullborne and cushionborne performance, manufacturing economy, functional space requirements, combat suite, habitability, survivability and safety within the overall constraint of meeting mission requirements. It is designed to meet a specified 20 year life requirement while retaining a realistic balance between minimum weight, structural reliability and cost construction.
- (U) The near term SES hull is subjected to a wide variety of loading conditions, including impact loads, while operating at high speed. These loads would normally required a conservative, heavy structure; however, near term SES performance requirements dictate a more sophisticated and lightweight structure. For convenience, structural loads are subdivided into Primary and Local load categories. Combinations of these categories provide the basis for the development of structural design.

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- (U) Primary loads are defined as those loads affecting the entire hull structural girder. These include overall hull bending, torsion and shear resulting from ship weight, and hull buoyancy distributions when the ship is off-cushion or from a wave impact when the ship is traveling at high speed on cushion.
- (U) Local loads are those applied over limited portions of the hull structure, such as loads resulting from hydrostatic or hydrodynamic pressure, desk burden, foundation and topside icing,
- (U) The hull bending, torsion, and shear that result from weight and buoyancy distributions when off cushion, and wave impact loads when transiting at high speed on cushion were investigated. The NASTRAN and multi-cell girder load distribution programs established internal loads for stress analysis. A plate/stiffener analysis computer program was used for the stress analysis of all major structural areas. Loads considered were those due to hull bending, torsion, pressures, drydocking and equipment.
- (U) Scantling design requires a delicate balance between structural weight and ease of fabrication, without sacrificing structural integrity. The scantlings were designed through the use of a computerized optimization program to vary frame, stiffener, and plate sizing with frame and stiffener spacing and provide comparisons of the resultant structural weight and the associated fabrication costs. A frame spacing of three feet with ten inch stiffener spacing was selected. In lightly loaded areas of the ship, such as superstructure, the frame and stiffener spacings were increased to provide light weight and faster ease of fabrication.
- (U) Hull structure optimization has provided a basis for optimum structural design of scantlings, wetdeck height, wetdeck ramp angle, full length side" lls, and keel length fences. The structure optimization has been instrumental in design decisions relating to the square bow near term SES.

- (U) The main hull girder is composed of a centerbody and two rigid sidehulls. The main, second, **third** and wetdecks, as well as seven (7) longitudinal bulkheads, comprise generally continuous longitudinal members which contribute to the section modulus over **the** entire length. All stiffeners on these members, as well as shell plating stiffeners, run longitudinally.
- (U) Bulkhead and deck penetrations are minimal, enhancing structural continuity, This result is a compromise between the location of structural bulkheads and the arrangement of machinery, equipment, and weapons systems. Minimizing the number of bulkhead and deck penetrations reduces the associated structural weight penalties which occur when primary load paths are interrupted and internal loads are redistributed through use of secondary load paths. Trusses are used to retain overall load carrying capability wherever large penetrations exist.
- (U) The hangar and pilot house structure located above the weather deck is assigned a secondary structural role and does not carry primary hull bending or hull torsion. As a consequence, the hangar is designed with a six foot (1.83 m) frame spacing and a 16 inch (0.41 m) stiffener spacing to provide adequate strength.

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(U) The hull transverse frames are relatively large aluminum extruded tees welded to the deck plates. These members function as beam sections to span across openings between decks and form the vertical frame columns. These members are capable of reacting axial, shear, and moment loads in the plane of the frame. The sidehull and innerbottom frames are lightest when designed as an open truss configuration. These trusses react the locally applied hydrodynamic pressures and function integrally with the non trussed portion of the transverse frame. Stiffened webs are used in place of the trusses to accommodate tank boundaries, foundations or local load conditions. Reactions to the bow seal and stern seal loadings are concentrated at locally reinforced transverse frames at the wetdeck level.

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- (U) Transverse bulkheads are spaced at 42 feet (12.80 m) intervals, with the exception of the aft most compartment where a 30 feet (9.14m) spacin is used to accommodate the propulsion machinery. These bulkheads are all watertight. Vertically oriented tee members are spaced at 10 inche (254 mm) on center. The longitudinal bulkheads are sized to resist primary loads, flooding loads and drydocking loads. Stiffeners are arranged 10 inches (254 m) on center, nominally.
- (U) The all-welded aluminum hull structure is designed for ease of fabrication, for minimum weight, and to provide structural integrity under all loading conditions. Marine grade weldable aluminum alloys 5086 -H116/117 and 5456 - H116/117, are rated best overall for the primary hull structure because of mechanical, corrosion, manufacturing, and cost considerations. Of these two, 5456 - H117 (H111 extrusions) was chosen because of its 19 percent greater strength-to-weight ratio compared to that for 5086-H117. The H117 temper is free of continuous grain boundary networks which would be susceptible to exfoliation or severe intergranular corrosion in a marine environment.
- (U) The basic ship structure would be fabricated in twenty (20) major structural assemblies including two (2) stabilizer fins (P&S) and the mast, Final assembly and erection would be accomplished outdoors in a building basin. All fabrication, subassembly, and assembly of the structures, from receipt of plate and extrusion until the assemblies are ready to be transported to the building basin for erection, would be performed indoors in a controlled environment. A 139,000 feet<sup>2</sup> (12,913.5 m<sup>2</sup>) Marine Assembly Facility would be required. Operations have been planned and sequenced to maximize down-hand and automatic welding such that no overhead welding is required prior to erection of the hull structure in the building basin, Overhead

- (U) welding required during erection would be less than two (2) percent of the total lineal footage of welding on the ship.
- (U) Erection of the hull in the building basin would proceed from the stern forward. This erection sequence was selected after reviewing outfitting density and erection sequences to determine that sequence which provides the longest **possible** span for the highest density area of the ship with respect to outfitting and system testing.
- (U) 2.3.1.2 Structural Drawings -- The dravity for the structural arrangement are contained in appendix B, Section B.3. They are:
  - Main Deck Plating
  - o Longitudinal Bulkhead
  - o Transverse Bulkheads
  - o Transverse Frame
  - o Bow Plating and Framing
  - o Superstructure
  - o Structural Extrusions
  - o Plating Combinations
- (U) The drawings are grouped in appendix B for consistency of report format and the benefit of the reader.
- (U) 2.3.1.3 Key Structural Features -- Outstanding characteristics of the near term SES include the optimum choice of size and shape of the hull, seal interface, and structural layout of primary members. The design is characterized as being an exceptionally clean ship with smooth flowing lines.

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- (U) The functional design of the ship provides minimum air turbulence for helicopter operations while the minimum motion characteristics of the ship enhance the ability of helicopters to take-off and land.
- (U) The physical constraints of the hull structure require that the craft have a beam of 108 feet (32.92 m) or less, a full load displacement of approximately 3000 tons (29892 kN.), and be capable of housing all required subsystems. Physical dimensions developed from parametric trade-offs established the following dimensions:
  - o Overall length of 266 feet 3 inches (81.15 m)
  - o Wet deck height of 18 feet (5.49 m)
  - o Wet deck ramp angle of 13.7 degrees
  - o Minimum main deck height of 40 feet above keel (12.19 m)
- (U) Internal geometry of the hull structure has been optimized to the following and are shown on figure 2.3.1-1:
  - o Stiffener spacing of 10 inches (0.25 m)
  - o Frame spacing of 3 feet (0.91 m)
  - o Transverse bulkheads spaced at 42 feet (12.80 m) intervals (aft bulkhead at 30 feet 9.14 m )
  - o Longitudinal bulkheads at approximately 14 feet (4.27 m) spacing
  - o Between deck height of 9 feet (2.74 m)
  - o Third deck height above keel = 22 feet (6.71 m)
  - o Second deck height above keel 31 feet (9.45 m)
  - O Main deck height above keel 40 feet (12.19 m)
  - o 01 deck at 49 feet (14.54 m)

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o 02 deck at 60 feet (control center deck) (18.29 m)

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Figure 2.3.1-1 (U): Structural Configuration (U)

(U)	2.3.1.4		St	tructu	ral	Weight	Breakdow	m	The	st	tructura	1	weight
	breakdown	of	the	hull	and	supers	tructure	is	shown	in	Table	2.	3.1-1:

	(1)	5	
SWBS	LONG TONS	KILONEWTONS	%
110	419.03	4175.2	52.1
120	152.79	1522.4	19.0
130	518.60	1580.3	19.7
150	14.49	144.4	1.8
160	19.11	190.4	2.4
170	2.78	27.7	0.3
180	38.20	380.6	4.7
100	805.0	8021.0	100

Table 2.3.1-1 (U) Structural Weight Breakdown (U)

(U) 2.3.1.5 Structure Risk Assessment -- The hull of the near term SES is designed to realistic worst case loading conditions which are forecast to occur within the ship lifetime. These structural loads were obtained from an extensive Rohr 2KSES/3KSES model testing and analytical loads development program. The structural materials are commercially produced aluminum alloys which have been utilized in existing Navy ships, such as the PHM and SES 100B. The baseline design configuration features conventional built-up plate-stiffener combinations, a conventional ship'framing system, and state-of-the-art welding and producibility details to minimize construction problems. Consequently, structure of the near term SES is producible, competitive with respect to cost; and represents an optimum design configuration for performance of the specified mission.

- (U) 2.3.2 PROPULSION -- The near term SES is powered by a waterjet propulsion plant, Its principle is the conversion of that mechanical energy supplied by the gas turbine-driven waterjet pumps into kinetic energy, by increasing the velocity of the seawater inducted at the waterjet seawater inlets and ejected through the waterjet pump exit nozzles. The general arrangement is shown on Figure 2.3.2-1.
- (U) The SWBS breakdown of the propulsion plant is:
  - Gas turbine system (234)
  - Transmission system (242, 243, 244)
  - Waterjet propulsor system (247)
  - Combustion air intake system (251)
  - o Exhaust gas uptake system (259)
  - Lube oil system (262)
  - 2.3.2.1 Summary Description
- (U) 2.3.2.1.1 Gas Turbine System -- A total of four (4) gas turbines, each driving a waterjet propulsor, are utilized in the near term SES propulsion plant. The four (4) turbines are arranged in pairs of two (2): one (1) pair is located on the starboard side of the ship and the other pair is located on the port side. Each gas turbine is operationally independent of the other .
- (U) The baseline propulsion gas turbine for the near term SES is the LM2500 gas turbine which is capable of delivering 22,500 continuous shaft horsepower (16,780 kW) and 27,000 intermittent shaft horsepower (20,130 kW). The alternate propulsion gas turbine is the FT9A-24 which delivers 36,500 continuous (27,220 kW) and 40,000 intermittent shaft horsepower (29,830 kW).



Figure 2.3.2-1 (U): Propulsion Plant General Arrangement, Starboard Side Only (U)

- (U) The FT9A-2A system requires more space than the LM2500 system due to its increased turbine length. The FT9A-2A engine is installed further aft, which shortens the drive shaft length. The propulsion plant is designed for future installation of the alternate FT9A-2A engine with a minimum impact on the propulsion plant or other ship systems.
- (U) The LM2500 marine gas turbine is derived from the TF39 military and CF-6 commercial turbo fan engines used respectively on the Lockheed C5A Galaxie and McDonnell Douglas DC-10 aircraft. The LM2500 gas generator consists of a variable vane 16-stage compressor; annular combustor; two-stage air-cooled turbine and associated gearboxes; controls; and accessories. The power turbine 'has six stages and is a low-speed, low stress design. The LM25C, engine, is presently in service on the DD963 class destroyers.
- (U) The FT9A-2A engines are identical with the FT9A-2 engines currently being developed by the Navy, Minimum interface hardware revisions are required for the SES application. The progenitor engines for the FT9A-2A are the FT4 marine and JT9D aircraft engines. The FT9A-2A gas generator has a low and high pressure compressor, each driven by a separate turbine and an annular combustor. The power turbine is derived from the FT4 power turbine now in service.
  - (U) 2.3.2.1.2 Transmission System -- This system consists of the propulsion shafting, shaft flanges, shaft bearings with mounting structure, flexible couplings and torque meters. Each of the four transmission systems connect a propulsion gas turbine to a waterjet propulsor reduction gearbox input flange. The shaft, flanges, bearings, seals and bearing housing form the shaft/bearing module which is installed (or replaced) as a unit. Figure 2.3.2-2 illustrates the arrangement. The reduction gearbox is described next in the waterjet propulsor system description.

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- (U) 2.3.2.1.3 Waterjet Propulsor System -- The waterjet propulsor system consists of the integral reduction gearboxes and waterjet pumps, instrumentation, mounting links, steering sleeves with hydraulic actuators, waterjet pump inlet flex joints, thrust reversers with hydraulic actuators, transom flexible seals, waterjet pump priming systems, attached lube oil pumps with minor lube oil system components and piping, seawater inlets, seawater intake diffusers, bifurcated ducts and variable ramp roofs with hydraulic actuators, A nozzle closure valve and a thrust bearing are contained within each waterjet pump. A shaft brake is attached to each reduction gearbox.
- (U) Each reduction gearbox (four (4) total) contains necessary gearing to reduce the input speed and divide the power between the two (2) waterjet pump rotors which run at different speeds. The propulsor assembly gearbox details and gear train are shown in Figures 2.3.2-3 and 2.3.2-4.
- (U) 2.3.2.1.3.1 Waterjet Propulsor Assembly -- The vaterjet propulsor is a two-stage; two-speed design based on the hydraulically similar PHM propulsor. The first stage is an inducer designed to produce a sufficiently high head rise at low suction (cavitating) conditions to permit the second stage impeller to operate at high rotation speeds without cavitation. The power split between the inducer and impeller is approximately 30:70. The inducer rotates at about 1/4 engine speed, the impeller at about double this. The propulsor assembly is shown in Figure 2.3.2-S.
- (U) 2.3.2.1.3.2 Waterjet Inlet -- Seawater for the four (4) waterjet propulsors is taken aboard through two semiflush inlets as shown in Figure 2.3.2-6. One inlet is located in each sidehull to serve the two waterjet pumps also located in each sidehull. Seawater for ship services is taken aboard through these inlets. The sidehulls are enlarged through fairings from their nominal cross-sections to accommodate the inlets. Waterjet inlet area is varied by continuous plate flexible ramp roofs, actuated by a hydraulic cylinder to control the seawater flow into the system. The water

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Figure 2.3.2-3. (U) Propulsor Assembly Gearbox Arrangement (U)



Figure 2.3.2-4 U): Propulsor Assembly Gear Train (U)



Figure 2.3.2-5 (U): Waterjet Propulsor Assembly (U)



Figure 2.3.2-6 (U): Waterjet Intake Duct Ramp Roof (U)

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- (U) flow through each sidehull inlet passes into the diffuser section of the inlet duct and is distributed through a duct bifurcation to the two pumps. Water flows through the inlets by combination of pump action and ship forward motion, at a rate determined by the ship speed, inlet area settings and pump speed. The curved diffusers then turn and raise the water to the pumps through the bifurcated ducts. An abrupt expansion is used at the entrance to the bifurcated ducts. Each bifurcated duct is constant area, symmetrical and has integral turning vanes.
- (U) 2.3.2.1.3.3 Steering and Reverser System -- Each waterjet propulsor has an associated steering sleeve and the two outboard propulsors have thrust reversers. The discharge water from each pump's single fixed-area nozzle passes coaxially through a flexible seal at the transom, and subsequently through a swiveling steering sleeve mounted on the transom. The steering sleeve deflects the waterjet to generate side forces on the ship. Each sleeve is hydraulically actuated, utilizing the ship hydraulic system, and is instrumented to permit position monitoring.
- (U) The thrust reversers direct the waterjets in a forward direction. In operation, they are pivoted into the water streams by controllable position actuators. During reverse thrust operation, the high-velocity water is redirected forward, down, and slightly outboard to minimize spray and hazard to nearby objects. The thrust reversers are variable position to give full forward through full reverse thrust on the outboard waterjets.
- (U) 2.3.2.1.4 Combustion Air Intake System -- The internal configuration of the combustion air intake system and the location of the demister banks, acoustic panels, gas turbine plenums, air heating system, and external opening of the air inlet are shown in Figure 2.3.2-7. The features of the intake design which reduce salt spray are the coaming projecting above the 01 level; the vertical portion of the intake which requires the air to turn 90 degrees to enter the demister banks; and the drainage sump at the third deck level.



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Figure 2.3.2-7. (U) Combustion Air Intake System Arrangement (U)

- (U) The intake contains sound supression panels in three locations to attenuate engine noise to acceptable levels. The panels in the section between the 01 level and main deck are comprisedof six inch (0.15 m) spaced perforated panels, installed in the athwartship direction. Thin aluminum splitters between the panels form six inch (0.15 m) rectangular ducts.
- (U) The intake system is designed to accommodate the LM2500 or the FT9A-2A engine. The design considers all combination s of these engines for propulsion and lift. The only modification required when the FT9A-2A engines are employed is an increase of demiscer face areas.
- (U) Anti-icing, de-icing, and pre-heating of the intake system for the engines is accomplished by recirculation and mixing of lift engine exhaust gas at the weather inlet on each side of the ship, as is shown schematically in Figure 2.3.2-8. Each combustion air intake system supplies air to one lift engine, two propulsion engines, gas turbine generator(s), and the gas turbine cooling systems.
- (U) 2.3.2.1.5 Exhaust Gas Uptake System -- This system consists of the exhaust ducts (including supports and insulation) which are routed from the propulsion gas turbines to the transom, where the combustion products are exhausted; The design incorporates a water trap at the transom to provide stern wave protection, Each exhaust duct is acoustically treated to attenuate noise.
- (U) 2.3.2.1.6 Propulsion Lube Oil System -- This system provides lubrication for the bearings in the transmission system and for the waterjet propulsor assembly. The reduction gear system is of the dry sump type and the pump thrust bearing and seal module require most of the oil in the system. The reduction gear carries driven pressure and scavenge pumps. The lube oil system upstream of the mechanically driven pressure pump, and downstream

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Figure 2.3.2-8 (U): Anti-Icing and Intake Air Heating System (U)

(U) of the mechanically driven scavenge pump, is defined as the propulsion lube oil system, Each propulsion drive train has its own dedicated propulsion lube oil system (four total). The lubricant used is 2190 TEP per MIL-L-17331.

#### (U) 2.3.2.2 Operation

- (U) 2.3.2.2.1 Start-Up -- The gas turbines are pneumatically started from the ship system. This system provides sufficient compressed air to start one gas turbine. The pneumatic (start air) system cross connects all propulsion and lift engines such that any one engine can start another by supplying bleed air from its compressor into the system. The start control sequence is automatic but manual start controls **provisions** are provided for back **up**. Each gas turbine engine can be started and ready to **deliver** power in approximately 90 seconds.
- (U) The waterjet propulsors are above the ship off-cushion waterline and thus require priming. Priming is accomplished in these successive steps: apply transmission brake to prevent rotation of the dry pump; shut nozzle closure; supply auxiliary water to rubber bearings; operate the air ejector that connects to both pump pairs; and when pumps are primed, water then covers the pump inducer centerline.
- (U) The brake is then released and the pump rotated enough to produce a static head of about 15 ft (4.57 m) H<sub>2</sub>O. When the nozzle closure is opened, the pump begins to deliver water, the ejector system and auxiliary water supply are shut off and the priming is completed. These features of the priming system are shown on Figure 2.3.2-9.
- (U) 2.3.2.2.2 Low Speed -- Low ship speed operation of the propulsion plant requires the ship to be *in* the off-cushion mode to reduce the possibility of broaching which could unprime the propulsors. Additionally, with the ship off-cushion, inlet head to the pump inducer is maximized to reduce suction specific speed. The steering sleeves and reverser may be configured to

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- (U) give low speed forward, astern, turning and sideways translation of the ship for undocking and maneuvering in a seaway. The power level is limited by the suction specific speed line of the propulsors to limit cavitation erosion of the pump components.
- (U) The seals are extended to a height/speed schedule when above 10 knots(5.14 m/s) ship speed to avoid reaching limit suction specific speed.The waterjet inlet is generally wide open in the low speed mode.
- (U) 2.3.2.2.3 Hump Transfition -- Hump transition requires the use of high power settings and, in the case of a heavily loaded ship and/or high sea state, may require use of the intermittent power level to produce the desired margin of thrust over drag. During transit, the waterjet inlet area is varied according to pump speed (power), ship speed and engine throttle setting. Suction specific speed limitations are not present at trans-hump speeds.
- (U) Ship heading control will require use of a combination of differential thrust, assymetrical throttle settings on the fan engines, and thrust vector control with the steering sleeves. The ships control system automatically determines the required combination and the mix of control forces that provides heading control with minimum fuel consumption.
- (U) 2.3.2.2.4 High Speed Cruise -- At cruise conditions, throttle settings for steady state conditions (and the associated inlet opening) are maintained by the propulsion control system.
- (U) 2.3.2.3 Machinery Characteristics -- The machinery characteristics are presented in the following tables:

Table 2.3.2-1:(U) Engine Characteristics (U)

	011114101	ERISTICS			
ITEM	LM 2500	FT9A-2A			
Turbine Inlet Temperature - <sup>o</sup> F( <sup>o</sup> C) Air Flow - 1b/sec (N/Sec) Dry Weight - 1bs (kN) Compression Ratio at Max, RPM S:FC - 1b/HP-hr (kN/w-hr) Max. Power at Sea Level- HP @ 80"'F (kW @ 27 <sup>o</sup> C) No. of Compressor Stages No. of Turbine Stages No. of Turbine Stages No. of Combustors Combustor Type Length-Inches (m) )iameter (Max) - Inches (m)	2300 (1260) 146 (649) 10,405 (46.281) 15:1 .381(2.28) 27,000 (20,134) 16 8 1 Annular 257 (6.528) 87 (2.210)	2255 (1235) 250 (1112) 21,300 (94.742)) 21:1 .397(2.36) 40,000 (29,828)) 17 5 1 Annular 337 (8.560) 73 (1.854)			

Table 2.3.2-2 (U) Reduction Gear and Transmission **(U)** Characteristics

ΊΤΕΜ	CHARACTERISTICS		
Leduction Gear			
Speed	4100 RPM		
Power	40,000 SHP (29830 <b>kW)</b>		
Weight (Dry)	9489 lb (42.21 kN)		
Length	76 inch (1.93 <b>m)</b>		
Width	59.50 inch (1.51 <b>m)</b>		
Lubricant	2190 TEP per Mil-L-17331		
Gears	Double-Helical 9310 steel		
	one-piece pinion and shaft		
Ratio			
First stage	4.359		
Second Stage	2.0508		
Bearings	Journal, Babbit lined		
Casting	Cast Aluminum A356-T6		
<b>Fransmission</b>			
Length	138 inch (3.50 m)		
Diameter	22 inch (.56 m)		
Bearings	Fwd - Duplex <b>ball thinwall</b>		
	Aft - Roller thinwall		
Shaft and Flanges:	4340 forgings		
Flexible Coupling,	Double diaphragm 🖬 1/2° misaligument		
	capability		
Torquemeter	Accurex Strain type		

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Table 2.3.2-3: (U) Waterjet Propulsor Characteristics (U)

ITEM	CHARACTERISTICS
Speed	4100 RPM
Power	40000 SHP (29830 kW)
Weight (wet)	22571 1b (100.396 kN)
Length	203 inch (5.16 m)
Height	70 inch (1.78 m)
Diameter	49.5 inch (1.26)
Efficiency *	88.5%
Headrise *	999 ft H <sub>2</sub> 0 (304.5 m H <sub>2</sub> 0)
Flow rate *	135,154 $\tilde{GP}.M$ (8.527 $m^3/sec$ )
Gross Thrust *	161,200 1bf (717.018kN)
Nozzle Diameter	17.52 inch (.45 m)
Speed Inducer *	940 RPM
Speed Impeller *	1999 RPM
Suction Specific	2,4250 at Inducer Centerline
Speed Limit	
Speed Limit	

\*Values at RPM and Power quoted and total inlet head of 203 ft.  $H_2^0$  (61.9 m  $H_2^0$ )

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ITEM CHARACTERISTIC Width 48 inch (1.22 m) Drop Fraction 0.5 14 ft<sup>2</sup> (1.301 m<sup>2</sup>) Max Opening Area  $4 ft^2 (.372 m^2)$ Min Opening Area 286,282 GPM (18.06 m<sup>3</sup>/s) Max Flow Rate 3 section continuous flexible Variable Roof. plate Equal legs with **•urning** vanes Bifurcation

#### Table 2.3.2-4: (U) Waterjet Inlet (U)

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- (U) 2.3.2.4 Arrangements -- The drawings and sketches depicting the near term SES propulsion system are contained in Appendix B.4. They are:
  - 0 Propulsion System
  - 0 Waterjet Inlet
- (U) The drawings are grouped in Appendix B.4 for consistency of report format and benefit of the reader, A sketch of a section of the demister is shown as Figure 2.3.2-10.
- (U) 2.3.2.5 Propulsion System Weights -- Weights within the propulsion system SWBS 200 are shown in Table 2.3.2-5.

		Weight			
SWBS	_Subgroup		<u>kN</u>	Percentage	
234	Gas Turbines	21.56	214.8	11.3	
241	Reduction Gears	16.07	160.11	8.4	
242	Couplings	.71	7.07	.4	
243	Shafting	1.19	11.86	.6	
244	Shaft Bearings	.60	5.98	.3	
247	Waterjet Propulsors	50.82	506.3	26.7	
251	Combustion Air		,		
	System	20.12	200.47	10.6	
252	Control System	.46	4.58	.2	
259	Uptakes	14.21	141.58	7.5	
261	Fuel Service System	.11	1.10	.1	
262	Lubeoil System	4.60	45.83	2.4	
298	Operating Fluids	59.56	593.43	31.3	
299	Repair Parts	44	4.38	.2	
200	Propulsion System	190.46	1897.65	100.0	
			1	1	

Table 2.3.2-5 (U). Propulsion System Weights (U)

(U) Table 2.3.2-6 shows the estimated functional weight percentage of major components within the propulsion system for an LM 2500 and FT9A-2A system.

SUBSYSTEM	PERCENT OF SYSTEM				
5655151111	LM2500	FT9A-2A			
Engines	9.1	16.9			
Gearboxes	a.4	7.1			
Propulsors	12.6	10.6			
Comb Air System	10.6	11.2			
Comb Exh System	7.5	10.3			
Oper. Fluids	31.3	26.4			
Miscellaneous	19.9	17.7			

Table 2.3.2-6 (U). Weight Percentage of LM2500 and FT9A-2A Propulsion System (U)

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Figure 2.3.2-10 (U): Propulsion Inlet Water Demister (Coalescer) (U)

2.3.2.6 Propulsion System Technical Risk Summary

- (U) Engines -- The GE LM2500 gas turbine engine is in production with a proven capability up to 21,500 SHP (16,033 kW), is low weight, and in use for other marine applications. The Pratt and Whitney FT9A-2A alternate engine is developmental and requires design and test effort; it will be in production after a few years; and component testing has begun, Current development efforts are limited to 33,000 SHP (24,608 kW).
- (U) Transmission -- The propuision transmission system is designed to transmit all anticipated alternating and continuous torques between the propulsion engine and the propulsor assembly without failure over a 20-year life span with specified overhaul of the life limited components; to have not more than 10 percent failures prior to the scheduled overhaul period of 5,000 hours minimum (10,000 hours goal) for the life limited components; to withstand a limit torque of 1,229,764 inch pounds (138.94 kN·m) without degradation of performance or failure; and to eliminate any critical speed (of any component) which is less than 125 percent of the system maximum operating speed.
- (U) Waterjets -- The propulsor is hydraulically similar to the PHM pump now in operation. Comprehensive model tests have already been successfully conducted for the 40,000 SHP (29,828 kW) propulsar. The waterjet inlet has been extensively tested with models and with similar inlets of the operational SES-100A and XR-1 testcraft. The installation design of the waterjet propulsor assembly will withstand all anticipated input powers, thrusts and external loads due to ship accelerations and equipment malfunctions without failure for a 20-year design life and with specified overhaul. The waterjet seawater inlet duct system has been optimized to improve performance, cavitation characteristics, drag and structural weight on the basis of substantial analysis and model testing.

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(U) The propulsion lube oil system, combustion air intake system, and exhaust gas uptake system are typical of present gas turbine ship installations. All components are presently available and proven in service. For the combustion air inlet, anti-ice protection by exhaust gas mixing is the accepted method of General Electric, Pratt and Whitney, and Garrett.

#### (U) 2.3.3 ELECTRICAL SYSTEM

- (U) 2.3.3.1 Summary of Key Features -- Primary 450 Volts power for the near term SES is generated at 60 Hz and 400 Hz frequencies by six gas turbine generator (GTG) sets. Three (3) identical GTGs rated 375 kW 60 Hz and three identical GTGs rated 375 kW 400 Hz provide a total system capacity of 2250 kW. All six (6) GTGs are driven by Garrett ME 831-800 turbines.
- (U) The distribution system is arranged to provide an operational choice of ring-bus or split-plant operation. Six (6) ship service switchboards are provided, three (3) for 400 Hz service and three (3) for 60 Hz service.
- (U) The lighting arrangement is based upon dividing the ship into four (4) lighting zones or "cubes". Three cubes comprise the internal illumination distribution system, while the fourth cube services the specialized needs of the helicopter hangar and landing lights. Lights throughout the ship are predominately of the fluorescent type and are energized by the 60 Hz system,

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- (U) 2.3.3.1.1 Type of System -- A block diagram depicting the functional integration of the electrical system is shown in Figure 2.3.3-1. The power generation system provides all anticipated ship service primary and secondary electrical power with minimum weight, minimum development risk and maximum assurance of required performance, reliability, and flexibility. Both the 60 Hz and 400 Hz systems generate power at 450 V, 3 phase, ungrounded delta. Power quality meets or exceeds the requirements for Type II 400 Hz power and Type I 60 Hz power per MIL-STD-1399/ 103.
- (U) In addition to driving the 60 and 400 Hz generators, the ME 831-800 gas turbines provide bleed air for starting the propulsion and lift engines (LM2500 or FT9) and also provide a small amount of continuous bleed air for the ship's compressed air system.
- (U) The near term SES' operating loads are approximately 50% on the 400 Hz system and 50% on the 60 Hz system. The ship's 400 Hz operating loads are distributed evenly among the three 400 Hz switchboards, each of which serves consumers located nearest to the particular switchboard. Each switchboard is connected to the other switchboards by bus ties which form a ring bus arrangement.
- (U) Two of the three generating plants are generally connected to the ring bus arrangement for all operating modes, allowing the third unit to be in a standby mode. Generators may be added or deleted as the power demand dictates when operating with the ring bus system,
- (U) The 60 Hz power distribution system is similar to the 400 Hz system.
- (U) The lighting system provides adequate and reliable illumination in all areas of the ship, regardless of operating mode or condition. Special and detail lighting is provided for specific tasks. The lighting fix-ture arrangement is spaced to provide the prescribed levels of working

surface illumination, as well as uniform, shadow free illumination **for** all areas. The system provides the following illumination services throughout the ship:

- General white illumination in all spaces
- Detail illumination according to work task
- Low-level, red-band illumination for darkened ship
- Two levels of blue-band lighting in the Combat Information center
- Automatic and manual battery operated battle lanterns
- helicopter platform visual landing aid and VERTREP platform illumination for night operation
- Navigation and running lights
- (U) The lighting system utilizes 60 Hz power for economic reasons since a 400 Hz system offers no appreciable weight savings and would be appreciably higher in cost. The lighting system also provides power for numerous non-lighting loads wherever this arrangement yields weight savings.
- (U) The system utilizes the Navy concept of dividing the ship into vertical volumes, each approximately a cube, for optimum distribution. The ship is divided info four cubes. One cube is dedicated to the helicopter landing area and supporting lighting. The remaining three cubes are divided into the forward, middle and aft portions of the ship. The lighting distribution system is fed from the three 60 Hz switchboards. Each of the three ship cubes contains two transformer banks fed from different switchboards. One transformer bank in each cube receives two separate power sources via a two-way automatic bus transfer, for supplying power to all areas containing vital lighting. The other transformer bank in the cube receives power from one switchboard. Figure 2.3.3-2 illustrates this arrangement.

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- (U) Lighting fixtures are designed to provide satisfactory illumination with optimum operational economy and minimum maintenance. Fluorescent lighting is used predominantly wherever feasible, owing to its superior lighting qualities and lower power consumption, Incandescent lighting is utilized only where a suitable fluorescent fixture is not available.
- (U) Standard Navy fixtures are normally used because of their proven qualities; in exceptional cases, other suitable fixtures may be selected where a functional advantage exists, or where an appreciable weight or cost saving can be achieved with no degradation in either service or reliability.

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Figure 2.3.3-1 (U): Electrical Plant Functional Block Diagram Illustrating Independent 400 Hz and 60 Hz Systems and Ring Bus Arrangement Which Precludes Total Loss of Power (U)



Figure 2.3.3-2 (U): Lighting System, One-Line Diagram (U)

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- (U) 2.3.3.1.2 Type of Components -- The GTG prime movers are Garrett ME 831-800 turbines currently being qualified for the Navy PHM program. The 831 series engine has four million hours of operational experience in protected and unprotected environments.
- (U) The 400 Hz GTG system is very similar to the PHM patrol hydrofoil generator set: each employs an ME 831-80-0 turbine, gearboxes with identical basic castings, bearings, and primary gears (i.e., gears that drive the 400 Hz generator), and identical turbine auxiliaries. The 400 Hz generator is also very similar to the generator used on the PHM patrol hydrofoil generator set (same design and frame size), differing only by a slightly longer lamination stack to provide a higher power level output.
- (U) In addition to the 60 Hz GTG use of the same gas turbine as the 400 Hz GTG, the other major components (such as the fuel system, lube system, and governors) differ very little between the two power frequency systems. The gearboxes are fundamentally identical except for the output gears which provide shaft speeds of 1800 RPM for the 60 Hz generator and 8000 RPM for the 400 Hz generator.
- (U) Each GTG set comprises a gas turbine, reduction gear, generator, governor, fuel system, self-contained lube system, enclosure and control system.
  Figure 2.3.3-3 and 2.3.3-4 show the turbine prime mover major components, envelope, and weight for the 60 Hz and 400 Hz units, respectively,
- (U) Each GTG is equipped with an electrical starter operating from its own dedicated 24 V dc battery system. On starting, in-rush currents of 2000 amperes exist and voltage dips below 15 volts will occur. These 1 'ge voltage dips dictate the need for an individual, dedicated battery and charger/power supply for each of the GTG's. This arrangement also ensures very high starting reliability, positively guaranteeing "blackship" starts.

- (U) The ME 831-800 gas turbine engine provides bleed air from its compressor. This source of compressed air constitutes a cost and weight effective means for starting the lift or propulsion gas turbine engines. The maximum air bleed rate is 104 lbm (0.786 Kg/s) from each turbine, and the output of two turbines, cooled through a heat exchanger is required to start the LM2500 (or FT9 A-2A). The bleed air power drain is substantial during the engine starting cycle, so the off-line GTGs are available to perform this function without disturbance of normal power generation.
- (U) The 400 Hz and the 60 Hz distribution switchboards are identical in construction. Typical outline dimensions are shown in Figure 2.3.3-5, Local control devices and instrumentation for GTG's are provided within a control cabinet located on the GTG. Switchboards are of the freestanding, dead front type, constructed with aluminum framing and sheeting. Access space is provided at both front and rear of each switchboard. All devices for the remote control and monitoring of the switchboards are conveniently terminated at terminal boards in the rear of the switchboard to facilitate connection of the ship's cables. Reverse power protection for the generator sets is provided within the switchboards.

(U) Circuit breakers mounted within the switchboard are of the proven reliable MIL-SPEC type. Molded case AQB Type circuit breakers are used within the distribution system to achieve reduced system weight and cost. The AQB Type bus tie and shore power circuit breakers are equipped with motor operated devices to enable remote operation. The generator circuit breakers are ACB Type.

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Figure 2.3.3-3 (U) The 60 Hz Gas Turbine Generator Set is a Compact Unit (U)



Figure 2.3.3-4 (U): The 400 Hz Gas Turbine Generator Set is Similar to the PHM GTG (U)



Figure 2.3.3-5 (U): Switchboard Arrangement (Typical) (U)

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- (U) 2.3.3.2 General Schematic -- An electrical system general schematic is shown in Figure 2.3.3-6, This shows the complete independence of the two primary power systems (60 Hz and 400 Hz) from each other. Each generator, both 60 Hz and 400 Hz, have an associated switchboard located in the same room with its generator, The locations of the generators have been made so that the three units for either system are dispersed one from the other, with two being low on the third deck and one high on the main deck.
- (U) Shore connections for both 400 Hz and the 60 Hz systems are made at connector receptacles located near the centerline on the 02 level. Inter locking is provided between the shore connection and the switch-board-mounted shore power circuit breaker to prohibit make-or-break of the shore connection under load.
- (U) Each circuit breaker has been selected to provide adequate protection in the event of a fault. A sequenced opening of breakers will occur with the generator breaker operating last. Should distribution circuit breakers open, manual resetting of the breakers is required as a safety feature to ensure that the fault or overload is first removed. Selected breakers may be remotely opened for damage control purposes but manual reset is required. Large power consumers are fed directly from switchboards while smaller consumers are routed to power distribution panels located throughout the ship. Transformers are located in close proximity to distribution panels for loads requiring voltages other than generated voltage. Voltage and frequency monitors (VFM) are provided where required for protection of 400 Hz electronics.

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Figure 2.3.3-6 (u): Electrical System General Schematic, Illustrating Flexibility and Availability Provided by Multiple **GTGs** and Ring Bus Interconnection of Switchboards (U)

- W2.3.3.3 General Arrangement -- The six GTG sets are installed in four different rooms, separated from each other by at least two water-tight bulkheads GTG Rooms 1 and 2 are symmetrically arranged and located on the third deck at the outboard extremes of the ship, as illustrated in Figure 2.3.3-7. Figure 2.3.3-7 also shows the location of the two GTGs (one 60 Hz and one 400 Hz) within each room.
- (U) GTG Rooms 3 and 4 are located port and starboard on the main deck, just forward of the combustion air inlet plenum. Room 3 contains one 400 Hz GTG as shown in Figure 2.3.3-8. Room 4, on the port side, contains one 60 Hz GTG and is arranged similarly to Room 3. The starting/control battery, battery charger and switchboard for each of these GTGs are also located within the rooms.

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Figure 2.3.3-7 (U): Electrical Generator Rooms 1 & 2 (U)



Figure 2.3.3-8 (U): Baseline GTG Room No. 3 (U)

- (U) 2.3.3.4 Electrical System Characteristics -- The estimated load under the most demanding condition is approximately 500 kW of 60 Hz power and 500 kW of 400 Hz power. Therefore, the normal operating configuration requires two each of the 60 Hz and 400 Hz generators to be running, leaving one of each type in reserve. These off-line reserve generators are automatically started when required, and are thus functionally equivalent to conventional "emergency" generators.
- (U) The GTG sets and associated switchboards are arranged for remote control and monitoring and for limited local control. Automatic and manual controls are provided for remotely paralleling the three 60 Hz generators and for remotely paralleling the three 400 Hz generators. Both the 60 Hz and 400 Hz systems are equipped with voltage and frequency trim controls, load shedding, load sharing, malfunction shutdown, overload controls, and warning alarms.
- (U) The control systems provide corrective measures for sustained overload or a generator failure. These provisions include automatic start of an off-line generator and automatic paralleling with the system bus. In the event of failure of an on-line generator, an automatic load shedding scheme protects the remaining vital loads. Manual reset of breakers is required following load shedding as a safety precaution. Sustained generator overloads activate an automatic sequence to shed non-vital consumers, and to start up and parallel an off-line generator if necessary. Failure or malfunction of an operating generator also results in immediate automatic startup and parallel operation of an off-line generator. The system provides ample capacity for across line motor starting of the largest motors currently identified or anticipated for consumers.
- (U) Two power sources are supplied for all vital loads. The lighting, "Circle W" ventilation, electronics, fire pumps and ship's control receive normal power from one switchboard and an alternate supply from a different switchboard via a bus transfer device located near the using equipment. Other vital consumers are supplied from a different switchboard for each element of a vital equipment pair, to assure continuity of

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service. Thus, in the event of a failure or casualty of the power supply to any vital load, all that systems' generators or switchboards (60 Hz or 400 Hz) would have to fail to create a total loss of power.

- (U) A radial lighting distribution system is employed that consists of 450 V, 60 Hz feeders from the ship's switchboards reduced through suitable transformer banks to 120 V distribution panels within each cube. The distribution panels supply centrally located distribution boxes, which distribute power to individual local lighting circuits. Vital lighting in spaces, as defined under "Emergency Lighting System" in Section 331b of the GSS, IS provided with a normal and alternate source of power through automatic bus transfer equipment, since this results in the simplest back-up arrangement.
- (U) Red low-level illumination is provided for standing lights, access routes and spaces requiring dark-adapted vision. Battery powered hand lanterns are provided throughout the ship to supply a limited amount of illumination in the event that other lighting sources fail.
- (U) 2.3.3.5 Electric Plant Weight Breakdown -- The following Table 2.3.3-1 shows the estimated percentage weights of the major equipments and components of the electrical system.

SUBSYSTEM	PERCENT OF SYSTEM		
Gas Turbine Generator Sets	20.0		
Turbine support equipment	14.0		
Switchgear, panels, fixtures	35.2		
Electrical Cable	20.5		
Miscellaneous	10.3		

Table 2.3.3-1 (U): Electric Plant Weight Breakdown(U)

(1) General Specification for Ships of the U. S. Navy

(U) 2.3.3.6 Technical Risk Areas -- The electrical system provides high confidence that the requirements for electrical power will be completely met, regardless of operating condition, The associated trade-off studies provide assurance that the baseline system can be implemented with off-the-shelf equipment and at competitive prices. This system features six generators, of which only four are required to supply the maximum load. This offers advantages over other configurations which depend on a smaller number of larger generators. These advantages include:

- A turbine or switchboard failure has less impact on total power generation capability.
- Major components are smaller and easier to remove for depot repair or replacement.

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- Smaller GTG envelope and smaller exhaust **piping** allows greater installation arrangement flexibility.
- Set enclosures are smaller and easier to remove in confined GTG rooms.
- It is feasible to provide a reserve GTG for each power frequency.
- (U) The power distribution system is closely patterned after those standard Navy practices presented in GSS Sections 300 and 320 and in appropriate Design Data Sheets. Minor variations only have been made, including (1) the addition of a ring bus arrangement for added flexibility and reliability, and (2) substitution of disconnect switches for circuit breakers at one end of each bus tie cable to achieve weight and cost savings. Therefore, with high confidence, the system will provide satisfactory and reliable system performance.
- (U) The composite design of the electrical system and the definition of its individual components functional and physical characteristics is considered a source of low risk. This conclusion is based on the ready availability of the chosen hardware, as well as its statistically proven performance and the straightforward integration of the overall system.

COMMAND, CONTROL AND COMMUNICATIONS  $(C^3)$ 2.3.4

- Summary Description  $--c^3$  functions are accomplished by **(U)** 2.3.4.1 subsystems and equipments arranged and integrated to optimize the collection, evaluation, display, and dissemination of data and intelligence supporting command and control. The  $C^3$  system includes equipments for:
  - Display

- Data processing
- Navigation and collision avoidance
- Interior communications
- Exterior communications
- (U) The  $C^3$  system interfaces with Combat System elements for underwater, surface and air surveillance, as well as Combat System fire control and weapons elements.
- (U) Worldwide navigation capability and continuous absolute and relative position as well as ship's speed, heading, drift angle and attitude, are provided by the navigation system. The navigation system includes the hardware and data processing necessary to receive and integrate signals from an inertial navigation system (SHIPS-G-5683; TYPE II), and from Omega (SRN-17) and satellite radio mavigation (AN/WRN-5: SATNAY).
- (U) The surrounding surface environment is monitored to provide the capability to sense and quantitatively measure potential collision situations. The collision avoidance subsystem displays the surface situation and computes trial evasive maneuvers so that the ship may safely avoid predicted areas of danger. Navigation aids, shoals, and other significant data are stored for display as a synthetic map along with radar derived data as an aid in coastline, harbor, river, and shoal area piloting.
- List of  $C^3$  Equipment -- The list of  $C^3$  equipment is contained (U) 2.3.4.2 in Appendix C. Interior Communications and Navigation Equipment are separately identified. The list itemizes equipment physical characteristics, weight and ship services requirements. UNCLASSIFIED

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- (U) Collection, evaluation, display and dissemination of information relative to the friendly and enemy environment, and control of sensors and weapons is centralized in a combat information center (CIC). Equipment and operator stations are arranged on the basis of functional adjacency requirements to improve reaction time and permit positive control over weapons and sensors.
- (U) The CIC arrangement permits evaluation of the air, surface or subsurface environment from a centralized station. The CIC operators exercise control of all weapons, sensors and **displays** and keep the commanding officer apprised of the tactical situation.
- (U) Multiple path exterior communications are provided, and communications equipment is arranged functionally in a manner consistent with minimum manning. Transmitter and receiver groups are located in the transmitter room adjacent to the communication center. Remote control devices for transmitter and receiver groups are centrally located in the communication center.
- (U) 2.3.4.3 C<sup>3</sup> System Weights -- The following table 2.3.4-1 delineates the weights of major C<sup>3</sup> subsystems.

· ·			
SUBSYSTEM	LT	kN	% OF TCTAL
<b>Command &amp; Control</b> System	5.0	49.82	15.5
Navigation System	3.5	34.87	10.9
Interior Communi- cations	14.7	146.47	45.6
Exterior Communi- cations	9.0	89.68	28.0
System Total	32.2	320.84	100.0

Table 2.3.4-1 (U): C<sup>3</sup> Subsystems Weights(U)

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- (U) 2.3.4.4  $C^3$  System General Arrangements and Function Block Diagrams -- $C^3$  system arrangements of the **ANVCE** Near Term Point Design SES are contained in Appendix B, Section B.S. Also included is an overall system block diagram encompassing only  $C^3$  e'ements but also elements of the ship's combat system **descri**ed in Section 2.3.7 of this report and a matrix of interior communications voice systems on the ship.
- (U) The drawings are grouped in the Appendix for consistency of report format and the benefit of the reader.
- (U) 2.3.4.5  $c^3$  Risk Assessment -- Only Navigation and IC Systems were evaluated in terms of risks. The remainder of  $c^3$  systems are comprised of government furnished or government nomenclatured equipment with minimal risk to the near term SES design.
- (U) Since the Navigation and Collision Avoidance Systems (CAS) are comprised almost entirely of government nomenclatured equipments, there is low technical risk in its implementation. Modifications to the AN/APS-116 radar constitute the principal departure from nomenclatured equipment. There is low technical risk involved in developing the required NAVCAS computer programs. The CAS consists of the following elements:
  - a. CAS control and display
  - b. **AN/APS-116M** Collision Avoidance Radar Subsystem with its own dedicated control unit
  - c. CAS data processor and computer programs (AN/UYK-20(V))
  - d. CAS water depth sensor
  - e. CAS map data storage

- f. Low light level television (space and weight)
- g. Radar Beacon (space and weight)
- h. Back-up search radar **AN/SPS-55** (part of Surface Surveillance, Section 4.4.6)

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(U) Navigation and collision avoidance equipment was selected from Navy inventory items to meet the accuracy, reliability and special requirements of the near term SES. The interior communication system (IC) equipment group provides the means and methods for directing functions within the near term SES, other than for weapons control, by the transmission and reception of orders and the exchange of information by electrical and audible means. The IC equipment group also provides audio and television entertaiament. All IC system equipments are standard equipments and involve minimum risk.

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#### 2.3.5 AUXILIARY SYSTEMS

- (U) 2.3.5.1 Auxiliary Systems Less Lift System -- The near term SES auxiliaries combine traditional shipbuilding experience with innovative design. The auxiliary systems were developed for operational requirements with performance, reliability and low weight as primary objectives.
- (U) 2.3.5.1.1 Climate Control System -- The Climate Control System consists of the compartment heating, ventilation, and air conditioning (HVAC) system; machinery space ventilation; and rhe ship's stores refrigeration system.
- (U) Heating, Ventilation and Air Conditioning (HVAC) -- The HVAC System provides conditioned air to various spaces and/or major equipment located throughout the ship. The system combines electrical resistance heating; meachnical fresh air supply and exhaust; and recirculating air conditioning. The system features 400 Hz electric motor powered packaged air conditioning plants and 400 Hz electric motor driven axial flow fans.
- (U) Machinery Space Ventilation -- Thirteen air supply systems supply 100 percent summer cycle outside air to all auxiliary machinery rooms, electrical generator rooms, lift fan rooms, lift fan engine rooms, and main propulsion engine rooms. There are no duct preheaters for heating air in winter cycle.

(U) Refrigeration System ~ Two separate 400 Hz motor driven centrifugal, packaged type, refrigeration plants are provided for ship's stores refrigeration. Each refrigeration machine supplies freon to the cooling coils in the freezer and chiller spaces. One unit maintains the required temperatures for both spaces during normal operation with redundancy provided by the second machine; two refrigeration machines are used for pulldown.



- (U) 2.3.5.1.2 Seawater Systems -- The Seawater Systems consist of all seawater supply and drainage systems. These include fire main, sprinkling, auxiliary seawater, scuppers and deck drains, plumbing drains, and drainage systems.
- (U) Firemain and Auxiliary Seawater System -- The seawater services are furnished by a single combined firemain and auxiliary seawater system.

The system is arranged as a **firemain** for damage control considerations, and separated into fire and auxiliary service functions at the respective required pressures. Four each centrifugal Dumps are used. They are each capable of a delivery of 400 gpm  $(.252 \text{mm}^3/\text{s})$  at 125 psig (0.862 kPa).

- (U) Scuppers and Deck Drains -- The scuppers and deck drains consist of all space deck drains at and above the second deck. Space deck drains (with GRP piping) from wet spaces and fan rooms are combined and directed overboard via scupper valves, The overboards are located on the third deck above the full load waterline to reduce drag.
  - (U) Plumbing Drains -- The plumbing drains are vacuum assisted which collect soil wastes from water closets and urinals, and waste drains from showers, lavatories, sinks, laundry, galley, and scullery. The drains are led to a vacuum collection tank from which wastes are either discharged overboard or directed to the collecting holding and transfer tank (CHT). Connections are also provided for discharge to shore receiving facilities.
  - (U) Drainage System -- The drainage system consists of a main and secondary drainage system which provides the drainage for the machinery spaces and other spaces on and below the third deck. The main drainage eductors of 500 gpm (0.317 mm<sup>3</sup>/s) capacity are provided for the propulsion engine rooms and the waterjet pump rooms. Eductor actuating water is provided by the fire main and auxiliary sea water

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system. Discharge is overboard above the full-load off-cushion waterline,

- (U) 2.3.5.1.3 Fresh Water Systems -- Fresh water systems include the distilling plant, the potable water system, the turbine water wash systems, the cooling water system, and the auxiliary fresh water cooling system.
- (U) Potable and Fresh Water System -- The potable water system is basically a standard shipboard system. The fresh (wash) water system operation is managed to reduce storage requirements. GRP piping is utilized to the maximum extent practical.
- (U) Cooling Water System and Auxiliary Fresh Water Cooling Systems -- Two electronic cooling water systems are provided: the cooling water system (freon cooled) and the auxiliary fresh water cooling system (seawater cooled). Cooling water for electronic equipment is provided by a closed loop system in accordance with pertinent NAVSHIPS drawings.
- (U) 2.3.5.1.4 Fuels and Lubricants Systems -- The light weight fuel and lubricants system is a straightforward design featuring common functional manifolds and minimal connections. The system consists of the ship's fuel oil system and the aviation fuel system, where a common fuel (JP-5) is used for all ship fuel services.
- (U) Ship's Fuel Oil System -- The ship's fuel oil system consists of the fill, transfer and service.
  - Fuel Oil Fill -- Fueling of the ship is provided at port and starboard fill stations. The fueling stations utilize seven inch (0.18 m) probe receivers, each capable of 3000 gpm (1.89 mm<sup>3</sup>/s). There are 23 fuel tanks.
  - Fuel Oil Transfer -- Provision is made for transferring fuel between tanks to shift the ship's center of gravity for optimum operating conditions. The 400 gpm (.252 mm<sup>3</sup>/s) pumps also transfer fuel to the fuel oil storage tanks, 156

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c. Fuel Oil Service - The two deep fuel oil service tanks are located amidships, port and starboard, with their adjacent fuel centers including functional manifolds, pumping equipment, filter coalescers and proper distribution lines. The port and starboard fuel service subsystems have the capability of cross-feed (redundancy) in emergency conditions.

- (U) Aviation Fuel System -- The aviation fuel system consists of the helicopter fueling and service system. The system includes two service tanks that are filled from the ship's storage tanks through filter coalescers.
- (U) 2.3.5.1.5 Air, Gas and Miscellaneous Fluids -- The air, gas and miscellaneous fluids consists of compressed air systems, nitrogen systems, fire extinguishing systems, and hydraulic fluid systems.
- (U) 'Compressed Air Systems -- Both low pressure and high **pressure** air systems are provided.
  - o Low Pressure Air System -- The low pressure compressed air system is furnished by bleed air from the GTG and main propulsion engine gas turbine. The low pressure compressed air system **consits** of ship's service, control air, and starting air system.
  - High Pressure Air System -- A high pressure air system is provided for charging MK-32 torpedo tubes. A nominal 3000 psig (20.68 MPa) compressor, dehydrator and air flasks are used for this particular launch activity.
- (U) Nitrogen System -- A Nitrogen System is provided for helicopter services. The nitrogencharging station in the helicopter hangar consists of five cylinders and a variable regulator capable of supplying 70 to 3000 psig (.048 to 20.68 MPa)of oil free nitrogen for helicopter tire inflation and other helicopter services.

- (U) Fire Extinguishing Systems -- The fire extinguishing systems on the ship consist of AFFF, Halon (FE 1301) fixed flooding systems, hi-expansion foam, and portable Halon extinguishers.
  - A high capacity AFFF proportioning system is provided **for** the helicopter hangar and landing area. A fixed sprinkling system is provided for the hangar and two hose stations are provided port and starboard on the landing platform.
  - Fixed flooding **Halon** systems which meet the requirements of NFPA No, **12A**, are the primary fire extinguishing systems for propulsion engine rooms; lift fan engine rooms; auxiliary machinery rooms; **waterjet** pump room; and electrical generator rooms.
  - A high expansion (Hi-X) foam system is provided as a secondary (backup) system for the Halon fixed flooding systems, Port, starboard, and amidships proportioning units are supplied from the fire.main system.
- (U) -Hydraulic System -- A centralized hydraulic system provides hydraulic flow for the subsystems and incorporates a lightweight flexible power distribution system capable of rapid response. Operating mode evaluations indicate that **the main dydraulic** power can be delivered by two hydraulic pumps driven by the lift fan engines. These pumps will be augmented by electric motor-driven pumps of comparatively small flow rate during peak hydraulic load activities. The motor-operated pumps will also be used during off-cushion and **in**port operations.
- (U) The maximum system hydraulic power available is 273.5 gpm (0.173 mm<sup>3</sup>/s) at 3000 psig (26.68 MPa); hydraulic fluid in accordance with MIL-H-83282 w-ill be used,

- (U) 2.3.5.1.6 Underway Replenishment System -- The Underway Replenish-. ment System comprises the Replenishment-at-Sea System and the Ship Stores and Personnel and Equipment Handling.
- (U) Replenishment at Sea -- Replenishment at sea is provided for by VERTREP and alongside refueling. A combined VERTREP, HIFR, and Helicopter Landing area is provided on the main deck aft of the hangar.
- (U) Stores, Personnel and Equipment Handling -- Strikedown has been simplified as much as possible by arrangement of magazines, storerooms and refrigerated spaces on the main and second deck for each of access. Handling on the main deck will be by hand pallet trucks, package truck, and manual means. Materials to be struck down to the second deck will be conveyed by a vertical conveyor, located starboard. A stores handling area is provided on the second deck. Heavy items will be handled by davit and monorail, The co-location of galley and refrigerated spaces eliminates need for a dimbwaiter.

- (U) 2.3.5.1.7 Mechanical Handling System -- The mechanical handling systems are the anchor handling, mooring and towing, boat handling, hangar door, and the helicopter securing-and traversing system.
- (U) Anchor Handling System -- The basic requirements are anchoring with a 70 knot (36.01 m/s) wind velocity, a 4 knot (2.06 m/s) current velocity, and in 40 fathoms (73.15 m) water depth,
- (U) A single anchor, of the **Danforth** Hi Tensile type, was selected on the basis of the recommended criteria.
- (U) Mooring and Towing. System --Three line handling capstans are provided to facilitate mooring alongside piers and other ships.
- (U) Boat Handling and Stowage -- Boat handling facilities consist of abandon ship equipment and an inflatable hard bottom boat for use

during helicopter plane guard operations and for man overboard recovery. Six MK-V inflatable CO<sub>2</sub> twenty five-man life rafts are provided in standard containers.

- (U) Hangar Door System -- Horizontally deployed hangar doors are used and consist of vertical hinged panels which travel on horizontal tracks. The doors are mounted under constant tension by spring loaded lower roller bearings that apply tension to upper roller bearings. Door operation is by an electric motor and gearbox drive.
- (U) Helicopter Securing and Traversing -- A helicopter securing and traversing system will be installed, but its final design has not been made. Alternatives which will meet the design requirement with use of minimum space and weight include a present preference for a modified version of the prototype being developed by the Navy for use aboard aviation facility ships. The unit is modified to accommodate two (2) helicopters.
- (U) 2.3.5.1.8 Special Purpose Systems -- The Special Purpose Systems consist only of the Environmental Pollution Control System. The Environ-~ mental Pollution. Control System is concerned primarily with the solid and liquid wastes produced by the ship. The primary item is the Collecting, Holding and Transfer (CHT) tank which collects all plumbing and fresh water drains. The holding tank is sized to accommodate one day's waste. A sewage pump is used to discharge waste from the vacuum collection tank to the CHT. This same pump (a standby pump is provided) is used to discharge the CHT to a shore connection. A sewage eductor is used outside of the contiguous zone.
- (U) Garbage is ground and flushed, via the vacuum collection tank, to the CHT, Solid trash is treated by compaction and retained aboard for disposal at a shore facility.
- (U) Contaminated oil drains (fuel, lube oil, helo defuel, stripping lines, etc.) are discharged into an oily water drain tank. They are pumped to share facilities by the waste oil drain pump.

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(U) 2.3.5.1.9 Auxiliary Systems Percentage Weight Breakdown -- Table 2.3.5-1 shows the estimated percentages for major auxiliary subsystems less the lift system.

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Table	2.3.5-1	(U):	Auxiliary	Syst	ems P	ercentage	Weight	Breakdown
			(Less ]	Lift	System	n) <b>(U)</b>		

SUBSYSTEM	% OF SYSTEM.
Heating, Ventilation, and Air Conditioning Seawater Fresh Water	13.4 15.4
Fresh water Fuels and Lubricants	10.6
Handling and Storage Air, Gas, and Misc. Fluids Mechanical Handling	19.9 19.0
Special Purpose System Miscellaneous	11.3 1.3



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#### (U) 2.3.5.2 Lift System

- (U) 2.3.5.2.1. Air Distribution Summary Description -- Lift system air distribution consists of two sets of lift machinery and ride control equipment schematically shown in Figure 2.3.5.2-1. Each set of lift machinery is arranged in an in-line configuration, one set on each side of the ship. Power for each set of lift machinery is supplied by an LM 2500 gas turbine engine. The required power and speed is delivered to the lift fans via the lift power transmission system which consists of the reduction gear unit, shafting, and associated components. The lift fans draw air through inlets on the ship's deck, and discharge The forward fan into separate and independent air distribution ducts. on each side of the ship supplies air to the bow seal, the center fan supplies the cushion, and the aft fan discharges into the stern seal. Each fan duct is supplied with a shut-off valve to prevent back flow when the fan is not operating.
- (U) 2.3.5.2.2 Seals Summary Description -- The design for the bow and stern seals utilizes a series of flexibly connected fiberglass planers at the water interface. A nylon/elastomer pressure bag behind the planers provides the force to contour and support the planers. Entitled the Advanced Planing Seals, they are a new, improved concept in SES seals that combines excellent low drag performance with rugged, high wear resistance qualities. The excellent wear resistance of the planing seals is exemplified by high speed water impact erosion of the glass reinforced plastic (GRP) elements, orders of magnitude less than that occurring with the rubberized fabric material of the common bag and finger seal systems. The advanced planing seals also perform the normal and vital functions of containing the air in the cushion, contributing to ship ride quality, and providing pitch and roll restoring forces to the ship.

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- (U) 2.3.5.2.3 General Arrangement -- The air distribution and seals are arranged as shown in Figure 2.3.5.2-2. Details of the air distribution and seals combined system are discussed in the next paragraph.
- (U) <u>Power Units</u> A total of two gas turbines, each driving three VG fans through a reduction gearbox, are utilized in the SES lift system. One LM 2500 is located on the starboard side of the ship and the other on the port side. Each gas turbine is independent of the other, and can deliver 22,500 (16.78 kW) continuous shaft horsepower and 27,000 (20.13 kW) intermittent shaft horsepower. The link mounting system is identical to that used for the propulsion plant LM 2500 gas turbines.
- (U) <u>Power Transmission System</u> --- The power transmission system begins at the flange which connects the power turbine to the reduction gearbox shaft. A disc type brake is mounted on the ;;earbox at the input shaft. At the output side of the reduction gearbox, a torsionmeter is installed, Two diaphragm type flexible couplings are installed between the torsionmeter (gearbox output shaft) and the first lift fan, one at each end of the shaft. The driven power to the fan rotor is picked up through the integral fan couplers. The integral fan couplers are those sections of drive shaft within, and integral to, the fans which permit decoupling of any fan. Flange couplings are used at each end of the fan throughshaft to connect to the drive shaft. A length of shafting and two shaft bearing supports with associated couplings are situated between the fan couplers of the second and third fans. Seals are provided where the life shaft penetrates watertight bulkheads,
- (U) The lift reduction gearbox is a parallel shaft design with an overall reduction ratio of 1.93 to 1. The gearing is external double helical of involute form and is case hardened and ground to AGMA quality 12 or better. The gear case is an aluminum casting.
- (U) The power transmission system for each set of lift fans is designed to transmit a maximum of 27,000 bhp (20.13 kW) from the gas turbine



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through the reduction gears to the lift fans. The system is designed to accommodate a maximum input shaft speed of 3,600 rpm (60 r/s) from the turbine and a **maximum** output shaft speed of 1,865 rpm (3108 r/s) from the reduction gear to the fans.

- (U) Lift Fans -- The Lift and Ride Control System uses a total of six lift fans. The fans are symmetrically located, three port and three starboard, with each group positioned in line on a common shaft.
- (U) All of the lift fans are identical except for assembly differences that depend on fan location. The fans are centrifugal type with an 86-inch (2.18m) diameter rotor, a housing, and variable geometry elements. They incorporate double axial inlet design, airfoil shaped radial blades, constant velocity volute housings, and a single circular discharge. The variable geometry fan elements (translating sleeve in each of the inlets) are included for modulating the air flow for ride control purposes. The fan is shown in Figure 2.3.5.2-3.
- (U) Included in the fan envelope are the self-contained rotor decoupler, rotor bearings and coaxial line shafting that permft independent decoupling of any fan while operating under any design load. The mechanisms additionally provide for remotely activated recoupling of fans from an at-rest condition.
- (U) <u>Lift Ducting</u> -- The lift air is delivered through ducts to the bow seal, cushion, and stern seal. The bow and cushion air ducts are short, conical sections which act as diffusers to reduce high velocity losses. The stern seal air duct is long in comparison and employs turning vanes in most elbows to reduce pressure losses. The long stern seal duct was selected in favor of long shafting as a result of trade-off studies. Ducting sizes are optimized for the system operating conditions. Attention is given to the velocity of the air balanced against the space allocation for the ducts,

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- (U) The four forward ducts have hydraulically operated butterfly type shut-off valves located near the fans. A louvered type shut-off valve is located over the stern seal in the long supply duct from the aft fan. These shut-off valves prevent back flow from the pressurized cushion if a fan is not operating for any reason. A pair of stern seal transfer ducts is also included in the lift system. These ducts provide stern seal to cushion air flow and contain throttling valves for stern seal to cushion pressure ratio regulation.
- (U) <u>Lift Air Intakes</u> -- The lift fan inlets supply atmospheric air to the lift fans for pressurization and subsequent distribution into the cushion, bow seal and **stern** seal. Five openings are provided in the deck, port and starboard, to supply air for each group of three fans. The intake openings are positioned directly above the lift fan bellmouths. Four of the inlets are 12.2 feet (3.72 m) wide by 4.4 feet (1.34 m) long; the fifth inlet, which supplies the adjacent inlets of the mid and aft fans is 12.2 feet (3.72 m) wide by 8.9 feet (2.71 m) long,
- (U) A fairing is provided around the openings to eliminate the ship boundary layer air and surface water flowing on the deck from entering the fan air inlets. The inlet design incorporates aerodynamic turning vanes to direct the air flow downward into the fan rooms. The vanes permit recapture of about half the air velocity head across the deck. An electrical heating system is incorporated in the vanes to provide antiicing capability. The vane walls of each flow passage are treated , to provide the necessary sound attentuation,
- (U) <u>Ride Control System</u> -- The ride control system integrates the variable geometry lift fans and vent valves and their associated actuators with appropriate ship motion sensors and the controller electronics into an active system. The total active system modulates the seal and cushion airflows to reduce the ship's heave accelerations to an acceptable level. The primary ride control system uses the variable geometry fans to control airflow. Vent valves are provided to expand the flow range

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- (U) available in high seas and to provide maximum versatility for RCS development.
- (U) The variable geometry feature of the fans consists of hydraulically translated sleeves in the fan inlets, The sleeves have a maximum travel range of 18 inches (0.46 m). When fully closed, they reduce fan flow to less than 10 percent of design point conditions. The frequency response bandwidth of the sleeve actuating system is 0 to 2 Hz, The nominal maximum slew rate is 57 inches/second (1.45 m/s),
- (V) The cushion vent system consists of two identical valve and duct arrangements at the stern of the ship near the centerline. The ducts, as shown in Figure 2.3.5.2-4 extend from the two wet deck cushion openings just forward of the stern seal into the third deck area and out of the transom of the ship. Discharging the vented air aft generates some propulsive thrust. Hydraulically operated, fast response, louvered valves are positioned in the ducts at the third deck level. The valves, as pictorially shown in Figure 2.3.5.2-S are designed as a battery of modules for fast response, reliability, and ease of replacement, The cushion vent ducting and valves accommodate flow rates up to 60,000 cfs (28.3  $m^3/s$ ). The valves are designed for a maximum pressure differential of 600 psi (4.14 MPa). Vent valve frequency response bandwidth is 2 Hz. Nominal maximum slew rate is 2.5 full strokes (close-open-close) per second.
- (U) <u>Advanced Planing Bow Seal</u> -- The advanced planing bow seal is **illus**crated in Figure 2.3.5.2-6. Geometry of the seal is given in Figure 2.3.5.2-7. The seal **consists** of four main elements which are next described.
- (U) An elastomer pressure bag is attached to the bow at the 40 foot (12.19
  m) waterline and normally extends aft in a continuous circular arc and connects to the wetdeck. The bag is configured of eight identical modules with elastomer end caps at the sidehull interfaces, The bag

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- (U) and end caps provide a flexible structure which contains the bow seal air while minimizing water ingress into the seal. The aft loop of the bow bag contains slotted openings of fixed width to provide controlled air flow between the seal and the cushion and to assure rapid water drainage.
- (U) The planer/stay portion of the seal consists of thirty-two (32) modules across the beam of the craft. These planer/stay modules are constructed of glass reinforced plastic (GRP) and are attached to the wetdeck at the 40 foot (12.19 m) waterline. The upper forward portion, or stay, has relatively low stiffness allowing it to conform to the curvature of the forward portion of the bow bag. Near the lowest portion of the bow bag loop, the stays widen and are joined together by flexible sealing strips to form a continuous fiberglass planer surface.
- (U) A 31-inch wide tapered GRP feather edge is attached to the trailing end of each bow seal planer module. This feather edge, having increased flexibility is used to attentuate the effective wave impact on the seal, assist in cushion sealing and improve the seakeeping capability of the craft,
- (U) Each planer is supported by a geometry strap and a retract strap. The strap provides mid span support and geometric control of the planer through the full range of sea states. The geometry strap normally carries a tension load due to the cushion pressure acting on the planers, but may be unloaded for a short duration when encountering high waves at a higher velocity.
- (U) A seal retract strap is attached to the retraction reel recessed inside the hull and extends down to an attachment at the aft edge of each planer, The straps provide for full retraction of the seals against the wetdeck for off-cushion operation and also for adjustments and trimming of the seals for minimum drag during hump transit, partialcushion and full-cushion operation.

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- (U) The 32 straps pass through slots in the wetdeck structure, and over sheaves, before attachment to the retraction reel drums. Provision is made at each drum for unlimited strap length adjustment. Locks at the retraction drive outputs prevent inadvertent seal extension by high loadings. The drive units allow for high and low speed seal retraction, low speed extending adjustment, and the rapid free-wheeling extention associated with the craft going on-cushion
- (U) <u>Advanced Planing Stern Seal</u> -- The stern seal is illustrated in Figure 2.3.5.2-8 and the seal geometry is given in Figure 2.3.5.2-9. Planer/ stay elements are attached to the wetdeck and extend to waterline 0. These elements are similar to those of the bow seal, i.e., tapered trailing edge. I-beam reinforced planing section, and highly flexible stay section, with the exception being that the stays are the width of the planer module. Thirty-two modules span the beam of the craft. The full width stays protect the elastomer bag membrane from the erosive effects of direct high speed water impact. The planer attachments are identical to those of the bow seal.
- (U) A four-lobed bellows bag is attached between the wetdeck and planer to contain air pressure within the stern seal. The bellows bag is built in modular sections and is fabricated of the same nylon/elastomer material as the bow seal bag, Holes are located along the lower lobe of the bellows bag and sized to permit rapid drainage of water. The four-lobe bellows is optimum for seal spring rate requirements and for tensile loading in the membrane.
- (U) Convolute tension cables are connected between the wetdeck and the junctions of the lobes of the bellows bag in order to maintain the geometry of the bellows bag through the entire deflection of the seal. A set of lower geometry straps, connected between the wetdeck and the planer at the bellows bag/trailing edge junction, restrain the aft movement of the seal. Retract straps are attached to each planer near the planer's trailing edge and are connected to the retract system

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(U) reel in a manner similar to the bow seal system. The stern seal retraction system is similar to the bow system.

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(U) 2.3.5.2.4 Tabulation of Key Parameters -- The key parameters of the lift system are presented in Tables 2.3.5.2-1, Lift System Physical Parameters, Table 2.3.5.2-2, Lift System Point Design, and Table 2.3.5.2-3, Seals Design Parameters.

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#### Table 2.3.5.2-1 (U): Lift System Physical Parameters (U)

		UNITS		VALUES	
		ENGLISH	(SI)	ENGLISH	(SI)
1.	Engine - LM2500, 2 Required				
	Design Rotational Speed	RPM	(r/a) Ku	3500	(58.33)
	Maximum Continuous Power (MCP)	HP	(kW)	22500	(16785)
	Specific Fuel Consumption (SFC)	Lb/SHP-Hr	(kN/kW-Hr)	.40	(2.39)
	Maximum Intermittent Power (MIP)	нр	(kW) / 10/	27000	(20142)
	Volume	Ft <sup>3</sup>	$(m^3) / (m^3)$	1064	(30.129)
	Basic Engine Weight	Lb	(kN) ~~~	10300	(45.817)
2.	Reduction Unit With Brake, 2 Req.				
	Power Capacity	UP	(kW)	27000	(20142)
	Gear Ratio			1.93	
	Gear Type: Single Reduction, Dougle	e Helical Invo	lute Tooth		
	Volume	Ft <sup>3</sup>	(m <sup>3</sup> ) KY	114	(3.228)
	Weight Port	Lb	(kN)	4922	(21.894)
	Weight Starboard	Lb	(kN) - V()	3762	(16.734)
3.	Lift Fans (ALRC) 6 Required				
	Type : Centrifugal, Dual Inlet, Cor	nstant Velocity	Volute, Variable	Geometry, Decc	oupling Device
	Rotor Diameter	In	(m)	86	(2.184)
	Rotational Speed	RPM	(r/s)	1450	(24.17)
	Tip Velocity	FPS	(m/s)	544	(165.8)

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, Table 2.3.5.2-1 (U): Lift System Physical Parameters Continued (U)

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		UNITS		VALUES	
		ENGLISH	(SI)	ENGLISH	<b>(</b> SI)
3.	Lift Fans (ALRC) Continued		KPA		
	Design Head Rise	PSF	(k/Pa)	333	(15.9)
	Design Flow	CFS	(m <sup>3</sup> /s)	6039	(171.005)
	Design Efficiency, Fan Percent			84	
	Specific Speed, $N_{S} = \frac{NO^{2}}{H^{3/4}}$			144	
	Exit Diameter	In	(m)	82.5	(2.096)
	Design Exit Velocity	FPS	(m/s)	163	(49.7)
	Maximum Rotational Speed	RPM	(r/s)	1865	(155.42)
	Maximum Flow (Approximate)	CFS	(m <sup>3</sup> /s)	10000	(283.2)
	Maximum Power	UP	(kW)	9000	(6714)
4.	Transfer Shafting				
	Total Length (1) Per Ship	Ft	(m)	104	(31.699)
	Total Weight (2)	Lb	(kN)	8756	(38.948)
5.	Distribution Ducting				
	Total Length <sup>(3)</sup> Per Ship	Ft	(m)	532	(162.154)
	Total Weight <sup>(4)</sup>	Lb	(kN)	26631	(118461)
6.	Fan Inlets				
	Type: Flush <b>Horizontal</b> with Acou	stic Turning Vane	es.		
	Velocity Ratio (IVR) at 80 Knots	(Free Stream/Inle	t Velocity)	.70	
	Weight	Lb	(kN)	11910	(52.978)

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- (1) **Total** length from gear box interface to last fan. Pan internal shafting not included.
- (2) Includes shafting flex couplings and bearing pedestals.
- (3) Includes ride control ducting.
- (4) Includes flex coupling and values.

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Table 2.3.5.2-2 (U): Lift System Point Design (V)

Ship Weight:	LT (kN)	3000 (2.9892 E+04)
Wave Height H1/3:	Ft (m)	4.6 (1.40)
Ship Speed :	Knots (m/s)	80 (41.2)
Pressures:	PSF (kPa)	
Bow:		349 (16.71)
Cushion :		342 (16.38)
Stern:		376 (18 .00)
Total Flow Rate:	CFS (m <sup>3</sup> /s)	37500 (I 061.88)
Lift System Efficiency:	X.	76.1
Duct Losses:	PSF <b>(kPa)</b>	
Bow :		28 (1.34)
Cushion:		24 (1.15)
Stern:		39 (1.87)
Fan Parameters:		
Speed:	RPM	1535
Total <b>Shaft</b> Power	<sub>HP</sub> (kW)	29743
Flow:	CFS (m <sup>3</sup> /s)	
Bow:		13146 (372.253)
Cushion:		13650 (385.525)
Stern:		10721 <b>(303,585)</b>
Engine Parameters (LM2500)	میں بیس ہے۔ میں میں	
Speed :	RPM	3266
Total Brake Power	HP (kW) / $\mathcal{N}$	• 30661 (22873.1)
Total Fuel Flow	Lbs/Hr (N/s)	13556 <b>(16.750)</b>
SFC	Lbs BHP-Hr ( <u>N</u> ),	<b>.442</b> (2.636)

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Table 2.3.5.2-3 (U): Seals Design Load Parameters (U)

1. BOW SEAL LOADS

ELEMENT	<b>DESIGN<sup>(1)</sup></b> FACTOR (MINIMUM)	NOMINAL WORKING LOADS	MAXIMUM LOADS
Wet Deck Stay	2	2800 <b>lbs/ft</b>	13,300 <b>1bs/ft</b>
Attachment		(114,000 N/m)	(202,000 N/m>
Fwd Wet Deck Bag	1.5	610 <b>lbs/ft</b>	19,200 <b>1bs/ft</b>
Attachment		(8,900 N/m)	(280,000 <b>N/m)</b>
Aft Wet Deck Bag	1.5	380 <b>lbs/ft</b>	13,200 <b>155/ft</b>
Attachment		(5,600 <b>N/m)</b>	(192,500 N/m)
Geometry Strap	2	20,990 <b>lbs/strap</b> (93,300 N/strap)	<b>43,010 lbs/strap</b> (142,000 N/strap)
Retract Strap	2	1,000 <b>lbs/strap</b> (4,450 N/strap	38,250 <b>lbs/strap</b> (171,500 N/strap)
Module-to-Module	2.0	340 <b>lbs/f</b> t	975 <b>lbs/ft</b>
Joint		(5,000 N/m)	(14,200 N/m)
Planer-to-Planer	2.0	1,000 <b>lbs/ft</b> (14,600 <b>N/m)</b>	5,000 <b>1bs/ft</b> (73,000 <b>N/m)</b>

(1)<sub>Maximum</sub> load multiplied by its respective design factor is the ultimate design load.

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Table 2.3.5.2-3 (U): Seals Design Load Parameters (Continued) (U)

ELEMENT	DESIGN FACTOR (MINIMUM)	(1)	NOMINAL WORKING LOADS	MAXIMUM LOADS
Planer Attachment to Wet Deck	2		710 <b>lbs/ft</b> (10,500 N/m)	8,650 <b>lbs/ft</b> (126,000 N/m)
Geometry Strap			1,420 <b>lbs/strap</b> (6,320 N/strap)	36,400 <b>lbs/strap</b> (162,000 N/strap)
Wet Deck Attachment, Geometry Strap	1.5		1,440 lbs (6,400 N)	44,000 lbs (196,000 <b>N)</b>
Convolute Cable	2		8,426 <b>lbs/cable</b> (37,400 N/cable)	15,690 <b>lbs/cable</b> (69,700 N/cable)
Retract Strap	2		9,000 <b>lbs/strap</b> (40,000 N/strap)	39,550 <b>1bs/strap</b> (176,000 N/strap)
Stern Bag Wet Deck Attachment	1.5		830 <b>lbs/ft</b> (12,100 N/m)	13,200 <b>lbs/ft</b> (193,000 <b>N/m)</b>
Planer-to-Planer Joint	2.0		1,000 <b>lbs/ft</b> (14,600 N/m)	5,000 <b>lbs/ft</b> (73,000 N/m)

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-44 -14 -14 **Maximum** load multiplied by its respective design factor is the: ultimate design load.

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Table	2.3.5.2-4	(U):	Seal	Materials	Physical	Properties	(U)
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Planer <b>Materials</b> Gloss	UNITS	VALUES <sup>(1)</sup>
Reinforced Fabric	English (SI)	English (SI)
	2 2	
eneric Materials		
S-Type Class		
Epoxy Resin		
sin Content	3 4	
nsile Strength	10°psi 10°Pa	29 <b>(29)</b>
Longitudinal		128 (610)
Transverse	3 /	110 <b>(525)</b>
.exible Strength	10 <sup>°</sup> Psi 10 <sup>°</sup> Pa	
Longitudinal		164 <b>(795)</b>
Transverse	<i>(</i>	142 <b>(680)</b>
lexural Modules	10 <sup>0</sup> psi 10 <sup>7</sup> pa	
Longitudinal		4.6 (21.0)
Transverse		3.7 (17.7)
<b>Pressure Bag</b> Materials Elastomer Coated Fabric		
:neric Materials		
Nylon Fabric		
Neoprene Elastomer		
ansile Strength	lbs/inch (N/m)	
Warp		<b>1805</b> 316.00
Fill		1620 <b>284.00</b>
longation. Ultimate	7 7	
Warp		53 53
Fill		72 72
		10 10
Pressure <b>Mag</b> Materials	UNITS	VALUES
Elastomer Coated Fabric	English (SI)	English <b>(SI)</b>
leight	$o_z/s_{g}$ , vd $(k_g/m^2)$	90 3.05
hating Adhesion	lbs/inch (N/m)	20 3.03
Warn		70 12 200
		62 10 050
:	inches (m)	
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		0.100 0.00254

(1)  $_{\rm Values}$  for 0/90 degree eleven ply laminates



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Figure 2.3.5.2-1 (U): Lift System Air Distribution Schematic (U)

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Figure 2.3.5.2-2 (U): SES Lift System Arrangement (U)

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Figure 2.3.5.2-5 (U): Cushion Vent System (U)



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Figure 2.3.5.2-7 (U): Advanced Planing Bow Seal Geometry (U)

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Figure 2.3.5.2-8 (U): Advanced Planing Stern Seal Assembly (U)



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Figure 2.3.5.2-9 (U): Advanced Planing Stern Seal Geometry

(U) 2.3.5.2.5 Lift System Weight Breakdown -- Table 2.3.5.2-5 shows the weight of each major lift system subsystem and each subsystem's percentage of the Lift System total.

	WEIGHT			
SUBSYSTEM	ĹT	kN	% OF TCTAL	
Engines	10.5	104.62	10.9	
Fans	20.5	204.26	21.2	
Reduction Gear and Shafting	8.2	81.70	8.5	
Seals	31.1	309.88	32.2	
Ducting	7.4	73.73	7.7	
Valving	4.5	44.84	4.7	
Intakes	8.8	87.68	9.1	
Uptakes	1.9	18.93	2.0	
Support System	3.7		<u> </u>	
LIFT SYSTEM TOTAL	96.6	962.52	100.0	

Table 2.3.5.2-5 (U). Lift System Weight Breakdown (U)

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- (U) 2.3.5.2.6 Lift System Technical Risk -- The total lift system risk depends upon the individual component risks. Considering the diversification of functions and the number of components included in the lift system (lift air machinery, ride control elements, seals), the overall risk is subjective and is based on the relative importance of each function as follows:
  - Lift Gas Turbine Engine System -- The LM2500 gas turbine engine is a production unit and is in use in other marine applications. The integration of this power unit into the lift system is well within present technological capabilities.
  - Power Transmission System -- Reduction gear design employs proven technology and similar gearbox designs have been utilized for marine applications. The transmission system arrangement and component selection are proven and within the present state-of-the-art. There is no apparent development risk for this system.
  - Variable Geometry Fan -- The variable geometry fan concept has been proven feasible by test at a number of scaled sizes. Especially significant is the use of 1/4-scale ALRC lift fans with VG on the XR-1 testcraft. The lift fan design must be verified in terms of full-size ship requirements and integrative ramifications.
  - Duct Configuration -- The analysis of the lift system duct configurations predicts the pressure losses with a high degree of confidence. The construction uses proven marine/aircraft concepts.
  - Lift Air Inlet -- The analysis supporting the lift inlet design is **base** on existing aerodynamic flow concepts. The materials and the shaping of the turning vanes are well within the current technology of the marine/aircraft industry.
  - Ride Control Valves -- The ride control valves are a type similar to that used successfully in the 100A program. Proven

- (U) off-the-shelf type components are used throughout the system. To further improve reliability, the mechanism is a simple straight-forward linkage design similar to aircraft linkage systems that are presently in use.
  - Advanced Planing Seals -- The success of the advanced planing seals in the most recent model tests lends a high degree of confidence in the design. The analysis of loads for the fullscale configuration, along with the design objectives and materials selections, indicate that all considerations are well within the present state-of-the-art.



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#### (U) 2.3.6 OUTFITTING AND FURNISHINGS

- (U) 2.3.6.1 Key Features of 0 & F System -- Outfit and furnishings (O&F is composed of a number of subsystems whose functional requirements include providing (1) habitable living and functional working spaces for the ship's crew, (2) safety features and fittings such as rails and lifelines, (3) ease of access to the working and living spaces, (4) protection against abrasion or galvanic corrosion for the hull structure (5) insulation to provide passive thermal, fire and acoustic protection and (6) storage and service spaces as required for the ship and its crew to perform their mission., All O&F subsystems conform to General Specifications for Ships of the U.S. Navy and OPNAVINST 9330.7A (proposed).
- (U) 2.3.6.1.1 Habitability -- Crew living spaces are compartmented with a maximum of 12 men to a compartment. CPO living spaces are compartmented with a maximum of 5 men to a compartment. Officers staterooms are double occupancy except that the Commanding Officer and Executive Officer each have single, separate staterooms.
- (U) Messing areas are located within a convenient distance of respective crew living spaces. Cross-traffic has been avoided. The galley is centrally located to serve the crew from one side and the CPO and commissioned officers from the other, again, eliminating cross-traffic.
- (U) Recreation areas are also located within a convenient distance of the respective crew living spaces. The habitability spaces are all located on the second deck and the watch stations are readily accessible for all hands.
- (U) 2.3.6.1.2 Stowage -- Dry provisions, chill storage and freeze storage are located next to the galley. The vertical conveyor is located within a few steps of the galley and each storage area. Supply Department storerooms and spare parts storerooms were located in areas of the ship convenient to users (e.g., repair shops).

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- (U) Deck gear lockers are located near each mooring and towing station. This provides convenience for stowing deck gear and facilitates keeping the decks clear at all times.
- (U) 2.3.6.2 Passive Fire Protection -- A fire protection system is necessary as an element of damage control and must incorporate within the system both active and passive means. The **active** fire protection **system** is described in **2.3.5.** The passive fire protection system is designed to protect the primary structure until the active system is brought into play.
- (U) For the design of the fire protection system, the ship spaces were grouped into two major classifications: Group 1, liquid fuel fire hazard spaces; and Group 2, solid combustible fire hazard spaces. In addition to fire protection for these spaces, passive fire protection is provided for the torpedo and small arms magazines.
- (U) 2.3.6.2.1 Group 1 Liquid Fuel Fire Hazard Spaces -- Group 1 consists of all engine rooms, auxiliary machinery spaces, gas turbine generator rooms and the helicopter hangar,
- (U) Passive fire protection for bulkheads and overhead structures for all Group 1 spaces are provided by a ceramic fibrous felt sandwich panel.
- (U) Panel Design -- The panel (see Figure 2.3.6-1) consists of one inch (2.54 mm) thick refractory fiber felt of four (4)  $1b_f/ft^3$  (191.46 N/m<sup>3</sup>) density (Carborundum Fiberfrax felt or equivalent) between 0.010 inch (.25 mm) corrosion resistant steel (CRES) half-hard front face sheet and 0.012 inch (.30 mm) aluminum, marine grade, back face sheet. Ceramic tubular spacers 0.5 inch (12.7 mm) outer diameter x 0.156 inch (3.97 mm) inner diameter with #6 CRES screws and nuts are employed on a lo-inch (254 mm) grid pattern to maintain the panel thickness and hold the face sheets together.

- (U) Close-out members of the panel are 0,010 inch (.25 mm) CRES half-hard channels with 1/2 inch (12.7 mm) flanges seam half-hard channels with 1/2 inch (127 mm) flanges seam welded to the front face sheet and riveted to the back face sheet.
- (U) Panel Attachment The panels are attached to the structure by screw attachment with #6 CRES screws to 0.06 inch x 0.5 inch x 1.0 inch (1.52 mm x 12.7 mm x 25.4 mm) aluminum rectangular tubing "furring strips", The furring strips are attached to the structure by adhesive honding with an adhesive modified with a fire retardant. The panels are spaces from the primary structure with a 1/2 inch (12.7 mm) air gap.
- (U) Panel Joints -- Panel joints (see Figure 2.3.6-Z) are sealed from vapor penetration as well as heat penetration by sandwiching the panel ends between two strips of refractory fiber felt which are compressed between a 0.060 inch (1.52 mm) aluminum strip at the back of the joint and a 0.030 inch (.76 mm) CRES strip at the front or fire threat side of the joint. Corner joints are similarly sealed with 0.060 inch (1.52 mm) aluminum angles and 0.030 inch (.76 mm) CRES angles which are used as corner trim. Wicking would be prevented by inserting the paneis in aluminum channels which are adhesive bonded to the deck with a fire retarded adhesive. A silicone sealant would then be used to seal the panel in the channel.
- (U) Decks -- The decks in Group 1 areas are protected with a 0.25 inch (6.35 mm) thick ceramic fiber moist felt insulation (Refractory Products Company WRP-X-AQ or equivalent). It is a moldable fibrous ceramic felt in an inorganic colloidal silica binder and has a density of 15 lb/ft<sup>3</sup> (717.99 N/m<sup>3</sup>). The felt is packed in plastic bags during



Figure 2.3.6-1 (U): Insulation Panel Design (U)

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c) BULKHEAD PANEL TO DECK JOINT

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Figure 2.3.6-2 (U): Panel Joints Designed to Prevent Vapor Leakage In a JP-5 Fuel Fire (U)

(U) shipment and storage to prevent drying. After adhesive bonding the felt to the deck, it is allowed to air dry and harden. The felt is bonded to the deck with an **air**-setting ceramic **cement** (Carborundum QF-180 or equivalent), which has a layer thickness of 0,010 inch (.25 mm). After air drying, the felt is faced with fiberglass cloth impregnated with a fire retarded epoxy resin. The cloth is an 1800 plain weave with a weight of 10 oz/yd<sup>2</sup> (3.33 N/m<sup>2</sup>). The epoxy resin is room temperature curing (Shell Epon 934 modified with fire retardant agents or equivalent).

- (U) Stanchions, Penetrations and Ladders -- Stanchions are protected by wrapping with 0.750 inch (19 mm) thickness of the moldable fiber moist felt insulation. The moist felt is bonded to the stanchion with ceramic cement. The moist felt is overlapped 1.5 inch (38.1 mm) to prevent a direct path to the protected member. All penetrations are sealed to prevent passage of vapors. Where the penetrating member is exposed to a fire hazard, it would be protected from structural collapse with moist felt insulation and/or intumescent paint. Ladders would be fabricated from corrosion resistant steel.
- (U) 2.3.6.2.2 Group 2 -- Solid Combustible Fire Hazard Spaces -- Group 2 consists of all electro o spaces, living spaces and command centers.

Passive fire protection for bulkhead and overhead structure for all Group 2 spaces is provided by a refractory fiber felt sandwich panel similar to the panels used for Group 1 spaces but with a panel thickness of 0.5 inch (12.7 mm).

(U) The decks are protected with deck covering underlay material and tile or carpeting in these spaces, Stanchions, penetrations and ladders would be treated as described for Group 1.

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- (u) 2.3.6.2.3 Magazines -- The passive protection for the magazines is one inch (25.4 mm) thick lightweight glass thermal insulation on the interior surfaces of the compartments and 0.5 inch (12.2 mm) thick fire protection panels on the exterior surfaces of the compartments.
- (U) 2.3.6.3 Estimated Percentage Weight Breakdown -- Table 2.3.6-1 shows the estimated weight percentage of the major components of the O&F System.

Table 2.3.6-1 (U). Estimated Weight Percentage of Major Components of the **O&F** System **(U)** 

<u>SUBSYSTEM</u>	8 OF SYSTEM
Ship Fittings	2.6
Hull Compartmentation	11.5
Presserve and Coverings	18.6
Hull Insulation	42.9
Furnishings	24.0
Miscellaneous	0.4

- (U) 2.3.6.4 O&F Arrangement Drawings -- Arrangements of O&F subsystems are shown in the drawings contained in Appendix B, Subsection B.1. The Hull Insulation, Sheathing and Deck Covering System for the near term SES is shown on drawings contained in Appendix B, Subsection B.6.
- (U) 2.3.6.5 Outfit and Furnishings Risk Assessment -- The fittings, furnishings, coatings, and outfit items used on the ANVCE near term SES possess proven shipboard capability, and are not peculiar to the SES. Passive fire protection system concepts have been proven by an extensive test program. Consequently, the risk involved is considered minimal and is no greater than that of the outfit and furnishings subsystems of conventional Navy Surface Ships.

- (U) 2.3.7 COMBAT SYSTEM -- The combat systems of the ANVCE Near Term Point Design SES consist of systems that provide a capability in demonstrating the military value of an SES that performs anti-submarine warfare (ASW), anti-air warfare (AAW) and surface warefare (SUW) naval missions. These equipments are listed in Appendix C which contain6 weight, volume, geometry, and service requirements for each item,
- (U) The combat system6 comprise subsystem6 for underwater, air and surface surveillance. The subsystems consist of surface and air search **radars**, passive ESM systems, towed and dipping sonar devices, and dispensed **sono**buoys. Target identification and classification is accomplished by an IFF system.
- (U) Fire control systems are provided for surface-to-&r, surface-to-surface, and underwater weapons. Surface-to-air and point defense weapons consist of vertially launched Standard missiles, and dual Close-In-Weapon System (CIWS) installations (space and weight). The anti-shipping weapons are Harpoon and MK48 torpedo. The ASV self-defense and offensive weapon is the MK46/1 torpedo. Weapons and sonobuoy delivery for offensive ASW operations is accomplished by helicopter (SH-3H). Space reservations have been made for future applications of mini-RPV's for SUW target localization and weapon terminal guidance, as well a6 for relaying sonobuoy field telemetry data.
- (U) 2.3.7.1 Surveillance -- Air surveillance is provided by the air search radar AN/APS-125 and DPEWS AN/SLQ-31(V2) or AN/SLQ-32(V2) systems. A backup capability is provided by the MK92/3FCS.
- (U) Surface Surveillance is accomplished by the surface search radar AN/SPS-55, with a backup capability furnished by the collision avoidance and navigation system.

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- (U) Underwater surveillance is provided by the TACTASS AN/SQR-19 and AN/AQS-13D sonars. DIFAR An/SSQ-53 and DICASS AN/SQ-62 sonobuoys are dispensed by helicopter (SH-3H). Sonobuoy data link is via UHF telemetry receiving sets AN/SKR-3A.
- (U) 2.3.7.2 Armament -- Armament includes surface-to-air missiles, surface-to--surface missiles, missile launching systems and air drop and over-the-side launched torpedoes. Small arms and pyrotechnic devices, hi-rate gun munitions handling, and stowage facilities are also provided. Armament missile systems are controlled by the fire control system elements of Command and Surveillance. Torpedoes are controlled by underwater fire control elements.
- (U) Armament provides the ship with weapons and a means for delivery of those weapons to counter air, surface, and subsurface threats with provisions for the following:
  - Eight environmentally sealed and protected Harpoon missiles carried in four lightweight launchers, each holding two cannister launched missiles.
  - Eight environmentally sealed and protected SM-1 missiles carried in four lightweight vertical launchers, each holding two cannister launched missiles.
  - o Two MK-32 triple torpedo tubes for the over-the-side launch of MK-46 torpedoes.
  - o Miscellaneous ordnance and small arms.

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- o Space and weight reservations for two MK-<sup>9</sup>5 MOD V torpedo tubes for ship launch of two MK-48 torpedoes.
- Space and weight reservations for two MK-15 MOD 0 Close-In Weapon Systems (CIWS)
- (U) 2.3.7.3 List of Combat System Equipment -- The list of combat system equipment (non-variable load items) is contained in Appendix C. The list itemizes equipment physical characteristics, weight, and ship services requirements.
- (U) 2.3.7.4 Combat System and Military Payload Weights -- Table 2.3.7-1 presents the weights of major components within the combat system and includes variable load elements. Table 2.3.7-2 shows military payload weights (C<sup>3</sup> + Combat System) In accordance with ANVCE WP-002 definitions.

		WEIGHT			
SWBS	TITLE	LT	kN	% OF TOTAL	
450 <b>&amp;</b> 460	Surveillance Sys.	20.4	203.26	23.9	
470	ECM	1.3	12.95	1.5	
480	Fire Control	1-2.2	121.56	14.3	
711	Guns	11.4	113.59	13.3	
721	Launch Devices	10.6	105.62	12.4	
751	Torpedo Tubes	27.5	274.01	32.2	
761	Small Arms	0.4	3.99	.5	
782	Aircraft Weapon Handling	0.5	4.98	.6	
783	Aircraft Weapons. Stowage	1,1	10,96	1.3	
COMBAT SYS	TEM TOTAL	85.4	850.92	100.0	

Table 2.3.7-1 (U) COMBAT SYSTEM WEIGHTS (U)

SWBS	TITLE:	LT	kN _	% TOTAL
400	C&S Less	49.5	493.82	2:
	Nav & Internal			
	Communications			5 
700	Armament	52.3	520.92	29.1
F21-27	Ordnance	47.7	475.08	26.5
F42	Helicopter JP-5	30.5	303.70,	16.9
MILITARY P	AYLOAD TOTAL	180.00	1793.52	100.00

Table 2.3.7-2 (U) MILITARY PAYLOAD WEIGHTS (U)

(U) 2.3.7.5 Combat System General Arrangements -- The arrangements of the near term SES Combat Systems are shown in drawings contained in Appendix B, Section B.1 and B.7. The coverage of the weapons and sensors are shown on the figures contained in Appendix B, Section B.2. The armament system functional block diagram is contained in Appendix B, Section B.7.

(U) 2.3.7.6 Combat System Risk Assessment -- The specified combat weapons and sensors suite is entirely Government-defined and has the minimal risk associated wit; well-funded development and selections from offthe-shelf equipment items.

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#### (U) 2.4 SURVIVABILITY AND VULNERABILITY

- (U) 2.4.1 SIGNATURE CHARACTERISTICS
- (U) 2.4.1.1 Radar Cross Section (.3-18GH<sub>Z</sub>) Radar cross section not provided. Data not available.
- (U) 2.4.1.2 Microwave Signature Microwave signature not provided. Data not available
- (U) 2.4.1.3 Infrared Signature -- Infrared signature not provided. Data not available.
- (U) 2.4.1.4 Visibility -- Visibility not provided. Data not available.
- (C) 2.4.1.5 Acoustic Signature -- The airborne radiated noise signature comes primarily from the engine combustion air inlets, propulsion exhausts and lift fan air inlets. The total signature at a distance of one (1) metre would be approximately 100 dB re 20µPa in the 250 Hz band. Including spreading and absorption, a 45 dB sound pressure level in the 250 Hz band will be reached at approximately 500 metres.
- (U) Target strength, dB at a one (1) yard (0.9144 m) reference distance (dB re 1 yd.), is shown in Table 2.4.1-1 and the underwater radiated noise signature (dB re 1μPa) is shown in Table 2.4.1-2.
- (C) The near term point design SES probably has a distinctive line spectra at approximately 500 Hz. This relates to the blade passage frequency of the lift fans. The acoustic signature will probably show directionality abeam and abaft the waterjets.
- (C)Airborne radiated noise signature may be reduced by treating the combustion inlet, propulsion exhaust, and fan inlets with additional splitters.Underwater radiated noise signature may be reduced by suitably treating

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TABLE 2.4.1-1 (C): Estimated Target Strength (dB) (U)

SHIP ASPECT CONDITION	BEAM	STERN/BOW
On Cushion	15	2
Off Cushion	20	10

- (C) the engine and fan mountings. This will reduce distinct spectral lines, but will virtually do nothing to reduce the overall level in any given 1/3 octave band, since most of the energy in any band results from the impingement of the waterjet stream on the ocean's surface.
- (U) 2.4.2 . HARDNESS -- Hardness features are not furnished. The near term SES is not designed to warship hardness standards nor does it feature armor protection.

TABLE	2.4.1-2	(C):	Estimated	Underwater	Radiated	Noise	Signature
			(dB re 1µ)	Pa) (U)			

	SHIP SPEED				
INTENSITY '	10 knots (5.14 m/s)	50 knots (25.72 m/s)	80 knots (41.14 m/s)	120 knots (61.74 m/s)	
tntensity of Highest Line <b>(0-100</b> Hz)	180	174	168	160	
Intensity of Highest Line (≥ 100 Hz)	170	164	158	1.50	
Intensity of <b>1/3</b> Octave Band <b>2kHz</b>	180	175	170	160	

#### 3 / LOGISTIC CONSIDERATIONS

- (U) The principal logistic elements contributing to the near term SES design baseline are maintenance planning, supply support, ship manning, training, technical publications, and support system requirements, Interdependently and interacting with other requirements, these elements affect ship sizing, light ship weight, variable load weight, and inherent design capabilities for performing selected missions. The overall approach to logistics will support the near term SES design, construction and fleet use.
- (U) The support system provides the logistic support resources required to maintain the ship in an operational readiness condition capable of meeting the availability requirement of the missions. The logistic support resources include personnel and training, initial and back up **inventory** of spares and repair parts, industrial support facilities (intermediate and depot support levels) and common/peculiar support equipment (**intermediate** and **depot** repair shops). These logistics elements are displayed **in** the support system block diagram, Figure 3-1. The support 'system is compatible to the maximum degree possible with U. S. Navy and other existing logistics support activities.



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Figure 3-1 (U): Support System Block Diagram (U)

(U) 3.1 RELIABILITY AND AVAILABILITY

Since Rohr Marine, Incorporated, is not conducting the Supportability/ Availability analyses (ANVCE WP-008)<sup>(1)</sup>, availability block diagrams are not a part of this report; however, subsystem availability predictions applicable to the near term SES are a part of this report. In addition, MTBF and MTTR data for major components of SES Subsystems are listed in Paragraph 3.1.3 along with a utilization factor.

- (U) 3.1.1 SES UTILIZATION (Not Provided)
- (U) 3.1.2 SES SYSTEM AND SUBSYSTEM -- The predicted availability for the near term SES is shown in Table 3.1-1. The predictions are based on a ten-day mission. Availability is defined as the ratio of mission uptime to total at sea time scheduled for the mission. The predicted availability for the near term SES is high due to:
  - High reliability and maintainability of the stay-stiffened planing bow and stern seals (e.g., all seal components can be replaced without dry docking)
  - Redundancy in the Lift and Propulsion Systems
  - High availability of the Electrical, Auxiliary, and Command and Surveillance Systems
  - A Design approach that emphasizes RMA

- (U) The availability predictions listed in Table 3.1-1 are relative to a mature design. Furthermore, these predictions are for a ship maintained in accordance with the Maintenance Concept outlined in Paragraph 3.2. The combat functions have not been considered in computing these pre<sup>2</sup> dicted availabilities.
  - (1) This is the understanding derived from the 20 September 1976 meeting at PMS-304. Rohr Marine, Inc., was to receive a "questionnaire/list of required data" from NAVSEC. In the interim, the information submitted in this report presents data used in the Rohr Marine, Inc. RMA analysis.

SUBSYSTEM	AVAILABILITY PREDICTION
Hull Structures	0.9990
Propulsion Plant'	0.9627
Electric Plant	0.9990
<b>Command and Surveillance</b>	0.9828
Auxiliaries Systems	0.9874
<u>Lift Sys</u> tem	<u>0.9768</u>
Overall Ship	0.91

Table 3.1-1 (U). SES Availability Prediction for the Near Term SES (U)

- (U) 3.1.3 RELIABILITY AND MAINTAINABILITY DATA -- The R/M data provided in this subsection are for only mission essential equipments. Not listed are equipment in the combat or C3 systems with the exception of those functions required for maneuvering and navigation. The equipment R&M data is listed by subsystem. The following definitions apply to the data lists:
  - EQUIPMENT Major equipment group of function
  - MTBF Mean Time Between Failures, hours
  - MTTR Mean Time to Repair or Restore (the times listed include a 50 percent allowance for conditions at sea)
  - UTIL Utilization Factor. That portion of time that the item is in use during the mission, hours.
  - NR Non-Repairable at sea.

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(U) 3.1.3.1 Propulsion Plant R/M Data

EQUIPMENT	MTBF	MTTR	UTIL
Combustion Air Supply Heating (NR)	11,500	5.0	0.5
Combustion Air Supply	244, 000	1.5	1.0
Combustion Air Supply (NR)	81, 300	5.0	1.0
Gas Turbine	6, 450	3. 0	1.0
Gas Turbine <b>(NR)</b>	10, 500	<b>24.</b> 0	1.0
GTRB Lube Oil Cooler	90, 000	4.5	1.0
GTRB Luve Oil Filter - Supply	60, 000	4.5	1.0
GTRB Lube Oil Filter 🛥 Scavenge	60, 000	4.5	1.0
Flex Coupling (NR)	72, 780	4.0	1.0
Tongue Meter	10,000	1.5	1.0
Shafting and Bearings (NR)	11, 600	6. 0	1.0
Thrust Reverser	6, 150	6. 0	0.1 <
Propulsor (NR)	6, 700	8.0	1.0
Waterjet - Steering	6,150	6. 0	1.0
Exhaust Duct	62, 000	4.5	1.0
Exhaust Duct (NR)	300, 000	15.0	1.0
GTRB Cooling Blower	18, 250	2. 25	1.0
Lube Oil Pump - Pressure	21, 800	3. 0	1.0
Att. Lube Oil Pump 🗕 Press.	34, 500	4. 5	1.0
Lube Oil Pump 🛥 Scavenge	21, 800	3. 0	1.0
Att. Lube Oil Pump 🛥 Scavenge	34, 500	4.5	1.0
Lube Oil Filter/Separator	30, 000	4.5	1.0
Lube Oil Control Manifold	46, 730	3. 0	1.0
Lube Oil Cooler	45, 000	4.5	1.0
Vacuum Pump	18, 250	2. 25	1.0
Inlet Sensors and Control	5, 000	1.5	1.0
Inlet Ramp Actuator	6, 100	3. 7	1.0
Inlet 🛥 Miscellaneous	91,000	3. 0	1.0
Inlet (NR)	45, 000	15.0	1.0
Propulsion System - Misc.	10,000	3. 0	1.0
Sensors for System Control	10,000	1.5	1.0

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(U) 3.1.3.2 Electric Plant R/M Data

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EQUIPMENT	MTBF	MTTR	UTIL
Engine Air Supply	70,000	1.5	1.0
Gas Turbine Generator 60 Hz	8,330	3.0	.1.0
Gas Turbine Generator 60 Hz (NR)	12,500	8.0	1.0
Gas Turbine Lube Gil Cooler	90,000	4.5	1.0
Exhaust Duct (NR)	26,000	5.8	1.0
60 Hz Switchboard	645,000	1.5	1.0
60 Hz Power Panel	173,580	1.5	1.0
60 Hz Transformer	1,000,000	1.5	1.0
400 Hz Switchboard	645,000	1.5	1.0
400 Hz Power Panel	173,580	1.5	1.0
400 Hz Transformer	1,000,000	1.5	1.0
Cooling Fan	18,250	2.25	1.0
Lighting Vital Spaces (each light)	1,000,000	1.5	1.0
Gas Turbine Generator 400 Hz	10,000	3.c	1.0
Gas Turbine Generator 400 Hz (NR)	15,000	8.0	1.0
28 VDC Rectifier	.36,000	1.5	1.0
28 VDC Distribution Box	28,930	1.5	1.0
28 VDC Power Panel	43,395	1.5	1.0

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Navigation and Collision Avoidance System R/M Data

EQUIPMENT	MTBF	MTTR	UTIL
Anti-Clutter <b>Collision</b> Avoidance Radar <b>AN/APS-116</b>	1,100	4.5	1.0
Anti-Clutter Collision Avoidance Radar AN/APS-116 (NR)	10,000	3.0	1.0
Surface Search Radar SPS-55	1,300	2.7	1.0
Surface Search Radar SPS-55 (NR)	12,000	1.8	1.0
Collision Avoidance Computer AN/UYK-20	2,000	0.4	1.0
Navigation Computer AN/UYK-20	2,000	0.4	1.0
Navigation Data Switchboard	2,000	1.5	1.0
SAT-NAV	500	0.75	1.0
OMEGA	1,500	1.5	1.0
Inertial Nav	5,600	1.0	1.0
Gyro (Types I and II)	5,600	1.0	1.0
Depth Sounder AN/UQN-4	5,700	0.75	0.5
Doppler Speed Sensor	1,000	1.5	1.0
Interior Communications	20,000	1.5	1.0
HF Transceiver	. 1,100	0.5	1.0
UHF Transceiver	2,100	0.5	1.0
VHF Transceiver	2,500	9.5	0.1
VHF Antenna (NR)	25,000	2.0	1.0
Transfer Switchboard	16,000	0.7	1.0

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(U) 3.1.3.4 C<sup>3</sup> Ship Controls R/M Data

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EQUIPMENT_	MTBF	MTTR	UTIL
Wheei	5,000	1.5	1.0
Autopilot	1,666	1.0	1.0
Propulsion Power Lever Actuator	5,000	1.0	1.0
Lift Throttle	5,000	1.0	1.0
Lift Control (Ship's Control Console and Propulsion Control Console)	5,000	1.0	1.0
Autopilot Control Display Unit	5,000	1.0	1.0
Navigation 🛥 Collision Avoidance Display	4,000	1.0	1.0
Central Processing Unit	2,000	1.0	1.0
Fire Protection Controls	1,000	1.0	1.0
Electric System Control	1,000	1.0	1.0
Fuel Management Control	1,000	1.0	1.0
Auxiliaries Control	1,000	1.0	1.0
Pbwer Supply	90,000	1.5	1.0
PPI Display	4,000	3.0	1.0
PPI Display (NR)	4,000	3.0	1.0
Commanding Officer Communications Console	50,000	1.0	1.0
Ship's Control Console - Monitoring'	10,000	1.0	1.0
Propulsion Control Console • Monitoring	10,000	1.0	1.0

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EQUIPMENT	MTBF	MTTR	UTIL
Air Conditioning Unit	12,650	4.0	0.5
Recirculating Fan	13,880	3.0	1.0
Mixing Box	38,080	3.0	1.0
Supply Fan	18,250	3.0	1.0
Exhaust Fan	18,250	3.0	1.0
Supply Fan - Machinery Space'	18,250	3.0	1.0
Exhaust Fan 🖛 Machinery Space	18,250	3.0	1.0
Fire Pump <b>(NR)</b>	10,500	8.0	1.0
Distiller	2,000	4.0	1.0
Distiller (NR)	6,000	9.8	1.0
Pump - Potable <b>Water</b>	15,150	3.0	0.5
Pump 🖛 F.W. Transfer	15,150	6.0	1.0
Pump - Coolant, Electronic	15,150	4.5	1.0
Demineralizer	32,860	4.4	1.0
Heat Exchanger	90,000	4.5	1.0
Valve, Temp. Control	11,700	3.0	1.0
Pump, Fuel Transfer	3,760	4.5	0.3
Pump, Fuel Service	3,760	4.5	1.0
Pump, Fuel Trim	3,760	4.5	0.5
F.O. Filter	60,000	4.5	1.0
Manifold, Fuel	10,000	3.0	0.75
Heat Exchanger .	90,000	4.5	1.0
Mass Flow Multiplier	50,000	4.5	0.1
Valve, Motor Operated	20,000	3.0	0.05
Regulator, Air	46,730	3.0	0.05
Air, Receiver	16,700	4.5	1.0
Hydraulic Pump 🛥 Att.	15,000	3.0	1.0
Hydraulic Pump 🛥 Motor Drive	10,500	3.0	1.0
Filter, Hydraulic	60,000	4.5	1.0
Cooler, Hydraulic	90,000	4.5	1.0
Control, Hydraulic System	50,000	4.5	1.0

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(U) 3.1.3.5 Auxiliaries R/M Data (Continued)

EQUIPMENT	MTBF	MTTR	UTIL
Regulator, Hydraulic <b>Resevoir</b>	23, 365	3. 0	1.0
Anchor Windlass (NR)	3, 350	5.0	0. 05
Capstan Mooring (NR)	3, 350	5.0	0. 05
Fuel, Probe-Receiver	50, 000	3. 0	0.10
Pollution Control System	10, 000	3. 0	1.0
Hangar Door - Actuation	10,000	4. 5	0. 05
Hangar Door • Manual	10, 000	4. 5	0. 05
Sensors for System Control	10,000	4. 5	1.0
Auxiliaries - Misc.	5,000	3. 0	1.0
Fire Detection	2, 000	1.5	1.0

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(U) 3.1.3.6 Lift System R/M Data

EQUIPMENT	MTBF	MTTR	UTIL
Gas Turbine	6,450	3.0	1.0
Gas Turbine (NR)	10,500	24.0	1.0
GTRB Cooling Blower	18,250	2.25	1.0
GTRB Lube Oil Cooler	90,000	4.5	1.0
GTRB Lube Oil Filter 🕶 Supply	60,000	4.5	1.0
GTRB Lube Oil Filter 🖷 Scavenge	60,000	4.5	1.0
Torsionmeter	10,000	1.5	1.0
Exhaust Duct (NE)	26,000	5.8	1.0
Reduction Gear (NR)	188,000	8.0	1.0
Pump 🛥 Lube Oil Pressure	21,800	3.0	1.0
Pump - Lube Oil Pressure - Attached	34,500	4.5	1.0
Pump - Lube Oil Scavenge	21,800	3.0	1.0
Pump 🛥 Lube Oil Scavenge 🛎 Attached	34,500	4.5	1.0
Filter Separator - Lube <b>Oil</b>	30,000	4.5	1.0
Control <b>Manifold -</b> Lube Oil	46,730	3.0	1.0
Lube Oil Cooler	90,000	4.5	1.0
Vacuum. Pump	18,250	2.25	1.0
Shafting & Bearings (NR)	41,000	6.0	1.0
Demister	23,200	1.5	1.0
Lift Fan	28,190	3.0	1.0
Lift Fan <b>(NR)</b>	8,000	18.0	1.0
Shut Off Control Valve	5,900	4.5	1.0
Control - Ride Control Valves	10,000	3.0	0.1 Z
Ride Control Valve	5,900	4.5	0.1 ∠
Bow Seal (NR)	6,965.	4.3	1.0
Stern Seal (NR)	6,965	4.7	1.0
Bow Seal Retract	9,120	4.5	0.054
Control - Bow Seal Ret.	5,000	1.5	0.05 4
Stern Seal Retract	9,120	4.5	0.05 4
Control 🛥 Stern Seal Ret.	5,000	1.5	0.05 AI
Misc. Valves 6 Piping	10,000	1.5	1.0
Sensors for System Control	10,000	1.5	1.0
Transfer Valves	5,900	4.5	1.0

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#### (U) 3.2 MAINTENANCE CONCEPTS

In consonance with the 3KSES TLR, the maintenance concept for meeting the objectives and availability goal is to: (1) perform the preventive/corrective maintenance on critical equipment onboard; (2) accomplish the emergency repair of non-critical equipments with **helo** provided (VERTREP) augmentation from the intermediate level support resources; and (3) defer/schedule all non-essenti: equipments/components maintenance for in-port availabilities. For design purposes, particular emphasis was to be given to: (1) maximization of the use Of existing and projected Navy equipments to permit use of standard maintenance procedures and supply support, (2) use of performance/condition monitoring for detecting incipient failures for critical equipments, and (3) provisions for equipment accessibility to support a component/module replacement strategy. The replacement strategy includes scheduled replacement, replacement on condition, and replacement at failure depending on the subsystem/equipment criticality. Therefore, the maintenance concept in support of near term SES availability and mission is based on a number of objectives and constraints.

(U) The maintenance objectives of the near term SES are:

- Support the SES in the achievement of assigned test and demonstration missions while assuring safety of ship and personnel, and meeting availability requirements,
- Use the inherent maintenance capability of operator personnel.
- o Minimize shipboard maintenance manning.
- Minimize "at sea" repair to the vital and critical equipments and components.
- o Minimize ship carried weight of logistic resources,
- Use the most cost-effective distribution of effort between shipboard and off-ship maintenance.
- Use helicopte · service (V'ERTREP) to provide logistics resources not carried on board, i.e., personnel skills, special tools and test equipment, spares, etc.

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- Use the replace and restore concept to the maximum, vice **piece**part repair.
- Provide adequate **accessibility** for servicing to minimize secondary removals/replacements.
- Maximize the use of existing and projected Navy equipments to permit use of standard maintenance procedures and supply support. Navy rotatable pool stocks will be used as applicable.
- Achieve incremental subsystem overhaul by maintenance actions and scheduled replacement of subsystems accessories and related auxiliaries consistent with the major item replacement cycle.
- (U) The maintenance constraints placed on the near term SES are:
  - Accomplish both preventive and corrective maintenance actions, to the maximum extent possible, while in port.
  - In view of the perennial need to minimize shin weight, a single item weight limitation of 160 Lbs (711.72 N), will relegate a few "potentially repairable at sea" maintenance tasks, on critical equipments, to a non-repairable at sea category.
  - o At sea maintenance shall be limited to that required, consistent with ship speeds and sea states.

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- (U) 3.2.1 INTERMEDIATE LEVEL SUPPORT -- Intermediate Maintenance Activities (IMA's) will accomplish PM not within the capacity of the ship's crew. The IMA will provide condition monitoring services not otherwise within the capabilities of the monitoring equipment aboard ship, during upkeep or Maintenance Availabilities'of the ship. Intermediate-level maintenance for the near term SES will include support from shore based and afloat Intermediate Maintenance Activities.
- (U) 3.2.1.1 Shore Based Intermediate Facilities -- The shore based intermediate level support will provide the following types of facilities to meet the operating, maintenance, training and supply support requirement of the near term SES:
  - Operating pier -- will provide for safe and efficient 0 mooring of the ship for servicing, maintenance and/or testing. The mooring provisions will be designed to be specifically compatible with the ship. An unobstructed access and a sufficient depth of water are required. Bits and chocks will provide the capability of withstanding wind loading up to 100 knots (51.44 m/s). Compatible dockside fittings for fueling/defueling, fresh water, compressed air, 60 and 400 Hz electrical power and telephone connections to the SES will be provided. Crane services for loading/unloading equipments/components and materials, gangways and/or ramps for personnel access/ egress will be provided. Emptying the collecting/holding tanks (CRT) of sewage and other liquid wastes will be accomplished by appropriate sludge barges and receiving vehicles. Solid trash (compaction) disposal will be provided.
  - Intermediate level maintenance ships/capability such as:
    - (1) Ship fitters/welding/pipefitters
    - (2) Mechanical pumps/auxiliary machinery
    - (3) Electrical generators/switchboards

- (4) Electronics/test instrumentation
- (5) Underwater inspection/repair support shop including photographic service

- (6) Operational computer program maintenance
- Training classroom8

- o Supply warehousing and storerooms
- o The administrative space, personnel, furnishing and equipments necessary to coordinate the logistics resource support, including the planning and scheduling of the resupply services to support the SES while at sea. Support shall be provided for logistics resources not carried on board (i.e., personnel skills, special tools and test equipment, spares, etc.).

(U) 3.2.1.2 Afloat Intermediate Facilities -- The afloat intermediate level activity will provide the following types of maintenance shop/ capability support:

- o Ship fitters/welding/pipefitters
- Mechanical pumps/auxiliary machinery
- Electrical generators/switchboards
- Electronics/test instrumentation .
- Underwater inspection/repair support shop, including photographic service.
- (U) 3.2.2 DEPOT LEVEL SUPPORT -- Depot-level support maintenance of the near term SES will include the following:
  - Preserving the underwater body, and maintaining sea-connected tanks, valves, pipes, and fittings.

- o Performing repairs requiring heavy lift capability and special tools and test equipment (examples: bow/stern seals, radar antennas, gas turbines, waterjet propulsor, electrical generators).
- Removing, installing, and testing certain equipments identified as stock rotating spare items (example: main propulsion and lift gas turbines),
- Stocking and repairing designated stock rotating spares items at selected depot maintenance activities.
- (U) The depot level support will provide a dry dock and the necessary work shops for systems/equipments for overhaul and/or repair beyond the capability of the intermediate maintenance activity. The depot level support will provide general workshop and drydock facilities and services.
- (U) 3.2.2.1 General Workshops -- Depot level maintenance shops/capability will provide maintenance for the waterjet propulsor, lift fans, seals, structural/welding, computers, consoles and related electronics, and gas turbine generators. A Naval Rework Facility is required for gas turbine maintenance. Overhaul points for communications, sensors, computers, displays, and related electronics must be designated. A facility, either Government or Contractor, is required for the maintenance of operational computer programs.
- (U) 3.2.2.2 Drydock -- A safe and efficient facility capable of drydocking the ship. Cranes, temporary pdwer, compressed air, fresh water, salt water, firemain, sewage collection and disposal shall be available at the dock site.

#### (U) 3.3 OVERHAUL CONCEPT

**Regular** overhauls, as now understood, are to be eliminated by intensive use of the upkeep periods as maintenance availabilities. The near term SES will employ the concept of progressive overhaul. Equipment replacement and alteration will be accomplished progressively during relatively frequent maintenance availability periods of short duration. Dry-docking will be accomplished, primarily to provide for major emergency repairs and/or ship alterations. The ship system will be designed to be capable of **incre**mental overhaul of its subsystems and subsystem accessories and related auxiliaries. Operational usage and schedule replacement will be **consis**tent with the major item replacement schedule.

- (U) 3.3.1 SCHEDULING (Not provided)
- (U) 3.3.2 PIPELINE REQUIREMENTS (Not provided)
- (U) 3.3.3 SHIPYARD OVERHAUL FACILITIES (Not used; see Section 3.2.2)
- (U) 3.3.4 LAND-BASED TEST FACILITIES (Not provided)
- (U) 3.3.5 MAINTENANCE **PROGRAM** INTERFACE (Not provided)

#### (U) 3.4 SUPPLY SUPPORT CONCEPT

The sizing of near term SES storerooms, commissary system and other supply spaces are constrained by design requirements and indirectly by the maintenance concept and the personnel requirements. Within the permissible volumetric and weight limits, the near term **SES** design provides the necessary supply support capability. The design supports the requirements for **10** and **15-day** missions in accordance with **LSES TLR mission profiles.** A salient design consideration is the frequency of underway replenishment, including helicopter (**VERTREP**) delivery of required **logistics** resources, and the requirement for underway refueling.

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- (U) The supply support concept provides material support for the assigned miss ions. The support includes initial outfitting of provisions, medical supplies and spares and repair parts as well as replenishment,
- (U) The supply concept provides for the fitting out of the SES. It provides for the material to be assembled in a shore warehouse prior to loading on board. The 1 ading of spares and repair parts and equipage will be kept to a minimum consistent with space and weight constraints, necessary to support availability and mission requirements. Tailored loads of support for specific missions will be utilized,
- (U) Replenishment for all repaitables, consumables, and spares will be provided through underway Replenishment Groups at sea and through normal resupply methods in port. Supply requirements, for at sea emergencies, will be accomplished by the utilization of helicopter deliveries. Maximum utilization of in-port delivery for all repairables, consumables, and spares, will be a program objective.

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(U)	3.4.1	MODIFIC	ATIONS provided	TO MOBILE !)	LOGISTIC	SUPPORT	FORCE SHIPS	
(U)	3.4.2	UNIQUE 3.2.2)	SHORE	FACILITIES	(Not used	l; see	Sections 3.2.1	and
(U)	3.4.3	UNIQUE	REPLE	NISHMENT	TECHNIQUES	(Not	provided).	
(U)	3.4.4	UNIQUE	SUPPLY	SUPPORT	PROCEDURES	(Not	provided)	

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#### (U) 3.5 HUMAN ENGINEERING

The human engineering effort on the near term SES encompassed three basic areas: (1) design of major work stations; (2) design of maintenance access; and (3) evaluation of the design in terms meeting habitability criteria requirements.

- (U) 3.5.1 DESIGN OF WORK STATIONS The pilot house, chart room, Central Operating Station (COS) and CIC were analyzed with regard to man-machine interfaces and functional adjacencies between operating personnel. The pilot house and COS are equipped with integrated display-control consoles to allow minimum manning at these stations. These work stations have also been designed for seated operations to ensure a high level of operability during operation in all sea states and at all ship speeds.
- (U) 3.5.2 MAINTENANCE ACCESS -- All ship spaces and equipments within these spaces were **analyzed** to determine if sufficient space had been allocated for both corrective and preventative maintenance. The analysis revealed that all subsystems and equipments can be installed, **serviced** and removed with a minimum of effort. Particular attention was given to the **waterjet** propulsors, propulsion gas turbines, lift gas turbines and the lift fans with regard to maintenance removal requirements.
- (U) 3.5.3 HABITABILITY -- The point design was compared with the habitability criteria stated in OPNAVINST 9330.78. The space allocations for crew living areas meet or exceed those requirements for berthing, sanitation spaces, recreation spaces, galley and messing. The crew living areas occupy a single deck to minimize the need for crew members to move about the ship whether on- or off-duty. Therefore, these design features are provided: (1) all off-duty crew spaces are on the same level to minimize the use of ladders; (2) within the constraints of crew/CPO officer off-duty separation, the best possible adjacency between mess rooms, recreation rooms, and berthing

- (U) spaces, has been provided; (3) sanitary spaces are located within the living spaces,
- (U) Noise/thermal separation between living and machinery spaces ensures a more comfortable off-duty crew environment. Off-duty spaces are separated from machinery spaces/engine rooms by passageways, storerooms or other effective noise and thermal barriers. This lessens ship weight allocation for insulation material while improving habitability.
- (U) The ride quality to be expected by the crew at higher sea states, in combination with higher ship speeds, was examined. Large amplitude vertical accelerations can exceed human tolerance levels to a point where human performance can be affected. To ensure that human performance is not degraded, Human Factors developed ride criteria limits that were used to verify the adequacy of the ride control system in limiting vertical accelerations within the operational sea state and speed envelope.

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#### (U) 3.6 SYSTEM SAFETY

The primary intent of safety program requirements is the elimination or control of hazards inherent in the design and in the operation of the SES in its environment. Particular attention was given to safe ship survival in any singular hardware malfunction of the lift, propulsion, steering, reversing, or **sidehull** damage from foreign objects, regardless of sea state, speed, displacement, or maneuver at the time of the casualty, Safe survival of personnel functional capabilities and preclusion from injury during and operatfonal or maintenance phase is eugally important.

- (U) 3.6.1 PRELIMINARY HAZARDS ANALYSIS -- The entire ship design was reviewed for gross hazard failure modes. Design characteristics singular to the SES were given emphasis. A major effort was placed on hull arrangement and structure, lift system, seals, waterjet pump, fire protection integration, operation and maintenance hazards, selected control aspects, and outfit and furnishings.
- (U) In most instances, operational ambient failure conditions were defined to aid the designer in eliminating a hazard, rather than relying on preventative manned reaction and cautionary training. Where ship critical or catastrophic conditions were predictable, equipment failure modes and personnel hazards were examined as possible sequences or parallel events. Closely examined were seals, the lift system machinery, fire detection, and extinguishment integration, selection of passive fire protection materials, and personnel protective gear for use while underway,
- (U) 3.6.2 SAFETY TRADE-OFF STUDIES -- System Safety Personnel investigated or supported all safety critical trade-off studies. Selected subjects of design safety trade-offs, applicable to the 1980 (near term) point design, follow.
- (U) 3.6.3 FIRE PROTECTION -- System Safety actively participated in the design of the fire protection system. Safety required that a

- (U) bulkhead be capable of sustaining a fuel fire for 30 minutes on the insulated side, with the non-insulated side not to exceed 400°F (204°C). This is achieved by a passive fire protection design with a stainless steel face shield backed-up by varying thicknesses of fiberfrax.
- (U) Auto/remote/local Halon 1301 fixed flooding with interconnect capability, and HI-X foam generators for back-up are used in fire suppression. Critical electronic spaces are similarly protected except without Hi-X foam. All other ship spaces are protected with standard Navy fire extinguishing systems. For example, the Helicopter hangar and flight deck are protected by AFFF foam sprinkling and hose reels and the torpedo room and missile stations with seawater sprinkling,
- (U) 3.6.4 LIFT SYSTEM AND SEALS --- The ride control and lift system design and development has been under continuous surveillance for its safety impact. Maintenance access and interlocking alarms into the fan compartments have been provided, The near term SES incorporates guide vanes on 0.5 Ft. (0.15m) centers at the fan inlet that preclude a personnel falling hazard,

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- (U) 3.6.5 RIDE CONTROL -- Safety features for maintaining control of body motions underway include: safety/shoulder harness restraining devices for seated positions, arm restraints for console operators, padded barriers and railings for walking and standing functions, non-skid deck surfaces, and head protective gear. Non-critical maintenance activities are minimal while underway in high sea states to minimize personnel injury from random vertical accelerations.
- (U) 3.6.6 HELICOPTER CONTROL STATION -- The helicopter control station was located at the port side of the Helicopter Hangar at the 01 level. This provides greater visibility and safety in the event of a helicopter crash or platform fire. In the event of a hangar fire, emergency egress to the 01 level is readily available.

- (v) 3.6.7 DECK EDGE CURVATURE -- The deck edge curvature provided for aerodynamic purposes has a two foot (0.61m) radius. This maximizes deck hand safety compared to larger radii, particularly during installation or removal of portable life lines and stanchions from the deck edge perimeter and the replenishment of stores and ordnance while underway.
- (U) 3.6.8 ANTENNA LOCATION -- The AN/APA-171 antenna is located on the main mast, approximately 30 feet (9.14m) above the weather deck, This lowers the personnel RADHAZ level on the helicopter platform and avoids radiating energy into the Pilot House, compared to possible alternate locations farther aft and closer to the 01 deck.

4 / TECHNICAL RISK ASSESSMENT

- (U) One of the design objectives has been to incorporate standard practices and parts to the maximum degree. Equipments developed and available from existing Government inventory have been preferred over new equipments to be developed. Qualification by extension of existing designs has been used to the extent practicable in lieu of development of new items.
- (U) The ship configuration is a viable concept and can be developed with minor or acceptable levels of risk. Furthermore, the near term ANVCE SES has been configured to accept further design alternatives which may enhance ship performance, utility and reliability. The overall technical risk is assessed as follows:
- (U) Hull Structure -- The hull is designed to realistic worst case loading conditions forecast to occur within the ship lifetime. The materials are commercially produced aluminum alloys which have been utilized in existing Navy ships, such as the PHM and SES-100B. The baseline configuration is conventional with state-of-the-art details to minimize construction risk. The hull as presently configured is producible, cost effective, and adequate to perform the specified mission.

SECTION 4

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- (U) Propulsion System -- The proven LM 2500 and the developmental FT9A-2A alternate engines were chosen on the basis of proven capability and advanced developmental status, respectively. The transmission design features high state-of-the-art reliability and performance. The waterjet propulsor and inlet design has been optimized on the basis of extensive analysis and sub-scale tests. All other components are typical of PHM, SES-100A, and XR-ID practice; are presently available and proven in service.
- (U) Electrical System -- The baseline system design can be implemented with off-the-she&? equipment. The design is low risk, cost effective, and will provide satisfactory and reliable performance with high confidence.
- (U) Command, Control, and Communication  $(C^3)$  -- The  $C^3$  systems are comprised almost entirely of Government **Nomenclatured** Equipments with attendant low risk in their use, The only potential risk is **HF communi**cations during on and off cushion ship operations that would effect the antenna ground plane. The risk associated with other  $C^3$  equipment is low or well within the state-of-the-art and absorbed by substantial, funded ongoing programs.
- (U) Lift System -- The LM 2500 gas turbine is a production unit used in other marine applications. Lift fan development is based on extensive subscale testing. The other elements of the air distribution system are typical of present gas turbine ship installations and within the present stateof-the-art. The advanced bow and stern planing seals have proved highly successful in sub-scale tests. While there are no historical research or performance data on this particular SES application, fullscale loads analysis and materials selection indicates that all considerations are within the state-of-the-art.

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- (U) Outfit and Furnishings (O&F) -- Nearly every item in the O&F system is a .proven shipboard item not peculiar to the SES. The risk is equivalent to that of O&F on conventional Navy ships. Passive thermal/fire and acoustic protection systems are based on extensive testing and material evaluations, The risks associated with their application will be minimal.
- (U) Combat System -- The risk is that associated with ongoing Government development of the combat system equipments. The interface design risk is low.

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#### APPENDIXA

#### DESIGN PROCESS

- (U) The various near term ANVCE Point Designs will be arrived at from different technology bases. Different standards, criteria and assumptions are used because of the different program offices and other Navy organizations involved. For example, structural safety factors between different vehicles are not the same, weight margins are frequently different and different ambient conditions may be assumed in quoting engine performance.
- (U) The near term SES point design concept outlined in this report adheres, wherever practicable, for consistency to information provided in such ANVCE documents as:

#### ANVCE Primary Documentation

0	WP-010 - dated 27 August 1976 - "Environmental Conditions"
0	WP-008 - dated 20 August 1976 - "Supportability/Availability"
0	WP-007 🕶 dated 30 July 1976 🖛 "Point Design Guidance
0	WP-005A 🖛 dated 13 August 1976 🛥 "Point Design Description"
0	UP-002 - dated 2 April 1976 - "Definition of Terms'

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#### ANVCE Supplementary Documentation

- "Design Standards for Surface Point Designs, Revision A",
   ANVCE Memorandum 90-76, dated 10 August 1976
- (U) WP-005A was used as the basis for the data developed in this report and was assumed as having precedence over other stated documentation requirements in cases of conflict. As a further aid to making proper evaluation of the near term SES point design presented in this report, this Appendix provides a basis for the insight needed into the design approach, criteria, philosophy and trade studies used in arriving at the design. This Appendix collects in summary form those pieces of information needed to identify the source of data and the design process used.

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#### (U) A.1 APPROACH

For a basic vehicle configuration and the major subsystems, several methods of establishing characteristics exist. They may be classified into three groups:

- Scaling -- projection of characteristics based on ratioing up or down from a chosen vehicle
- Modification -- development of characteristics based
   on small changes to an existing vehicle
- Synthesis -- development of characteristics based on design data, parametric analysis and theoretical investigations
- (U) The approach primarily used for the Rohr version of the **ANVCE** near term SES Point Design is modification to the Rohr 3KSES proposed design. This proposed design is, in turn, based upon scaling of appropriate model and testcraft data, as well as upon synthesis *as* just defined. The specific approaches in each disciplinary area are next identified and presented in concise form.

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#### (U) A.2 DESIGN CRITERIA

-Those pertinent design criteria, standards and assumptions used in the Point Design are provided in the following areas: hull structure, propulsion, electrical plant, command and surveillance, auxiliary systems, lift system, outfit and furnishings, armament, loads, weight margins, and vehicle. Tabular forms and references are used as appropriate in the sections that follow for each **of** these areas.

- (U) A.2.1 HULL STRUCTURE -- Loads were developed that correspond to a number of operational definitions. The selected loading conditions are the result for a ship operating over a 20-year life anywhere within its operational envelope.
- (U) The following load cases are considered "operational" and the required safety factors used when applying these loads are 1.30 on the minimum yield strength and 1.80 on the ultimate strength:
  - Load Case 1 -- Cushionborne, Operational 

     This case is based on on-cushion operation anywhere within the operational envelope. There are no heading or speed restrictions.
  - Load Case 2 -- Hullborne, Low Sea State This case represents hullborne operation (entirely off-cushion) in sea states 5 and below. There are no heading or speed restrictions.
  - Load Case 3 -- Partial Cushion, High Sea State This case is for partial-cushion operation (not entirely off-cushion) in sea states 6 and above. There are no heading or speed restrictions.
- (U) The following load cases were considered as emergencies due to system(s) failures, Because the ship is in an emergency mode, operational maneuvers to alleviate loads and motions would be deemed appropriate, The

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- (U) safety factors used for the following two conditions are 1.0 based upon the minimum yield strength and 1.50 based upon the ultimate strength:
  - Load Case 4 -- Hullborne/Lift System Failure in High Sea States - This condition is for a lift system failure in sea states 6 and above. Headings within 45 degrees of head seas are not considered, but there is no restriction on speed.
  - o Load Case 5 -- Hullborne/Lift and Propulsion Failure in High Sea States → This condition is for lift and propulsion system failures in sea states 6 and above. Speed is considered to be zero, but there is no restriction upon heading.
- (U) A final load condition considered was for ship damage with subsequent flooding. The safety factor applied was 1.20 on the minimum ultimate strength. No safety factor is used for yield strength since the ship would already have suffered structural damage; therefore, local yielding was permissible.
  - Load Case 6 
     Damaged Ship 
     This condition is for the ship suffering maximum damage (two compartments flooded). Still water bending moments are considered along with hydrostatic loads due to flooding to the "V-Lines".
- (U) The 3KSES hull structure is designed to the predicted maximum once per lifetime loads that the ship will experience in a twenty-year life. These loads are not considered singly since those sea and weather conditions which produce the most severe loads, such as longitudinal bending, also produce other associated loads, such as shear, torsion and those due to hydrodynamic pressure forces. Figure A.2.1-1 presents the load nomenclature and definitions used in the description of the structural load cases which follow. Figure A.2.1-2 presents the maximum cushionborne bending moment and the shear, hydrodynamic pressures and vertical accelerations associated with

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- (U) Load Case 1. The loads resulting from the conditions of Load Cases 2, 3 and 4 are presented in Figures A.2.: -3, A.2.1-4, and A.2.1-5, respectively. The loads resulting from Load Case 5 were found to be significantly less than those of Load Case 4, and are not presented. The many possible damage conditions of Load Case 6 are too numerous and complex to discuss in this document, However, the hydrostatic heads associated with flooding to the V-Lines were the loads which determined the scantlings of many structural elements.
- (U) While the hull structure is adequate to withstand the aforementioned loads with the safety factors specified in the load cases, the hull structure was originally designed to somewhat higher loads but lower required factors of safety. These high loads were the result of off-cushion ship operation in high sea states (sea states 6 through 9). Model testing and analysis demonstrated the advantage of partial-cushion operation in those high sea states, and this mode has been adopted for operation in that portion of the operational envelope. With completely off-cushion operation in sea states 6 and above due to an emergency, such operational maneuvers as implied by the speed and heading restraints of Load Cases 4 and 5 are deemed appropriate. The near term SES hull structure adequately withstands the developed loads and adopted factors of safety.
- (U) Fatigue Considerations -- A well established fatigue life (FATLF) computer program, along with accelerated time and fatigue testing of full scale welded panels, was used for verification of the endurance capabilities of the ship structure. Fatigue life of those test panels was increased significantly through the use of special fabrication and welding techniques. Basic joint design, along with controlled and scheduled welding and an in-service failure prevention plan, should assure a safe operational lifetime.

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Figure A.2.1-1 (U): Loads Nomenclature and Reference System (U)

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## Figure **A.2.1-2** (U):

Shear Loads, Bending Moments, Hydrodynamic Pressures, and Vertical Accelerations Corresponding to Load Case 1 (U)

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Figure A.2.1-3 (U): Shear Loads, Bending Moments, Hydrodynamic Pressures, and Vertical Accelerations Corresponding to Load Case 2 (U)

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- (U) A.2.2 PROPULSION -- General design criteria for the near term SES propulsion system includes maximization of performance, reliability, maintainability and simplicity. The propulsion machinery spaces are designed to accommodate either G.E. IM2500 or P&W FT9A-2A gas turbine engines. Specific design criteria applied to the point design are:
  - All machinery accessible for maintenance off-cushion without dry-docking, No corrosive air/water interfaces.
  - Short, straight drive shafts with no alignment and vibration problems. Flexible couplings to absorb dynamic misalignments.
  - Overspeed gas turbine engine control for protection against propulsion inlet air ingestion without complete engine shutdown.
  - Non-redundant link mounted propulsion components. The link mounted propulsor has less deflection than a gun mount. This simplified alignment, steering, and reversing interface and reduces vibration problems.
  - Low loss combusion air inlet system designed for 2.9 inches (7.36 cm) H<sub>2</sub>0 loss for LM2500 and 4.9 Inches (0.12 m) H<sub>2</sub>0 loss from FT9A-2A installation. Sufficient interval flow area to install a three stage inertial coalescer-interid moisture separator operating at a face velocity of 17.5 ft/sec (5.33 m/sec). The total salt ingestion goal is0.00136 ppm with a projected water wash interval of 450 hours. Capability to withstand a 4 foot (1.22 m) wave of green water on the 01 level without demister flooding and resultant breakthrough. Sufficient volume forward of the engine bellmouths to reduce pre-swirl and counter swirl to less than 5 and 12 degrees, respectively, and to keep distortion below 10 percent,

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- Low loss propulsion exhausts the design criteria for sizing the exhausts is based on obtaining maximum net thrust to the ship with low weight, back pressure, fuel consumption and jet thrust within a maximum limit of 6 inches (0.15 m) H<sub>2</sub>O.
- Acoustically treated intake and exhaust to meet Navy Category E requirements on the flight deck.
- o Anti-icing system designed to provide protection to
  -20<sup>o</sup>F (-28.9%).
- 0 Engine cowling designed to limit potential personnal contact areas to  $125^{\circ}F$  (51.7°C).
- Minimum number of moving parts in the flexible ramp roof variable area waterjet inlet. Smooth roof contour at any opening position. Vented roof cavities and pressure balanced to reduce structural loads and weight. Symmetrically configured bifurcated duct for low velocity distortion,
- Propulsion inlet designed to provide cavitation free operation to ship speeds exceeding the maximum ANVCE specified speed.

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(U) A.2.3 ELECTRIC PLANT -- The near term SES Electric Plant design has been guided and controlled by a set of design criteria, standards, and a system design philosophy, collectively oriented toward the design of an uncomplicated and **flexible** system featuring minimum weight, cost, and fuel consumption. The current design highlights the following:

- Adequate generated power, measured by operating margins, off-line reserves, and power quality
- Weight and envelope minimization
- Environmental compatibility
- Minimal technical risk
- Interface compatibility with ship structure
- Adequate RMA and Safety considerations
- Use of proven components where practicable
- Use of standard Navy design precepts for the power distribution system
- (U) The system design philosophy emphasizes the criticality of a continuous source of electrical power, with judicious minimization of system weight, envelope size, and cost of components and installation. Every effort is made to strike a proper balance between innovative and traditional design. Modernization to include superior materials or components is encouraged, particularly where significant benefits accrue in reduced life-cycle costs, enhanced safety, or performance improvements. A number of standards were incorporated in the design methodology to ensure suitability for Navy use and compatability with the anticipated marine environment. Among these were:

MILITARY SPECIFICATIONS AND STANDARDS

- MIL-E-917 Electric Power Equipment, Basic Requirements (Naval Shipboard Use)
- MIL-STD-454 Standard General Requirements for Electronic Equipment

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MIL-STD-1399/ 103	Interface Standard for Shipboard Systems Section 103 Electric Power, Alternating Current
MIL-S-16036	Switchgear, Power, Naval Shipboard
NIL-C-17361	Circuit Breakers, Air, Electric, Insulated Enclosure (Shipboard Use)
MIL-C-17587	Circuit Breakers, Air, Electric, Open Frame Removable <b>Assembly</b> (Shipboard Use)
MIL-C-17588	Circuit Breakers (Automatic - ALB) and Switch, Toggle (Circuit Breaker, Non-Automatic - NLB), Air, Insulated Enclosure, 125 Volts and Below, AC or DC, Naval Shipboard
MIL-G-3124	Generator, Alternating Current, 60-Cycle (Naval Shipboard Use)
MIL-G-21480	Generator System, 400 Hz AC, Aircraft
MIL-G-22077	Generator Sets, Gas Turbine, Direct-and Alternating-Current, Naval Shipboard Use
0902-001-5000	General Specifications for Ships of the U. S. Navy (GSS); Naval Sea Systems Command <b>(NAVSEA)</b>
DDS-300-2	Design Data Sheet, AC Fault Current Calculations
DDS-311-3	Design Data Sheet, Ship Service Electric Power System, Application and Coordination of Protective Devices
DDS-304-2	Electrical Cables, Rating and Characteristics

DDS-311-Z Design Data Sheet, Voltage Regulation for AC Ship Service Electric Power Systems

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- (U) A.2.4 COMMAND AND SURVEILLANCE -- The Combat System, including command and surveillance, armament and navigation and collision avoidance, was dictated by the 28 May 1976, LSES Top Level Requirements Document. Equipment lists were provided by the U. S. Navy.
- (U) The Ship Control System design was based on utilization of existing, approved equipments, such as FFG control system components and the AN/UYK-20 computer, to provide integrated control of ship operations, damage control, and auxiliaries and ship plant monitoring by a minimum of crew members.

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#### (U) A.2.5 AUXILIARY SYSTEMS

- (U) A.2.5.1 AIR CONDITIONING -- Requirements for the near term SES air conditioning system are:
  - o The decentralization of the air conditioning system by dividing the load in small serviced areas, and by using the fan rooms to accommodate the cooling/heating/fan integral units.
  - o Replacement of the chilled water system by straight air and hot-cold mixing boxes, and selection of lightweight foam type reinforced materials for ducting.
  - o Existence of state-of-the-art components already qualified by commercial and/or military requirements and in actual operation.

The results foreseen are:

- Pseudo redundancy, since failure of one unit will bring only fractional failure to the subsystem.
- o Weight savings inherent to aircraft components.
- o Energy savings by proper management and more efficient equipment.
- o Reliable system by the use of qualified components.
- (U) A.2.5.2 LUBE SYSTEM -- A number of subsystems on board require lubrication. The prime thermal drivers for propulsion and lift and the electric power generating units will be self-contained; others like propulsion gearing, power transmission, waterjet pump and lift gearing, fans and power transmission will require dedicated lube subsystems.

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- (U) The concept of a single centralized lube system versus multiple, dedicated systems was analyzed on the basis of: weight, cross contamination, cooling requirements, length of lines and bulkhead penetrations involved, reliability, and redundancy. Decision was made to employ the multiple, dedicated systems conceptual approach.
- (U) The standard way of using cooling seawater should be accepted only if it does not demand extra loading on the seawater subsystem, as for propulsion gear-pump units where water is available from the waterjet pump (second-stage cavity). The lift system should employ air as cooling media, and the location of the heat exchanger (oil to air) should be established (inlet or outlet of fans).
- (U) Pre- and post-operation lube oil circulation should be provided, as well as standby lubrication to assist main lube pump in low speed operation. The aeration of lube oil should be considered and the quality of lube oil should be closely controlled. High holding capacity for particulate contaimination and dewatering (vacuum plus coalescers) filters is inherent in the use of advanced practices and state-of-the-art components. A closed lube system should be compared with alternate schemes.
- (U) Short coupled lines should be used as exemplified by advanced systems used in other industries (petrochemical), and the clustering of fittings and components should be replaced by functional manifolds. The material for transmission lines should be compatible with that for gears and bearings, and should reflect low weight, fatigue strength compatibility and ease of handling. The lines should be supported by resilient mounts.
- (U) The results foreseen from this approach are enhanced system functioning, weight savings, energy savings (by using cooling media already available), and improved reliability by use of qualified components, practices in other industries, and application of naval operation experience.

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- (U) A.2.5.3 SEAWATER SYSTEM -- An integrated seawater system serves firemain, seawater service and sprinkling functions with an appreciable weight reduction. Additional weight savings were effected by installation of an open horizontal loop, i.e., elimination of the wet weight cross connection.
- (U) Installation of GRP piping for seawater, auxiliary system and wet firemain removes corrosion problems and effects weight savings of approximately one-third, compared to that for an equivalent copper-nickel system. Components to be used are readily available and qualified for marine use.
- (U) A.2.5.4 POTABLE AND FRESH WATER SYSTEMS -- Generation of potable and fresh water from seawater requires selection of the desalination process, i.e., reverse osmosis versus one of the several types of distilling processes. The inability of presently available reverse osmosis units to meet the salinity requirements of the general ship specifications prohibited ics use.
- (U) The trade-off of potable and fresh water systems involved investigation of components and configurations possessing potential weight savings. This led to the selection of vacuum-assisted water closets and low water demand showers. The resulting weight reduction is due to the reduced quantity of water collected and stored via'the drainage system and the reduced pumping capacity requirement. Further weight reduction was obtained with GRP piping,
- (U) A three-distiller configuration to reduce the stored potable water tonnage was investigated. Each unit was capable of supplying the ship's daily demand, and the tank tonnage was reduced by one-third of the required 40 GPM (25.24 mm<sup>3</sup>/s) per accommodation. The fresh water storage tonnage was reduced by restricting the utilization of fresh water (demineralized) to gas turbine engine washing and to make-up water for the auxiliary fresh water electronic cooling system.

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- (U) The selection of electrical power (in lieu of gas or steam) was made upon its ready availability. The 400 Hz supply was selected for all pump motors, on the basis of weight savings over 60 Hz types,
- (U) A.2.5.5 DISTILLING PLANT -- The selection of the type and capacity of distilling plant(s) requires the consideration of ease of maintenance and operation, quantity and form of energy available, and the fresh water requirements. The three basic types of distillers for naval ships are vapor compression, submerged tube, and flash. Each was evaluated in the trade process of optimal design selection.
- (U) A.2.5.6 FUEL SYSTEM -- The fuel system performs the following functions: provides fuel of proper quality to all the thermal drivers for propulsion, lift, and electric power generation provides CG location management by using fuel transfer as a means of trimming; provides storage and service of fuel for the aircraft on board.
- (U) Designated tanks are established for: trimming and storage, storage, service for on board equipment, and service for aircraft. The need of interconnecting tanks for functional operation dictates the use of multiple controls and a well planned distribution system that provides redundancy. Fluid lines with mechanically assembled joints of well known reliability are used in sections which may need to be removed and replaced; otherwise, butt weld connections are used. Proliferation of connections is avoided by use of functional manifolds. Due to high flow conditions, valves must have defined times for the close-to-open or opento-close cycles to avoid hammering. Lines should be supported by resilient mounts to avoid premature fatigue and undue noise or vibration coupling, Underway fueling should be in agreement with naval practices.
- (U) The quality of the fuel should be closely controlled by use of high capacity filters for particulate contamination and water removal in lines between storage tanks and service tanks, and between service tanks and thermal driver units or aircraft.

- (U) The results foreseen are: weight savings, by a judicious selection of componnets and materials, and reliability by the use of **redundancy** and qualified components.
- (U) A.2.5.7 COMPRESSED AIR SYSTEM -- The compressed air system permits propulsion and lift turbine starting. It supplies air for actuation of back pressure valves, exhaust gas transfer valves and propulsion engine exhaust doors, and for miscellaneous uses as required. Weight reduction of the compressed air system was acheived by starting the GTG's by electric battery power. Several tons of high pressure charged air bottles were thereby eliminated. Practically all of the compressed air system components would be selected from available and qualified light-. weight components.
- (U) A.2.5.8 FIRE EXTINGUISHING SYSTEM -- A trade-off study was made to provide the design criteria and rationale for selection of the best flooding extinguishing agent. CO2 and Halon 1301 extinguishing systems were compared, and a Halon 1301 system was found to require less weight and to discharge a much shorter time as shown here:

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Agent	<b>Compart-</b> ment	Quantity of Agent	Total Discharge Time	/Toxicity Weight 'Class	
co <sub>2</sub>	5000 Ft <sup>3</sup> (850 m <sup>3</sup> )	250 Lb (1.11 kN)	90 <b>Sec</b>	825 Lb <b>5a</b> (3.67 <b>kN)</b>	
Halon 1301 I	5000 Fr <sup>3</sup> (850 m <sup>3</sup> )	141 Lb (627 <b>N)</b>	10 <b>Sec</b>	263 Lb 6 (1.17 kN)	

- (U) A.2.5.9 HYDRAULIC SYSTEM -- The choice of hydraulically-powered actuators/motors in lieu of either electrical or pneumatic equipment included weight, performance, cost, compatibility of design, installation and environment factors in each application. A trade-off study indicated a weight saving of several tons by employing hydraulicallypowered -equipment. The studies resulted in selection of the following system features:
  - Hydraulic Fluid: MIL-H-83282 was selected due to its ability to be operated at fluid temperatures up to 400°F (204°C); it is a synthesized hydrocarbon fluid that is interchangeable with MIL-H-5606.
  - 0 System Pressure: 3000 psi (20.68 kPa) is recommended as the system pressure; it is the most widely used high pressure, and consequently, a great variety of qualified components are marketed from which to choose.
  - o Optimum Fluid Temperature: A fluid system temperature between 100 to  $130^{\circ}F$  ( $54^{\circ}C$ ) is recommended for stable fluid operation.
  - 0 Pump Selection: Variable displacement constant pressure pumps of aircraft type were selected for lightweight and input horsepower economics proportionate to flow rate.
  - Reservoir: Pressurized reservoirs (bootstrap type) are substantially lighter and require less stored fluid (fluid weight alone is reduced by 1600 lbs (7117 N) minimum). These reservoirs are sized to deliver the required pump inlet pressure and maintain the entire return system pressurized which avoids external contamination.
  - o Rigid Tubing: CRES 304 is the selected material; it is readily available in the required diameters, relatively easy to bend and weld, and is appreciably less costly than tubing made from 21Cr-6Ni-9Mg. Welding was selected in preference to the use of fittings in the interest of

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minimizing leakage. Welding is also preferred to brazing on the basis of fabrication and inspection considerations.

- o Flexible Tubing: Flexible tubing is Teflon-lined to avoid static charges and dirt contamination associated with rubber (which also "sluffs off" particles which can dam servo valves).
- o Cleanliness and Filtration: Hydraulic fluid cleanliness must be enforced, fluid must be purchased to Class 1, components must be clean to Class 2 prior to installation, and the entire system must be maintained at Class 3 by adequate on-board filtration.
- (U) A.2.5.10 POLLUTION CONTROL -- The pollution control systems are for wastewater and oil. Wastewater includes sewage (human body wastes, blackwater, soil lines) and sanitary (or gray) water, which includes shower, laundry and galley water). The selection of a marine sanitation device includes evaluating the regulations, technical and operational factors, installation, and maintenance, and the cost of the system.
- (U) A weight trade-off analysis for the marine sanitation device was made on the basis of a one-day operational period to disclose a weight saving through use of a no-discharge type compared to a flow-through type. A waste oil tank, sized for a 15-day mission provides storage of collected waste oil from machinery and equipment drains for subsequent disposal at a shore facility, thereby conforming to the zero oil discharge regulation.

- (U) A.2.6 LIFT SYSTEM
- (U) A.2.6.1 AIR MANAGEMENT -- The design criteria applied to the development of the near term SES lift system air management concept were:
  - o The total nominal cushion flow rate at low sea states, to be 37,500 CFS (1061.88  $m^3/s)\,.$
  - The cushion pressure for a 3KSES point design would be 342 PSF (16.38 kPa).
  - Approximately **1/3** equal parts of total air supply to be delivered to the bow seal, cushion and stern seal.
  - A system efficiency shall be at least 75 percent.
    The system efficiency is defined as

$$\frac{(\underline{P} \times Q)/550}{BHP} \times 100$$

where P = cushion pressure at rated design

**Q** = total cushion flow

BHP = prime mover horsepower output

- All machinery should be capable of withstanding the following ship acceleration levels in g's: 6 up, 4 down, 2 forward, 3 aft and 0.5 thwartships.
- The lift system should have a minimum availability factor of 0.9285. Availability is defined as the ratio of mission uptime to total planned mission length.
- O There would be no requirement for blast resistance.
- Machinery spaces'would be acoustically treated to meet categories A through H.

- o Aircraft structural design practices would be applied to the design of machinery components in a marine environment with the goal of producing high strength-to-weight ratio components with a correspondingly high reliability.
- Mechanical vibration requirements for all ship machinery and equipment would be in accordance with Section .073c of the GSS.
- (U) In support of these criteria, thirty-three separate component specifications were developed to govern the lift system design.

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#### (U) A.2.6.2 SEALS SYSTEM

- (U) A.2.6.2.1 Seals Design -- The **seals** design was developed within requirements which include :
  - o sealing of the cushion with a minimum drag and minimal leakage of cushion air;
  - o design for a minor influence upon ship pitching motion in the absence of ride control;
  - o in concert with ride control devices, aids in reducing bow and CG accelerations to a level compatible with ride quality requirements; and
  - o exhibits lateral compliance while operating in waves other than those dead ahead or astern.
- (U) The seals are of modular design with the flexible seal material modules separated by tear inhibiting attachment fittings to reduce seal vulnerability. They are designed to minimize water ingress into the pneumatic bags and to provide for the rapid drainage of water that enters the bag. Standardization was emphasized in all portions of the design. Seal system weight was minimized with total design weight less than the following:

	<u>Maximum Acceptable</u>		Target		
Bow Seal, lb (N)	33,000	(147,000)	25,000	(111,000)	
Stern Seal, lb (N)	32,000	(142,000)	25,000	(111,000)	

(U) Attachment fittings were designed to minimize weight, be simple to remove and replace, to minimize structural fatigue of the flexible seal pressure bag material, to resist the effects of the marine environment, and (between hard structure and fabric) to be designed such that rubbing and impacting between the two structures is minimized to reduce wear. Further constraints included requirements that any seal system operational failure mode would not result in an unsafe ship operating condition and that retraction would be provided for off and partial cushion operation.

(U) The result is seal systems that feature ease of maintenance, repair and replacement with simple tooling and procedures in **drydock**, at dockside, 'and at sea. Non-elastomeric surfaces were employed on the planing bow and stern seals at the seal water interface to minimize hydrodynamic drag and **maximize** seal service life. The major seal system components were designed to MTBF characteristics of:

<u>Seal System Component</u>	<u>Minimum Acceptable</u>	<u>Target Service Life</u>
Planing Surface at	400 Operating	100 hours at
Seal/Water Interface	Hours	80 knots (41.16 m/s)
Bag and Upper Loop	I.000 Operating	2000 Operating
Seal Structures	Hours	Hours

- (U) A.2.6.2.2 Seal Materials -- Tear strength of the coated fabric pressure bag material was specified as a minimum of 300 pounds (1,333 N) with a target of 500 pounds (2,220 N), for tear propagation in the fill direction. (Tear strength is considered to be the controlling factor in the selection of the pressure bag material.) Tensile strength of the pressure bag material has a required minimum of 1000 pounds per inch (175,000 N/m) in the warp direction and 800 pounds per inch (140,000 N/m) in the fill direction. The pressure bag material is required to possess good environmental resistance, consistent with the seal system design specifications. The weight of the pressure bag material is minimized, consistent with the other requirements, with a maximum weight of 100 oz sq yd (33.25 N/m<sup>2</sup>).
- (U) The pressure bag material requirements included surviving  $10^6$  cycles at 20 percent of ultimate tensile strength in the warp direction (R=0.2); the goai was  $10^6$  cycles at 30 percent of ultimate tensile strength (R=0.2). Seams in the pressure bag material must meet the requirements for the coated fabric. The seams must also be relatively flexible and stiffness discontinuities in the joint minimized.
- (U) **Flexural** fatigue strength of the glass reinforced plastic (GRP) planer material shall be a minimum of 90,000 psi (6.20 x 108 Pa) in the

- (U) longitudinal direction and 85,000 psi  $(5.85 \times 10^8 \text{ Pa})$  in the transverse direction. Target values are 135,000 psi  $(9.30 \times 10^8 \text{ Pa})$  in the longi-tudinal direction and 105,000 psi  $(7.25 \times 10^8 \text{ Pa})$  in the transverse direction.
- (U) Maximum acceptable decrease in **flexural** fatigue strength of the planer material after aging in hot water shall be 18 percent. The target **value** is 12 percent. Tensile strength of the planer material shall be a minimum of 70,000 psi (4.83 x  $10^8$  Pa) in the longitudinal direction and 60,000 psi (4.14 x  $10^8$  Pa) in the transverse direction. The corresponding target values are 107,000 psi (7.38 x  $10^8$  Pa) and 90,000 psi (6.20 x  $10^8$  Pa). Tensile modules of the planer material shall be a minimum of  $3.7 \times 10^6$  psi (2.5 x  $10^{10}$  Pa) in the longitudinal direction and  $3.4 \times 10^6$  psi (2.3 x  $10^{10}$  Pa) in the transverse direction. The corresponding target values are  $5.0 \times 10^6$  psi (3.4 x  $10^{10}$  Pa) and  $4.2 \times 10^6$  psi (2.9 x  $10^{10}$  Pa).

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#### A.2.7 OUTFIT AND FURNISHINGS

(U) 'A.2.7.1 HABITABILITY -- The habitability standards should conform or exceed General Specifications for Ships of the U. S. Navy and OPNAVINST 9330.74 (proposed). Crew accommodations are as follows (based on manning requirements of the TLR):

	~ERTHING BREAKDOWN				
	TLR	TLR	TLR	TOTAL	ACTUAL
	CREW	GROWTH	RESERVATIONS	BERTHS PROVIDED	CREW
Enlisted	85	2	8	95	63
CPO	10	2	1	13	9
Officer	15	0	2	17	12
TOTAL	110	4	11	125	84

(U) A.2.7.2 PASSIVE FIRE PROTECTION -- The design philosophy for treatment of spaces in Group 1 implies prevention of primary aluminum structure from reaching 400° F (204° C) for a period of 15 minutes. This conservative approach in an active system design results in detection and extinguishment of a fire in within 5 minutes maximum.

The Fiberfrax panel system was selected for its superior performance relative to other lightweight **systems** considered. The methodology used to establish the insulation thickness is described in the following steps:

- a. A computerized thermal analysis established the relationship between felt insulation thickness and temperature of the structure under fire conditions.
- b. A full-scale JP-5 fuel fire test was conducted and the temperature distribution of the front face sheet of the insulation panels was monitored throughout the test.

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- (U) c. The temperature/time profile obtained during the tests was used as an input to thermal analysis, and temperature/ time curves were obtained for several insulation thicknesses (see Figure A.2.7.2-1 and A.2.7.2-2).
  - d. From the curves of Figures A.2.7.2-1 and A.2.7.2-2, plots were made of insulation thickness versus time for the structure to reach 400° F (204° C) (See Figure A-2.7.2-3).
- (U) The passive fire protection material for Group 2 spaces was also selected on the basis of smoke and toxic properties in a fire environment. The concern stems from the direct threat to personnel and from restricted visibility along escape routes. The very low smoke and toxic gas emission properties of Fiberfrax made this material attractive for application in Group 2 spaces.
- (U) The design approach to treatment of spaces in Group 2 is based on a modification of the fire loading concept described in the Society of Naval Architects and Marine Engineers (SNAME) Aluminum Fire Protection Guidelines. The fire loading of a space is a measure of the quantity of combustibles per unit deck area. It is expressed as pounds of wood per square foot with combustibles other than wood related to wood with a heat capacity of 8000 BTU/lb (1.86 x  $10^7$  J/kg), The methodology used to establish the amount of protection (insulation thickness) is described in the following steps:
  - a. Full .: ale fire tests were conducted with fire loadings of 12.5, 10, 7.5, 5 and 2.5 lbs mass of wood per square foot (61.0, 48.8, 36.6, 24.4 and 12.2 kilograms of wood per square meter).
  - b. The temperature/time profiles of the front face of the insulation panels during the tests were used as input to the thermal analysis computer program. Figure A.2.7.2-4 shows the temperature/time profiles for the various fire loadings.

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Figure A.2.7.2-2 (U): Temperature/Time Curves of Back Face of Insulation Panel and Aluminum Structure for Various Insulation Thicknesses in **a** JP-5 Fuel Fire (Structure Insulated on Far Side) **(U)** 

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Figure A.2.7.2-3(U): Insulation Thickness Vs Time for Aluminum Structure to Reach 400 Degrees I? in JP-5 Fuel Fire (U)

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- C. The program output the temperature/time envelope of the aluminum structure for various amounts of insulation thickness. The maximum temperature of the structure with a given insulation thickness for each fire loading is plotted in Figures A.2.7.2-5 and A.2.7.2-6.
- d. From the curves of Figures A.2.7.2-5 and A.2.7.2-6, plots were made of insulation thickness versus fire loading for one-side and two-side insulated structures (see Figure A.2.7.2-7).
- e. The insulation thickness was selected from these curves. (Panel thicknesses in increments of 0.25 in. (6.35 mm) were selected for practical manufacturing and ready material availability.)
- (U) The primary need in protecting magazines is to provide cooling when there is an adjacent fire hazard. Water sprinkling is the most efficient means to cool these spaces. Likewise, glass thermal insulation can be used more efficiently than refractory fibrous insulation in these spaces to prevent heat from entering,

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INSULATION THICKNESS, INCHES (mm)

Figure A.2.7.2-5 (U): Maximum Temperature of Aluminum Structure Versus Insulation Thickness for Various Fire Loadings in Solid Combustibles Fires (Structure Insulated on Far Side) (U)

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Figure A.2.7.2-6 (U): Maximum Temperature of Aluminum Structure Versus Insulation Thickness for Various Fire Loadings in Solid Combustibles Fires (Structure Not Insulated on Far Side) (U)

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(U) A.2.8 ARMAMENT - All topside sensors and armament were required to have as great an unobstructed coverage envelope as practicable. The order of precedence for coverage in descending order for the near term SES is:

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- o EW System AN/SLQ-31 or -32(V2)
- o Air Search Radar (AN/APS-125)
- o Surface Search (AN/SPS-55)
- o Collision Avoidance Radar (CAB)
- o FCS MK92
- o STIR
- 0 CIWS (MK15/0)
- (U) Harpoon launchers are fixed and should be facing forward. Both Harpoon and the vertical launchers for the Standard missile were to be located to result in minimal plume ingestion problems for the main combustion air intakes. Torpedo launchers were to be located to facilitate 0 • 45 deg options for firing MK46 torpedoes and a fixed athwartship axis for MK48 torpedoes (based on NAVORD studies). Appendix B contains diagrams outlining the coverage of the major near term SES weapons and sensors.
  - (U) The near term SES would only have a reload capability at sea for the MK46 torpedoes used in helicopter related ASW operations. As specified in the 3KSES TLR, no reload-at-sea capabilities would be provided for vertical missiles, MK48 torpedoes, surface launched MK46 torpedoes or Harpoon missiles.

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#### A.2.9 LOADS

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(U) .The weight allowances for variable load items were derived from Naval Ships Technical Manual dated 1 March 1974, Chapter 9290, Paragraph 173.1, titled "Detailed Description of Conditions of Loading for Surface Ships." Paragraph 173.1(a) covers weight allocations for crew and effects as follows:.

	Pounds (Newtons)	Per	Man
Officers (commissioned or warrant)	400 (1779)		
Chief Petty Officers	330 (1468)		
Other Enlisted Personnel	230 (1023)		

(U) The 3KSES TLR used as the near term SES requirement specifies a ship personnel complement of 17 officers, 13 chief petty officers and 95 enlisted men. The weight allowances then are:

		We:	ight
Personnel	Qty	Lbs.	<u>(kN)</u>
Officers	17	6800	(30.24)
Non-Corns	13	4290	(19.08)
Enlisted	95	21850	(97.19)
TOTAL	125	32940	(146.5)

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- (U) This 146.5 kN total corresponds to 14.71 long tons (F10).
- (U) Paragraphs 173.1(c) and (d) of the referenced Technical Manual cover weight allocations for provisions, personnel stores, and general stores as follows:

Provisions	Pounds	(Newtons	) Per	Man	Per	Day
Dry		3.20	(14.2	23)		
Freeze		1.11	( 4.9	94)		
Chill		1.65	( 7.3	(4)		
Clothing and Small Stores		0.07	( 0.3	81)		
Ship's Store		0.80	( 3.5	6)		
General Stores		1.06	( 4.7	2)		
(U) The ship provisions, personnel stores, and general stores using those provisioning allowances for a X-day mission follow:

Provisions and Personnel Stores:

6.83	pounds/man/day	30.38 N/man/day
x 15	days	15 days
102.45	pounds/man	455.7 N/man
x 125	men	125 men
12,806	pounds ÷ 2240 =	5.71 long tons (F31
(56.96 <b>kN)</b>		(56.96 <b>kN)</b>

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#### General Stores

1.06	pounds/man/day	4.72 N/man/day			
x 15	days	15 days			
15.9	days	70.73 N/man			
x 125		125 men			
1,988	pounds+2240 =	0.89 long tons (F32)			
(8.84	4 kN)	(8.84 <b>kN)</b>			

(U) The 3KSES TLR requires support for two SH-3H helicopters for a 15-day mission at the rate of 45 flight hours per month. The SH-3H has a nominal fuel consumption rate of 215 gallons per hour (0.0027 m<sup>3</sup>/hr) and JP-5 weighs 6.8 lbs per gallon (6654 N/m<sup>3</sup>). Therefore,

215	gallons/hour	(.0027 m <sup>3</sup> /hr)
x 6.8	pounds/gallon	(6654 N/m <sup>3</sup> )
1,462	pounds/hour	(1.80 <b>N/hr)</b>
x 45	hours/month	45 hours/month
65,790	pounds/month/helicopter	(292.6 <b>kN)</b>

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65,790	lb. ÷ 2 <b>(15-day</b> mission)	32,895 pounds/helicopter
		x 2 helicopters
		65,790 pounds (292.6 <b>kN)</b>
65,790	lb.+ 2240 pounds/ton	= 29.3 long tons (292.6 kN)
		helicopter fuel allocation

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#### A.2.10 WEIGHT MARGINS

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(U) The near-term ship weight margins were allocated in the same manner as for the 3KSES. The weight margin policy for the 3KSES was outlined in Navy letter PMS304-20 SER 2091; dated 12 June 1975. The weight margins were applied as in the cited letter with the exception of M13 (preliminary design and advanced development margin) which was depleted because the appropriate design phase has been completed for the 3KSES. The following Table A.2.10.1 outlines the margins as applied.

#### TABLE A.2.10-1 (U): Near Term SES Weight Margins (U)

SWBS No.	SWBS No. DESCRIPTION	
M11 <b>M12</b> M13	Detail design margin Building Margin Preliminary Design and Advanced Development	2.5% LS <sup>(1)</sup> 1.0% LS
<b>M21</b> M22 M23 <b>M25</b>	Margin Contract design margin Contract Mod. margin GFM Margin Service life Margin	3.0% LS 2.0% LS 1.0% LS 0.5% LS 25 LT (249.10 kN)

(1) LS = Light Ship

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#### A.2.11 VEHICLE

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(U) A.2.11.1 Payload Weight Breakdown — The vehicle weight summaries shown in Table A.2.11-1 and A.2.11-2 detail the near term ship as defined in ANVCE WP-002, "Definition of Terms", dated 2 April 1976, Section III. The contract margins are included in the vehicle empty weights. These weight breakdowns support range and payload performance projections in Section 2.2.3.

#### TABLE A.2.11-1 (U): Vehicle Weight Summary (FT9A-2A) (U)

SYMBOL	TITLE	TITLE LONG SHORT TONS TONS		METRIC TONS	KILO NEWTONS	
W <sub>E</sub> <sup>1</sup>	<b>Empty Weight Less</b> fixed payload items	1561.0	1748.3	1586.0	15,554	
<sup>w</sup> c	Ship's Complement and Effects & Store	21.4	24.0	21.7	213.2	
WP	Payload	177.2	198.4	180.0	1,765	
WF	Liquids	1240.5	1389.3	1260.4	12,360	
W	Vehicle Weight	3000.0	3360.0	3048.2	29,892	

SYMBOL	TITLE	LONG CONS	SHORT TONS	METRIC TONS	KILO NEWTONS
w <sub>E</sub> <sup>1</sup>	Empty Weight less fixed payload items	1599.0	1790.9	1624.7	15,932
<sup>w</sup> c	Ship's Complement and effects <b>&amp;</b> stor	21.4 ks	24.0	21.7	213. <b>:2</b>
W <sub>P</sub>	Payload	177.2	198.5	180.0	1,765
WF	Liquids	1202.4	1346.7	1221.7	11,981
lī₩	Vehicle Weight	3000.0	3360.0	3048.2	29,892

#### TABLE A.2.11-2 (U): Vehicle Weight Summary (FT9A-2A) (U)

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- (U) A.2.11.2 STABILITY AND RESERVE BUOYANCY The near term SES must survive, with margin, the operational hazards of the open ocean, as specified in the criteria of:
  - Goldberg, L. L., Tucker, R. G., "Current Status of Stability and Buoyancy Criteria Used by the U. S. Navy for Advanced Marine Vehicles?, Naval Engineers Journal, October 1975.
  - Sarchin, T. H., Goldberg, L. L., "Stability and Buoyancy Criteria for U. S. Naval Surface Ships", Transactions of the SNAME<sup>(1)</sup>, Volume 70, 1962.
- (U) The freeboard and internal subdivision of the near term SES must be selected to satisfy the qualification of the criteria for reserve buoyancy and stability in terms of:
  - Hullborne intact stability
  - o Reserve buoyancy under conditions of hull damage
  - Damaged stability
- (U) Analysis has demonstrated that the near term SES design would meet the Navy criteria established for Large SES's as set forth in the cited references for displacements in excess of 3000 tons.

(1) Society of Naval Architects and Marine Engines

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#### (U) A.2.12 MANNING

The Rohr selection criteria for crew size and composition, and some of the design alternatives by which the near term SES crew size and composition was developed, are the result of a Rohr-developed methodology that utilized the LSES TLR and the "Guide to the Preparation of Ship Manning" (OPNAV 10P-23), to impact design and trade-off studies.

- (U) A.2.12.1 MANNING **CRITERIA** -- In arriving at the crew size and composition, the following criteria were used:
  - The design of the near term SES supports demonstration of the feasibility of platform performance, including that at high speed, and combat capability.
  - The near term SES was not designed to meet existing Navy standards for wartime use, but incorporates salient features of a combatant ship for evaluation purposes.
  - o Required operational capabilities (ROC) as defined in the LSES TLR of 28 May 1976 were employed to identify requirements for manned stations and their location, control equipment, and manned station layouts and support systems. The ROC are projected for performance of military value demonstration and combat system compatibility.
  - o The Projected Operational Environment in Fleet Operations was derived from the TLR to delineate specific capabilities which the fully-ready LSES should achieve as goals as follows:
    - At sea in peace time, Readiness Condition IV and for Battle Readiness, Special Condition I.
    - A capability to perform anti-air, anti-submarine, and surface warfare on a non-simultaneous basis.
    - 3) A capability to meet emergency contingencies.
    - 4) A capability to perform maintenance for which the crew is assigned responsibility.

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(U) A.2.12.2 READINESS CONDITION -- Conditions of readiness for the purpose of determining operational, maintenance, administrative and support capabilities required to support the SES are as follows:

- Special Condition I Battle Readiness -- These conditions for the near term SES are:
  - 1) Condition I ASW: Anti-submarine operations
  - 2) Condition I AAW: Anti-air operations
  - 3) Condition I SUW: Surface operations

All required personnel continuously alert. All required operational systems manned and operating. No maintenance expected except that associated with critical and vital equipment repair. Reduced readiness requires changes from the Required Operational Capabilities approved by the Chief of Naval Operations for Special Condition I.

- Condition IV: Peacetime Cruising Readiness Operational systems are normally manned only to the extent necessary for effective ship control, propulsion and security. Accomplishment of all underway maintenance, support and administration functions is expected. Maximum advantage is taken of training opportunities. Expected endurance at Condition IV is 15 days.
- Condition V: In-Port Readiness Systems are manned to the extent necessary for effective operation. Watch stations are assigned as required to provide adequate security. Personnel on board are **adequate** to meet anticipated in-port emergencies and perform in-port functions as prescribed by unit ROC. Accomplishment of all required maintenance, support and administrative functions is expected. Maximum advantage is taken of training opportunities and (subject to the foregoing requirements), the crew has a maximum opportunity for rest, leave, and liberty.

- (U) A.2.12.3 MANNING ALTERNATIVES --- The following design alternatives were instrumental in the development of the crew size and composition:
  - o The near term SES Ship's crew was developed within the implied requirements of the combat system concept for a weaponized test ship, rather than for a lead ship of its class.
  - o The administrative office requirements were combined into two adjoining offices to provide adequate working areas rather than individual office spaces per man. The combined offices are:
    - Operations Office, Weapons Office, Engineering Office --The combination of these offices into the department office provides working space for the department heads, ship's 3-M coordinator, and engineering personnel.
    - 2) Data Bank/Technical Library Within the data bank there are work areas for research and equipment, for making copies of stored data and for conference purposes.

This central administrative complex is interconnected by arches providing access to each function performed. The design is economical in terms of equipment, furniture, space, and manpower utilization, and results in weight reduction.

- o The central (rather than remote) control concept has resulted in more efficient utilization of manpower. Ship automation features include full control of ship's steering, propulsion, auxiliaries and damage control from the pilot-house and Central Operating Station (COS). The minimum required watch positions for the SES are:
  - 1) **OOD/Ship** Control Officer
  - 2) JOOD/Asst. Ship Control Officer
  - 3) Lookout/Signalman
  - 4) Propulsion Control Console Operator
  - 5) Damage Control/Auxiliary Console Operator

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- (U) A.2.12.4 OPERATIONAL MANNING **REQUIREMENTS** Operational manning is the sum of quantitative and qualitative naval manpower needs to man essential operating stations during a specified condition of readiness. The operational manning requirement for a condition of readiness is expressed in terms of the related condition watch organization. The minimum essential **operational stations** developed for the near term SES are:
  - Special Readiness Condition I, manned on a one-section basis, requires 79 operational stations.
  - Readiness Condition IV, manned on a three-section basis, requires 5 operational stations (15 personnel). The minimum number of personnel required for Readiness Condition IV is 54 (duty and watch).
  - Readiness Condition V, manned on a one-in-three watch rotation within each of six duty section basis, requires two operational stations (36 personnel).
  - Flight quarters, manned on a one-section basis, requires
    37 operational stations.
- (U) A.2.12.5 ORGANIZATIONAL MANNING The organizational manning requirements developed for the near term SES are:

	Officers	CPO's	Other Enlisted	Total
Crew <b>Helo</b> Det. TOTAL	0 8 0 4 1 2	<u>0 b</u> 0 9	<u><u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u><u></u></u></u>	19 66 85

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#### (U) A.2.13 PERFORMANCE

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The proposed 3000 LT (29,892 **kN)** near term SES includes all of the fuel (for both ship and helicopters), sensors and weapons specified in the 28 May 1976 3RSES TLR. The basis upon which the near **term** SES design performance was developed compared with 3RSES TLR requirements is:

Design Parameter	3KSES TLR LT (kN)	ANVCE Near Tern SES LT (kN)
F <b>ull</b> Load Displacement (LT; <b>kN)</b> Mean Operating Displacement (LT; <b>kN)</b>	3000 (29,892) <b>1920<sup>(1)</sup> (19,131)</b>	3000 (29,892)) 2400 <sup>(2)</sup> (23,914
Wind Speeds	Pierson <b>Moskowit</b> (no attitude gra	<b>z</b> Sea Spectra dient)
<b>T</b> 'ail Pipe (Trapped Fuel) Allowance (LT; <b>kN)</b>	46 (458)	64.6 (644)
<b>Marine</b> Fouling Allowances	1 mil Surface Fi	nish
Ambient Temperatures - air water	80 <sup>°</sup> F (26.67 <sup>°</sup> C) 59 <sup>°</sup> F (15 <sup>°</sup> C)	

(1) Mean	Operating	Displacement	at	10%	fuel	load	(LM2500	propulsion)
(2) Mean	Operating	Displacement	at	50%	fuel	load	(LM2500	propulsion)

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- (U) Detailed comparisons between performance of the **3KSES** design and the 28 May 1976 TLR requirements regarding speed, hump margin, acceleration and deceleration, turning, range, and operational Sea State performance are outlined in the following sections:
- (J) A.2.13.1 SPEED The predicted speed capability and requirements are shown in Table A.2.13-1. All speed requirements at a full load displacement of 3000 LT are met, including the requirement of 30 knots (15.4 m/s) with a significant wave height of 15 ft (4.57 m), FT9A-2A engines at maximum continuous power (MCP), and for headings up to 60 deg or more from a head seas condition. Off-cushion, the SES provides operational speed capability approaching the goals.
- (U) A.2.13.2 HUMP THRUST MARGIN Comparison between the predicted and required hump thrust margins for the **3KSES** are shown in Table A.2.13-2. The near term SES betters the deceleration goals specified with either the LM 2500 or FT9A-2A configuration. The acceleration goal is met with the LM 2500 configuration; however, the FT9A-2A configuration requires almost twice the acceleration goal time interval.
- (U) A.2.13-4 TURNING -- The TLR specified that the **3KSES** must meet the following:
  - On and off-cushion, ahead and astern, control of heading for docking, undocking and low speed maneuvering in a seaway.
  - Maximum Tactical Diameter of 4500 Et (1.37 km) at speeds below hump speed.
  - Maximum Tactical Diameter of 15,000 ft (4.57 km) when entering a turn at maximum speed. (The SES is not required to maintain constant speed in turns above hump speed).

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Table 2.3.13-1 (C) Maximum Speed Performance (U)

			Requirement	Knots (m/s)	Predicted	
Operation	Configuration	Ft.(m)	Coal	Min,	Knots (m/s)	
Ahead On-Cushion	Mean Operating Displacement <b>LM2500</b> at MCP	<b>0</b> 3.3 (1.0) 15.0 (4.57)	$\begin{array}{ccc} 100 & (51.4) \\ 80 & (41.2) \\ 40 & (20.6) \end{array}$	70 (36.0) 30 (15.4)	76 (39.1) 70 (36.0) 31 (15.9)	
	Full Load Displacement <b>FT9</b> at MCP	0 3.3 (1.0) 15.0 (4.57)'	$\begin{array}{ccc} 100 & (51.4) \\ 80 & (41.2) \\ 40 & (20.6) \end{array}$	70 (36.0) 30 (15.4)	81 (41.7) 73 (37.6) 30 (15.4)	
Ahead Off-Cushion	Full Load Displacement Engine at MCP	0	15 (7.7)		14 (7.2) <b>LM2500</b> 15 (7.7) <b>FT9</b>	
		15.0 (4.57)	10 (5.1)		9 (4.6) <b>LM2500</b> 9 (4.6) <b>FT9</b>	
Astern Off-Cushion	Full Load Displacement Engines at <b>MCP</b>	0	10 (5.1)		5 (2.6) <b>LM2500</b> 5 (2.6) <b>FT9</b>	
	Englines at <b>EUF</b>	10.0 (3.05)	5 (2.6)		4 (2.0) LM2500 4 (2.0) FT9	

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Table **A.2.13-2** (C). Hump Thrust Margln (U)

		Significant Wave Height - Ft. (m)		Require	ment-%	Predicted Capability %
Operation	Configuration			Goal	Min.	
Ahead <b>On-</b> Cushion	Mean Operating Displacement <b>LM2500</b> at <b>MIP</b> (1920 LT; 19,131 <b>kN)</b>	3.3	(1.0)	15	10	86
	Full Load Displacement <b>FT9</b> at MIP (3000 LT; 29,892 <b>kN)</b>	3.3	(1.0)	30	20	2 1

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Table A.2.13-3 (C). Acceleration/Deceleration (U)

		Soc	Requirement		Predicted Capability	
Operation	Configuration	State	Goal	Min.	LM2500	FT9
Ahead On-Cushion Acceleration to Full Speed	Full Load Displacement	0	<b>180</b> Sec.	<b>-</b> '	<b>92*</b> Sec.	<b>330</b> Sec.
Ahead On-Cushion Deceleration from Full Speed	Full Load Displacement	0	<b>3000 Ft.</b> (914.4 m)	-	735 Ft. (224.0 m)	2955 Ft. (900.7 <b>m)</b>

\*This value is seemingly low only because the LM2500 configuration is limited to sub-hump operations at FLD.

- (U) Figure A.2.13-1 depicts several turns attainable with the FT9A-2A configured near term SES at full load displacement. The figure shows that the SES can better the TLR's on- and off-cushion turn requirements.
- (U) A.2.13.5 RANGE -- The predicted range performance characteristics are compared with the TLR range requirements. The range capability of both the LM2500 and the FT9A-2A configuration is computed on the basis of an average speed greater than 63 knot8 (31 m/s); the LM2500 configuration nearly attains its goal, bettering the requirement by more than 15 percent. The FT9A-2A configuration better8 the requirement by about 10 percent. Range performance is shown in Table A.2.13-4.
- (U) A.2.13.6 MAXIMUM OPERATIONAL SEA STATE -- The relationships between ship operating mode and the operational envelope are shown in Figure8 A.2.13-2 and A.2.13-3. These figure8 define the operating envelope8 in term8 of the operating mode, speed and sea state. Figure A.2.13-2 define8 operating envelopes which are based on the Navy's Top Level Requirement8 (TLR) of 28 May 1976 while Figure A.2.13-3 defines the envelopes which are TLR goals. The on-cushion envelopes define the operation with respect to the propuision system gas turbine engine. The baseline engine is the LM2500 and the alternate is the FT9A-2A.

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Table A.2.13-4 (C). Range (U)

		Significant Wave Height	Requirement NM (km)		Predicted Capability
Operation	Configuration	Ft. <b>(m)</b>	Goal	Min.	NM (Km)
Ahead On- Cushion	Full Load Displacement LM2500 Average Speed . 60 Kts (31 m/s)	3.3 (1.0) (No Wind)	3000 (5556)	2500 (4630)	2960 (5482)
	Full Load Displacement FT 9 - Speed 60 Kts (31 m/s)	3.3 (1.0) (No Wind)	3500 (6482)	3000 (5556)	3295 (6102)

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Figure A.2.13-3 (C): 3KSES Operational Envelope - Goals (U)

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#### A.3 DESIGN PHILOSPHY

- (U) The overriding philosophy of the near term point design SES design for the capability of demonstrating that the SES concept can fulfill a role as an operational fleet unit. Every design decision has supported this philosophy. The result is a balanced design in which no single feature is dominant. All subsystems and their components were accorded careful development and engineered to meet the specified Top Level Requirements (TLR).
- (U) The ANVCE near term SES is a cost effective design, inhabited and operated by sailors, which provides superior performance, seaworthiness, and survivability in high sea states. The design philosophy is manifest in the ship's performance and subsystems design.
- (U) The SES meets or betters Top Level Requirements for speed, range, and hump margin in all sea states at a full load displacement of 3,000 LT (29,892.1 kN). The available range margin can be traded off against producibility, weight or increased payload. It betters all requirements for turns, Translation and rotation maneuvers are easily made at zero and low forward speeds for docking, harbor operations, and certain tactical situations. It comes to a full stop from maximum speed in 1000 yards (914.4 m).
- (U) The ride quality is much better than required for crew comfort and performance of precision tasks. The superior ride quality is maintained over the entire operational envelope and has been proven at sea. A destroyer (DD-963) cruising at 10 knots, sea state 5, meets the established 4 hour limits. The near term point design SES operating at 60 knots, sea state 5, easily meets and can exceed the same 4 hour ride criteria.
- (U) The design is inherently stable. It is safely operable well beyond tha limits of the operational requirements. It is **functional** in sea state 6.

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- (U) It is designed to survive hurricane conditions. Extensive digital computer simulation and 3,800 hours of tow tank testing confirmed the design as stable and safe.
- (U) It is a habitable and highly maintainable ship due to careful attention given to functional space arrangements and by designing the ship with 9 foot (2.74 m) deck heights to assure adequate head room in all spaces where activity is required. Duty stations and living spaces are located away from noise and vibration producing machinery. All living spaces and messing areas are located for best ride quality and with least noise.
- (U) The lift and ride control system is unique and effective. It is a proven system. The ride control system (RCS) attenuates vertical motions to levels within ride criteria limits.
- (U) It utilizes an advanced planing seal concept which easily meets the trans-oceanic requirements of long life and high reliability. The seals are a marked advance in the state-of-the-art.
- (U) The propulsion system is designed for operational use. It is a simple, proven system sized for growth. It is a symmetrical system port and starboard that is easily aligned and maintained,
- (U) The near term point design SES incorporates an integrated ship control system which enables five (5) men to operate the ship in complete safety. It is designed for centralized operation, operational simplicity, full exploitation of the SES potential, and fail safe operation. Reliability and safety are fully integrated into the design.

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#### (U) A.4 TRADE-OFF STUDIES

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**Many** design variations were considered during the development of the near term SES point design. These required various trade-off studies in the general areas of ship configuration, subsystems, and performance.

- (U) A.4.1 CONFIGURATION TRADE-OFFS -- The near term SES is a full langth sidehull ship with an effective length-to-beam (L/B) ratio of 2.60. The choice of full length sidehulls over partial length sidehulls was the result of trade studies that included consideration of parameters such as drag, static and dynamics stability, sea worthiness, seal design, maneuverability and structural weight fraction.
- (U) The selected seals design resulted from trade-offs that considered the application of a two-dimensional, planing type seal, or a bag-and-finger type seal. Factors evaluated in the definition of the seal baseline included design simplicity, durability, response characteristics, high speed drag, performance and off-cushion drag penalties.
- (U) Lateral directional stability at high yaw angles is provided by fixed ventral fins. The specification of these devices and their related fences are the results of trade-off studies considering various geometries and evaluating their drag, waterjet inlet broaching, and maneuvering performance.
- (U) The configuration also includes semi-flush waterjet inlets and related ventilation cutouts. T: 3 location and geometry of the inlets and ventilation cutouts are the result of trade studies involving drag, weight, propulsion efficiency, and machinery location considerations.
- (U) A number of trade-offs were made to determine the impacts of variation in bulkhead spacing, frame and stiffner spacing and number c decks within the hull. The considerations were optimization of the structural weight fraction while providing sufficient enclosed volume to accommodate the required ship company, machinery fuel, and specified military payload.

#### (U) A.4.2 KEY SUBSYSTEMS TRADEOFFS

- (U) A.4.2.1 Main Propulsion System -- Trade-offs for the propulsion machinery subsystem emphasized criteria which resulted in a design that provides optimum performance, low development risk, minimum complexity, high reliability, maximum protection from environmental elements, good habi-tability and replacement of most major components without drydock of the ship. The primary tradeoff was between waterjet propulsors and partially submerged, supercavitating propellers, Waterjets were chosen because the produce much lower noise and vibration levels, are less susceptible to damage by floating debris, have less complex transmission systems, can be maintained without drydock (except for some elements of the waterjet inlet), and can be acquired at lower cost and with less developmental risk.
- (U) The propulsion system utilizes four LM2500 gas turbines identical to those in service on the DD963 ships, The LM2500 engine has low fuel consumption, adequate power, long life and high reliability. However, all components of the propulsion subsystem are sized to accommodate the higher rated FT9A engines, with but minor modifications.
- (U) Other major tradeoffs were in the propulsion machinery arrangement, combustion air system, and waterjet inlet. All propulsion components, except the waterjet inlet, are located above the wet deck to obtain good maintainability and minimize complexity. Use of seemingly available space in the sidehulls resulted in poor installations with disadvantages outweighing the marginal advantages in performance, Similarly, the combustion air system was generously sized to minimize engine power losses and maximize accessability, salt removal, and noise suppression.
- (U) The selected waterjet inlet is a flush, variable roof arrangement that provides superior cavitation and recovery performance, simplicity and low drag.

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- (U) A.4.2.2 Lift System -- An intensive parametric tradeoff study of both axial, mixed flow and centrifugal fans resulted in the selection of dual inlet, single discharge, constant velocity volute, centrifugal fans because of their low weight, compact geometry, and favorable performance properties. A further tradeoff resulted in consideration and rejection of two circulation control designs when compared to the fan concept. Circulation control was found relatively complex and not as advanced as the technology for fans; a proven 1/4 scale fan model was in operational use. The selection of the lift prime mover was based upon the fan power requirements which matched the proven LM2500 with no other GT available in the power range for comparison.
- (U) Trade-offs of various fan locations and their attendant shafting and ducting complexity were performed. The result was a design featuring simple inline shafting, minimum ducting length and minimum use of duct elbows. The inline shafting employs proven marine helical gear sets (single reduction) over more complex planetary gears.
- (U) Ducting trade-offs are closely related to those for the power transmission, With fan locations and air delivery points established, further tradeoffs determined the minimum weight ducting configuration, with no common plenum or duct plenum, no duct air spliting, and use of round ducts. The fair-weather intake design resulted from trade-off studies concerning free stream pressure recovery, noise control, fabrication techniques, base drag, weight, and water ingestion.

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- (U) The location of the ride control ducting and valving was determined through trade-offs involving ship's available space, thrust augmentation, and weight impact.
- (U) Major trade-offs for the seals were in seal geometry, modularization, and selection of detail hardware and materials. The seals geometry tradeoffs compared planing seals with bag-and-finger seals. The planing seal geometries included both two- and three-dimensional (curved bow planform)

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seals in concert with the square bow/full length sidehull tradeoff.

- (U) The planing seal was selected for its demonstrated lower drag forces, improved wear resistance and the durability of glass reinforced plastic planar elements. The two-dimensional plan 3 bow seal was selected along with the square bow/full length sidehull because together they offered a more simplified seal design, modularization of components, and improved seal maintainability and reliability.
- (U) Modularization trade-offs were performed to optimize seal maintenance, to minimize loads and, to assure high performance in a seaway. Components included were number and type of restraints (straps and cables) and quantity of planers and bag modules,
- (U) Significant hardware and seal mater trade-offs included comparisons of (1) straps and cables, (2) mater s for planers, pressure bags, restraints, attachments, and modular oints and (3) planer-to-strap transition attachments. Key criteria in these trade-offs were weight, reliability, maintainability, ease of fabrication, and methods of design verification.
- (U) A.4.2.3 Trade-offs optimized the electrical power generation and conversion subsystem design. The weight was reduced by almost 50% by increasing the use of 400 Hz power. The power requirements were adjusted through judicious selection of user equipment so that 400 Hz and 60Hz power consumptions were equal. The weight savings resulted from the extensive use of 400 Hz generators and motors, which weigh less than one-eighth as much as their 60 Hz counterparts.
- (U) Direct generation of 400 Hz power by generators powered by aircraftderivative turbines (in lieu of 60 to 400 Hz converters) was a principal factor in this accomplishment. While **impressive** weight savings at reasonable dollar cost were made, further conversion to 400 Hz usage

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would result in sharply increased costs, owing to the need for special equipment development.

- (U) Auxiliaries -- Weight trade-offs were made of 12 air conditioning systems and equipment items as a result of this study. A decentralized system was selected. This system divides the load into smaller serviced areas, each using packaged air conditioning units.
- (U) Single centralized and multiple dedicated lube systems were analyzed on the basis of weight, cross contamination, cooling requirements, length of lines, bulkhead penetrations, reliability, and redundancy. A multiple dedicated system was selected.
- (U) The trade-offs for the potable and fresh water systems involved investigation of components and configurations possessing potential weight savings. Vacuum-assisted water closets and low water demand showers were selected. Weight was reduced through reduced quantities of collected and stored water via the drainage system and the reduced pumping capacity requirement. Further weight reduction was obtained by selecting GRP piping.
- (U) A trade-off study was made to provide the design criteria and rationale for the most advantageous total flooding extinguishing agent. CO<sup>2</sup> and Halon 1301 extinguishing systems were compared, and a Halon 1301 system was preferred over a CO<sub>2</sub> system for its lower weight and shorter discharge time.
- (U) Hydraulically-powered actuators, motors, and pumps were compared to electrical and pneumatic equipment on the basis of weight, cost, compatibility installation requirements and operating environment. Trade-off comparisons indicated a weight saving of several tons by employing hydraulically-powered equipment. In some instances, the electric motor-driven actuators appeared so bulky and cumbersome as to be essentially impractical. In the case of high-per-

- (U) formance servo-driven devices such as the ride control valves, low inertia servo-motors with power ratings not readily obtainable would be required.
- (U) Weight trade-offs for marine sanitation on the basis of a one-day operational period disclosed weight savings by utilizing a no-discharge type compared to a flow-through type.
- (U) A.4.2.5 Outfittings and Furnishings -- Trade-offs were made for the insulation and protection (fire, thermal and acoustical) of the aluminum structure. A rigid panel placed outside the frames was compared to a flexible blanket placed against the structure. The rigid panel design was selected because of:
  - Ease of installation

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- Reusability of panels after removal for inspection of structure
- Ease of modular panel replacement
- Elimination of separate sheathing and false ceilings
- . Resistance to deterioration during normal shipboard use
- Efficient thermal protection of structure through utilization of an air gap between the panel and structure and a reflective surface facing the fire threat and
- Elimination of insulating against fire for the cabling and piping systems.
- (U) Contrariwise, the advantages of flexible blanket design are lower cost, slightly lower weight, increased space, and elimination of the hazard of fire penetration behind the insulation panel. However, the develop-

#### A-68

ment of an effective and practical seal for panel joints to prevent fire penetration offset the advantages of flexible blanket design.

- (U) The large amount of insulated and sheathed cabling and piping external to the flexible blanket design, coupled with the relatively close frame spacing of 3 feet, further minimized the increased space advantage of the flexible blanket design and imposed a weight and cost disadvantage.
- (U) **A.4.3** PERFORMANCE TRADEOFFS -- Maximum performance of the selected design configuration was optimized with respect to:
  - 1) Speed (at minimum drag) with maximum continuous power.
  - 2) Thrust margin at hump speed with maximum intermittent power.
  - 3) Range.
  - (U) Optimization of each of these performance factors involved selecting a best operating policy (i.e., the determination of operating trim and draft), lift system airflow settings, and seal adjustments within the adjustment latitude and constraints of the design. While this selection could be an n-dimensional optimization process of great complexity, only a limited number of major effects need be considered in practice. The key trade-offs are:
    - T<u>rim and Draft for Least Drag</u> Ship operating attitude for minimum drag is **determined** by **comparing tank** test data with analytically-derived relationships. The resulting policy is checked against system constraints to assure that the desired attitudes can be achieved with the available adjustments.

 Lift System Optimization - Airflow distribution, pressure ratios and seal settings are optimized with empirical data in conjunction with analytical characterizations of the lift system. Policies for least drag and least total fuel rate are developed,

3) Optimum Cruise Speed - There is a speed at which range is maximized for each vehicle weight between zero and 100 percent fuel. This speed is found recursively by a performance computer program that includes appropriate representations of drag, lift system and propulsion system characteristics.

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#### APPENDIX B: DRAWINGS AND DIAGRAMS

#### (U) B.1 GENERAL ARRANGEMENT DRAWINGS

(U) This section of Appendix B contains the general arrangement drawings for the near term ANVCE SES Point Design. These drawings are as follows:

<u>Figure</u>	G/A Title	Dwg.	Ref.
B.1-1	Outboard Profile	LL80	2001
B.1-2	Inboard Profile	LL802	2002
B.1-3	01 Level and Above	LL80	2003
B.1-4	Main Deck	LL803	2004
B.1-5	Second Deck	LL802	2005
B.1-6	Third Deck	LL80:	2006
B.1-7	Wet Deck	LL80	2007
B.1-8	Traverse Section	LL80	2008
B.1-9	Inboard Profile	LL80	2010
B.1-10	Bow and Stern Views	LL80	2011
B.1-11	Tank Arrangement	LL80	1001
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NO 4	<u> </u>	Q-7	3896.4	3710.9		64
NO 5	SHULL	14-2B	4163 2	3965.0		. 90
NO 6		14-28	4163.2	3965 0		. 90
NO 7	T3W	14-28	2409-2	2294.5		2
NO 8		14-28	2409.2	2294.5		
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(U) B.2 WEAPON AND SENSOR COVERAGE DIAGRAMS

(U) This section of Appendix B contains the weapon and sensor coverage diagrams for the ANVCE near term SES Point Design. These diagrams are:

#### Figure <u>Title</u>

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- **B.2-1**. APS-125 Air Surveillance Coverage is Unobstructed
- B.2-2 Elevation Coverage from the High APA-171 Antenna Position Extends the Radar Horizon for "Pop-Up" Threat Detections
- **B.2-3** Surface Search Coverage with the AN/SPS-55 is Extensive for Maneuvering, Piloting, and SUW
- **B.2-4** Elevation Coverage for Surface Search is not Obstructed Along Critical Azimuth Bearings
- **B.2-5** Collision Avoidance Coverage is Unobstructed for Critical Sectors and Ship Maneuvering Options
- **B.2-6** Elevation Coverage is Unobstructed for Debris Detection Close to the Ship's Bow, Dead Ahead
- **B.2-7** Fire Control System Surveillance and CW Illumination Coverage is Extensive
- **B.2-8** Elevation Coverage Provides Full Capability for AAW and ASMD **Fire** Control
- B.2-9 The Mk 54 Mod 0 Antenna Site Augments Mk 92 FCS Coverage
- **B.2-10** Full STIR Elevation Coverage for Sea Skimmer and Zenith Threats
- **B.2-11** The CIWS Weapons Groups Provide Complete **360-Degree** ASMD Azimuth **Coverage**
- **B.2-12** Full CIWS Weapons Group Elevation Limits are Only Reduced for a Small Sector Dead Ahead

- (U) B.2-13 The Forward Location of the IR Sensor in the EW Suite Covers Critical Threat Approach Corridors
  - **B.2-14** The Forward IR Sensor has an Elevation Coverage Providing an Unrestricted Field-of-View
- (U) These diagrams each have descriptive titles that emphasize the features of the weapon and sensor coverage inherent in the near term SES.



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Figure B.2-2 (U): Elevation Coverage from the High APA-171 Antenna Position Extends the Radar Horizon for "Pop-Up" Threat Detections (U)

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Figure B.2-3 U): Surface Search Coverage with the AN/SPS-55 is Extensive for Maneuvering, Piloting and SUW (U)

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AS-279/AP (APS-116(M) CAS)

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Figure 3.2-5 (U): Collision Avoidance Coverage is Unobstructed for Critical Sectors and Ship Maneuvering Options(U)

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Figure B.2-6 (U): Elevation Coverage is Unobstructed for Debris Detection Close to the Ship's Bow, Dead Ahead (U)

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Figure B.2-8 (U): Elevation Coverage Provides Full Capability for AAW and ASMD Fire Control(U)

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Figure B.2-9 (U): The MK 54 MOD 0 Antenna Site Augments MK92 FCS Coverage (U)

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Figure B-2-11 (U): The CIWS Weapons Groups Provide Complete 360-Degree ASMD Azimuth Coverage (U)

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Figure B.2-12 (U): Full CIWS Weapons Group Elevation Limits are Only Reduced in Depression for a Small Sector Dead Ahead (U)

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Figure **B.2-13 (U):** The Forward Location of the IR Sensor in the EW Suite Covers Critical Threat Approach Corridors (U)

IR SENSOR AN/SLQ-31 (V2)

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#### (U) B.3 STRUCTURE **DRAWINGS**

(U) This section of Appendix B contains the structure drawings for the ANVCE near term SES Point Design. These drawings are:

Figure	<u>Title</u>
B.3-1	Deck Plating <b>-</b> Main Deck
B.3-2	Bulkhead 🛥 Long, CL
B.3-3	Transverse Bulkheads
B.3-4	Transverse Frame
B.3-5	Bow Plating and Framing
B.3-6	Superstructure
B.3-7	Extrusions - Structural
B.3-8	Tabulation - Plating/Tee

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Figure 8.3-7 (Sheet 1 of 5) (U)

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	ExT	н	W	7.	T2	LB/FT	I IEM	Н	w	T.	T <sub>2</sub>	LB/FT	្រា	ITX	н	W	T.	T2	18/	FT						
	-201	2.50	1.65	.100	.00	.474	-234	12.00	6.00	750	.500	11.695		295	10.00	6.00	.425	625	11.1	18						
	-202	2.50	1.65	.125	.125	.587	-239	4.00	8.00	.250	.250	3.392		296	8.00	6.00	.500	.750	10.0	06						
	-203	300	1.75	.100	.100	. 543	-242	12.00	2.50	350	.190	3.566		297	15.00	6.00	.700	.275	9.3	78						
	-204	3.00	1.75	.125	.125	. 674	246	400	2.00	.250	. 150	1.232	1 5	298	1.00	4.00	1.000	.750	14.1	82						
	-205	150	1.75	-125	.125	. 146	-248	12.00	1.00	.160	.160	2.743	1 5	299	4.00	8.00	.375	.500	5.5	75						
	-206	150	1.75	.150	.150	. 889	257	8.00	800	.600	.575	8.744	ΙΓ													
	-207	4.50	2.25	.150	.150	1.148	-258	12.00	4.00	.500	.250	5.624	iΓ													
	-208	5.00	2.50	.175	.175	1.484	-266	12.00	4.00	L000	.500	10.9 75	Ι Γ													
	-209	5.00	2.50	.200	.200	1.690	-273	12.00	4.00	.225	.175	3.418	1 [													
	-210	5.50	2.75	.350	.350	3.200	-274	8.00	4.00	.275	.125	2.387	1 [													
	-211	6.00	300	.200	.200	2.095	-275	10.00	6.00	. 700	.400	9.144														
	-212	6.50	3.25	.250	.250	2.744	-276	8.00	4.00	.950	.375	7.441														
	-213	7.00	150	.350	.350	4.108	-277	5.00	600	.700	.350	10.619														
	-214	700	3.50	.450	.450	5.295	- 278	15.00	6.00	.400	225	6.557														
≻	-215	7.00	350	.600	.600	6.887	-279	12.00	4.00	.325	.200	4.195														
	-216	4.00	8.00	.375	.375	5.039	- 280	12.00	4.00	625	325	7.152														
	-217	8.00	8.00	1.000	1.000	17.404	-281	10.00	4.00	600	.550	6.570								ľ	•W					
	-218	4.00	8.00	.750	.750	9.790	- 282	10.00	4.00	.950	325	7.779								ļ				Ł		
	-219	4.00	8.00	.500	.375	6.137	-285	8.00	4.00	.400	.700	8.033							ł	٩		<u> </u>		r		
	-220	4.00	800	.313	.180	3.657	-284	8.00	4.00	.400	.300	4.481										$\mathbf{i}$		L7,		
	-221	4.00	2.50	.150	.120	.972	-285	<b>8</b> .00	4.00	.575	.350	5.659							н			R	2. Iz	L		
	- 222	0.00	8.00	.150	.750	14.974	-286	8.00	4.00	.325	200	3.274											2			
	-773	350	1.75	.160	.160	.946	-257	15.00	6.00	.800	450	12.916									U					
i	- 226	8.00	6.00	.750	.500	15.151	-288	18.00	6.00	.300	.200	6.157										_				
	-228	8.00	6.00	.750	.750	11.518	- 289	15.00	6.00	.425	.250	7.143		DO	CUME	NT R	ELEAS	E			+ }	- T2				
	-229	8.00	6.00	.500	.250	5.624	-290	11.00	4.00	.550	.200	5.180	-	- <b>P</b> A	العذور		-	chel	12							
	-230	a.00	6.00	.750	.500	8.239	-291	12.00	4.00	.700	.225	6.162		CON	16 163			· · ·								
	-231	1.00	0.00	-160	.160	2.190	-292	15.00	6.00	.375	200	5.969							SEE	<u>S</u> P	IEET	I FOR	NO	ies l	REVIS	SIONS
	232	200	6.00	.250	.250	5.392	-273	10.00	4.00	.425	.175	3.896							821	COD	t IDEMT	DWE NO				, I
1	-233	1.00	100 j	.500]	.250	5.674	-294	8.00	3.00	.250	.125	1.988							B	51	1662 1662	Γ L	LI	010	004	1/
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Figure **B.3-7 (Sheet 2** of 5) (U)

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Figure **B.3-7** (Sheet 3 of 5) (U)





Figure B.3-7 (Sheet 4 of 5) (U)

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Figure **B.3-7** (Sheet 5 of 5) (U)

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#### (U) B.4 PROPULSION SYSTEM DRAWINGS

(U) This section of Appendix B contains the following propulsion system drawings:

#### Figure **Title**

- **B.4-1** Main Propulsion Machinery Arrangement, P/S
- B.4-2 Waterjet Inlet Arrangement, Port and Starboard
- (U) The remainder of the detailed propulsion system description for the ANVCE near term SES is contained in Section 2.3.2.

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(U) B.5 C<sup>3</sup> ARRANGEMENT DRAWINGS AND BLOCK DIAGRAMS

(U) This section of Appendix B contains the command, control, and communications (C<sup>3</sup>) arrangement drawings and block diagrams for the near term ANVCE SES. They are:

<u>Figure</u>	Title
B.5-1	Combat Information Center, Main Deck
B.5-2	Communication Center, Main Deck
B.5-3	Radio Transmitter Room, Main Deck
B.5-4	Data Processing Room, Main Deck
B.5-5	Helicopter Control Station, 01 Level
B.5-6	Command and Surveillance Block Diagram
B.5-7	IC Voice System Matrix



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OVER       EXCHANCE IN A CERT INFORMATION CONTROL       EXCHANCE INFORMATION CONTROL       Image: Im		-MICHOFILM		REVISIONS	,	
OVER   21   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1   1			A REVISED P	DESCRIPTION FR ECR LODOD 3	0ATE APPROVED 4-24-76 40/2/25	
OVER       32     MX 61 CONSOLE (SPACE C.WEGHT)       34     MX 62 CONTEXC FALL (SPACE C.WEGHT)       35     MX 62 CONTEXC FALL (SPACE C.WEGHT)       36     MX 62 CONTEXC FALL (SPACE C.WEGHT)       37     CONTEXC FALL (SPACE C.WEGHT)       38     MX 62 CONTEXC FALL (SPACE C.WEGHT)       39     CONTEXC FALL (SPACE C.WEGHT)       37     CONTEXC FALL (SPACE C.WEGHT)       38     CONTEXC FALL (SPACE C.WEGHT)       39     CONTEXC FALL (SPACE C.WEGHT)       30     CONTEXC FALL (SPACE C.WEGHT)       31     CONTEXC FALL (SPACE C.WEGHT)       32     CONTEXC FALL (SPACE C.WEGHT)       33     CONTEXC FALL (SPACE C.WEGHT)       34     CONTEXC FALL (SPACE C.WEGHT)       35     CONTEXC FALL (SPACE C.WEGHT)       34     CONTEXC FALL (SPACE C.WEGHT)       35     CONTEXC FALL (SPACE C.WEGHT)       36     CONTEXC FALL (SPACE C.WEGHT)       37     CONTEXC FALL (SPACE C.WEGHT)       36     CONTEXC FALL (SPACE C.WEGHT)       36		1 1	1		6-20-76 1 20 Anistino	
31     MK & 61     CONSOUE (SPACE & WEGAT)       32     MK & 61     CONSOUE (SPACE & WEGAT)       33     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       34     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       35     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       36     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       37     VOED FARLE (SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       38     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       39     CLOSE IN SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       30     CLOSE INSCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       31     SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & WEGAT)     1       30     FARLE (SPACE & MARLE SPACE & MARLE (SPACE & WEGAT)     1       31     SCREWLS SISTEM REPORT CONTOCE FARLE (SPACE & MARLE SPACE & MARLE SPA						
SVER       32     MK 61 CONSOLE (SPACE { WEIGHT)       32     MK 61 CONSOLE (SPACE { WEIGHT)       32     MK 49 TORPED D FRING PARTEL (SPACE (WEIGHT)       32     LIGS IN WEAPONG STORT REPORTS CONTROL PAREL (SPACE (WEIGHT)       34     RECORD FORMER DESC.       35     CONST DURING PARTEL (SPACE I WEIGHT)       36     LIGS IN WEAPONG STORT REPORTS CONTROL PAREL (SPACE I WEIGHT)       37     LIGS IN WEAPONG STORT PERIOD CONTROL PAREL (SPACE I WEIGHT)       36     LIGS IN MEAPONG STORT PERIOD CONTROL PAREL (SPACE I WEIGHT)       36     LIGS IN MEAPONG STORT PERIOD CONTROL PAREL (SPACE I WEIGHT)       36     LIGS IN MEAPONG STORT PERIOD CONTROL PAREL (SPACE I WEIGHT)       37     LIGS IN MEAPONG STORT PERIOD CONTROL PAREL (SPACE I WEIGHT)       36     LIGS INFORM TROUGHT OF REPORTS PERIOD PERIOD CONTROL PAREL (SPACE I WEIGHT)       37     LIGS INFORM TROUGHT OF REPORTS PERIOD PER						
OVER         24       PNK 46 TOAPEDD FINING FINIS, USPACE 4 V/FIGNT)         25       CUDS 11, WEADONS 52, STEM SERVICE CONTROL FORLE (SPACE 1 WEIGHT)         26       SADIO FACINE TUXERED ESK.         27       CUDS 01, FINIS, FINIS, FINIS, USPACE 4, V/FIGNT)         28       EXAMPLE TUXERED ESK.         29       CONTROL FORLET         20       EXAMPLE TUXERED ESK.         21       EXAMPLE TUXERED ESK.         22       EXAMPLE TUXERED ESK.         23       EXAMPLE TUXERED ESK.         24       EXAMPLE TUXERED ESK.         25       EXAMPLE TUXERED ESK.         26       EXAMPLE TUXERED ESK.         26       EXAMPLE TUXERED ESK.         27       EXAMPLE ESK.						
21     WK 48     CONSOLE (SPACE 4 WE CUT)     1       25     KK 48     CORPEDD FIRINE PAREL (SPACE 1 WEIGHT)     1       26     KK 48     CONSET IN WEADONS SYNTEM REMOTE CONTROL PRANEL (SPACE 1 WEIGHT)     1       27     KALD POOLY ZAUKET CESA     1       28     FOLS POOLY ZAUKET CESA     1       20     FOLS POOLY ZAUKET CESA     1       20     FOLS POOLY ZAUKET CESA     1       20     FOLS POOLY ZAUKET O SPLAC CONSOLF ANJUACH (FOD)     1       20     FOLS POOLY ZAUKET ANSULATION (FOLSE)     1       20     COMA SE CONTROL PAREL (FOLSE)     1       21     REGUTION     2       22     CONTROL PAREL (FOLSE)     2     1       31     REGUTION SECONTROL PAREL (FOLSE)     1     1       32     REGUTION CONSOLE ANSOLA ANTOLOGICONTROL (FOLSE)     1     1				,		
OVER         24. MK &B TORREDO FIRING ENKEL (\$202.5 \u0397)         25. CLOSE IN WERDOLS \$371FM ENTOTE CONTROL PRAFL (\$PRCE 1 WEIGHT)         26. TORPEOD FIRING ENKEL (\$1202.5 \u0397)         27. TORPEO FIRIC (\$121.5 \u0397)         28. TORY ENGLISH (\$125.5 \u0397)         29. TORPEOL (\$130, \$71,00 \u0397)         21. TORPEOL (\$130, \$71,00 \u0397)         22. TORPEOL (\$130, \$71,00 \u0397)         23. TORY ENGLISH (\$130, \$71,00 \u0397)         24. TORPEOL (\$130, \$72,00 \u0397)         25. TORY ENGLISH (\$130, \$12,00 \u0397)         26. TORY ENGLISH (\$130, \$12,00 \u0397)         27. TORPEOL (\$130, \$12,00 \u0397)         28. TORY ENGLISH (\$130, \$12,00 \u0397)         29. TORY ENGLISH (\$130, \$12,00 \u0397)         20. TORE ENGLISH (\$100, \$12,00			*			
31     MK &BI CONSOLE (SPACE 4 WEIGHT)     1       32     MK &BI CONSOLE (SPACE 4 WEIGHT)     1       32     MK &BI CONSOLE (SPACE 4 WEIGHT)     1       32     SOLAR TORPEDO FIRING PANEL (SPACE 1 TOG FAREL (SPACE 1 WEIGHT)     1       34     SOLAR TORPEDO FIRING STATUS SALEL (SPACE 1 WEIGHT)     1       35     SOLAR TORPEDO FIRING SALEL (SPACE 1 WEIGHT)     1       34     SOLAR TORPEDO FIRING SALE (SPACE 1 WEIGHT)     1       35     SOLAR TORPEDO FIRING SALE (SPACE 1 WEIGHT)     1       32     SOLAR TORPEDO FIRING SALE (SPACE 1 WEIGHT)     1       35     SOLAR TORPEDO FIRING SALE (SPACE 1 SALE 1						
21     MK & CONSOLE (SPACE & WEIGHT)     1       22     MK & TORREDO FLANKE PAREL (SPACE & V/FIGHT)     1       23     CLOSE MULTICES SUPERING PAREL (SPACE & V/FIGHT)     1       24     STARPEDO FLANKE PAREL (SPACE & V/FIGHT)     1       25     STARPEDO FLANKE PAREL (SPACE & V/FIGHT)     1       24     STARPEDO FLANKE PAREL (SPACE & V/FIGHT)     1       25     STARPEDO FLANKE PAREL (SPACE & V/FIGHT)     1       26     STARPE ASSENSEL & STORSE (SPACE ASSENSEL & SPACE & V/FIGHT)     1       27     STARPE ASSENSEL & SPACE & V/FIGHT     1       28     SCHORE ASSENSEL & SPACE & V/FIGHT)     1       29     STARPE ASSENSEL & SPACE & V/FIGHT)     1       20     STARPE ASSENSEL & SPACE & V/FIGHT)     1       20     STARPE ASSENSEL & SPACE & V/FIGHT)     1       20     STARPE ASSENSEL & SPACE & V/FIGHT)     1       21     SCORTEON INFORMED & SPACE & V/FIGHT)     1       21     SCORTEON INFORMED & SPACE & V/FIGHT)     1       21     SCORTEON INFORMED & SPACE & V/FIGHT)     1       21     STARPE ASSENSEL & SPACE & V/FIGHT)     1       21     STARPAREDE CONTROL C & SPACE V/FIGHT)     1 <td></td> <td></td> <td></td> <td></td> <td></td>						
21       MX.63       CONSDUE       (SPACE 4, WEIGHT)         24       MX.63       TORPEDD       FIRING       FIRING         24       MX.64       TORPEDD       FIRING       FIRING         24       EXDDID       FIRING       FIRING       FIRING         24       EXDDID       FIRING       FIRING       FIRING         24       EXDDID       FIRING       FIRING       FIRING         25       EXDID       FIRING       FIRING       FIRING         26       EXDID       FIRING       FIRING       FIRING         27       EXDID       FIRING       FIRING       FIRING         28       FIRING       FIRING       FIRING       FIRING         20       ET PERFECTOR       FIRING       FIRING       FIRING         20       ET PERFECTOR       FIRING       FIRING       FIRING         20       ET PERFECTOR       FIRING       FIRING       FIRING       FIRING         20       ET PERFECTOR       FIRING       FIRING       FIRING       FIRING       FIRING         20       FIRING       FIRING <td></td> <td></td> <td></td> <td></td> <td></td>						
21     Mix 61     CONSQUE (SPACE 4, WE(GHT))     1       23     CHOSE IN WEADOLS SYSTEM REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       23     CLOSE IN WEADOLS SYSTEM REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       24     RADIO FONDEL SALED DESK.     1       25     CONTROL PANEL ADVIS SYSTEM REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       26     TOTOLSE DESTRES CONTROL PANEL (SPACE 4 WEIGHT)     1       27     TOTOLSE DESTRES CONTROL PANEL (SPACE 4 WEIGHT)     1       20     EST EXCOMPT NO.3366/350-55     1       20     EST PECOMER ADVISOR SERVEY     1       20     EST PECOMER ADVISOR SERVEY     1       21     EST PECOMER ADVISOR SERVEY     1       22     EST PECOMER ADVISOR SERVEY     1       32     COMMAN SET CONTROL CONSULT ANTONO     2       33     ECONSULT ADVISOR SERVEY     1       34     EST CONTROL CAMAPS-125     1       35     EADOR SET CONTROL CAMAPS-125     1       36     ECONTROL CAMAPS-125     1       37     WERD SET CONTROL CAMAPS-125     1       36     EADOR SET CONTROL CAMAPS-125     1       37     WERD SE						
31       MK 61 CONSOLE (SPACE 4 WEIGHT)       I         32       MK 65 TORPED FISHING PARLE (SPACE 4 V/EIGHT)       I         32       CLOSE IN VERADUS SYSTEM RAMPE CONTROL FANLEL (SPACE 4 WEIGHT)       I         32       CLOSE IN VERADUS SYSTEM RAMPE CONTROL FANLEL (SPACE 4 WEIGHT)       I         32       EONE FASSE MAY FOR SERVICE CONTROL FANLEL (MOD)       I         32       SOUND FASSE FALL FOR SON SOLE (SANJE)       I         32       EONE FASSE MAY FOR SERVICE (SANJE)       I         33       ECONSOLE (SANJE)       I         34       FOR ECONSOLE (SANJE)       I         35       CONSOLE (SANJE)       I         36       ACOMING ATOR ASSERVALY       I         36       CONSOLE (SANJE)       I         37       RECEVER AND CATOR ASSERVALY       I         38       CONSOLE (SANJE)       I       I         39       ROAR ASSERVALY       I       I         36       ACOMING AND ASSERVALY       I       I         36       ROAR ASSERVALY       I       I         31       ROAR ASSERVALY       I       I         310       ROAR ASSERVALY						
31       MK 61       CONSOLE (SPACE & WEIGHT)       1         32       MK 49       TORREDO FIRING, PANEL (SPACE & WEIGHT)       1         34       RADIO FIGUE TAURER DESSA       1         37       TORREDO FIRING, PANEL (SPACE & WEIGHT)       1         34       RADIO FIGUE TAURER DESSA       1         37       TORREDO FIRE CONTROL FANGE MAY 2001       1         38       TORREDO FIRE ASSEMANCE CONTROL PANEL (MK 305       1         37       TORREDO FIRE CONTROL FANGE MAY 2005-36       1         38       TORREDO FIRE CONTROL FANGE MAY 2005-36       1         39       CONTROL FANGE MAY ROTSE AND 2005-35       1         31       TORREDO FIRE CONTROL FANGE MAY 2003-36       1         31       TORREDO FIRE CONSULT ON AND AND AND AND AND AND AND AND AND AN						
21     MK 61     CONSOLE (SPACE & WEIGHT)     1       23     MK 45     TORPEDO FIRING PANEL (SPACE & VIEIGHT)     1       24     EXCOMPTOD FIRING PANEL (SPACE & VIEIGHT)     1       25     CLOSE IN WEAPONE SYSTEM REMOTE CONTROL PANEL (SPACE (WEIGHT)     1       26     TORNE TOLKER LESK.     1       27     EXCOMPTOD FIRING PANEL (SPACE (WEIGHT)     1       28     FORME TOLKER LESK.     1       29     FORME TOLKER LESK.     1       20     EXCOMPTON LEXITY OF TOLKER LESK.     1       20     EXCOMPTON LEXITY OF TOLKER LESK.     1       20     EXCOMPTON LEXITY FORMER CONSOLE * AN/DUBLIC MODDING TOLKER AND LEXITY OF TOL						
211     MK 6.1. CONSOLE (SPACE & ME GHT)       125     PLAUSE IN MERIONS FISTING PROFE CONTROL PANEL (SPACE { WEIGHT)       125     PLAUSE IN MERIONS FISTING PROFE CONTROL PANEL (SPACE { WEIGHT)       121     FRADOR SECTOR MERIONE CONTROL PANEL (SPACE { WEIGHT)       123     SONF RECEIVER (STORES)       124     FRADOR SECTOR MERIONE       125     SONF RECEIVER (STORES)       126     STORE RECEIVER (STORES)       127     SONF RECEIVER (STORES)       128     FCOMMER ASSEMBLY RO-358 JACES-156       139     COMMER ASSEMBLY RO-358 JACES-156       141     REFECIEVER (MAUCATOR ASSEMALY       15     LC STATION       16     ACOUST CONSLUCE "ANALY RO-358 JACES-156       16     ACOUST CONSLUE" ANALY RO-358 JACES-156       17     RECEIVER (MAUCATOR ASSEMALY       18     RECONFRONCE MARABER CONSOLE" ANALYSER       19     CONSSUE (STROME CONSOLE" ANALYSERS       11     RELECTOR MIC ANARESE CONTROL CONSOLE" CONSOLE" ANALYSERS       11     RELECTOR MIC ANARESE CONTROL CONTROL CONSOLE" STROE       11     RELECTOR MIC ANARESE CONTROL CONTROL CONTROL CONSOLE" CONTROL						
21     MK 48     ICONSOLE (SPACE 4 WEIGHT)     I       24     MK 48     TORPEDD FIRING PANEL (SPACE 4 WEIGHT)     I       25     CLOSE IN WEAPOREDD FIRING PANEL (SPACE 4 WEIGHT)     I       24     BADIO FROME TALKED DESK     I       27     TORPEDD FIRING CONTROL FANLL (SPACE 4 WEIGHT)     I       24     EADIO FROME TALKED DESK     I       27     TORPEDD FIRING CONTROL FANLY CONSOLE     AN/UQE-1 (MOD)       21     EOUT STATUNE TALKED DESK     I       29     COMMA SET CONTROL FANDOR TO STEMASON     I       29     COMMA SET CONTROL FANDOR TO STEMASON     I       20     ETEREMONE ASSEMANT ACTISE TANON TO STEMASON     I       21     ESTATION LS-337A     I     I       21     REGORDER ASSEMANT ACTISE TANON TO A-R3537(VI2/0YA-4(V)     I     I       21     REGORDER ASSEMANT ACTISE TANON TO A-R3537(VI2/0YA-4(V)     I     I       21     REGORDER ASSEMANTANIA     I     I     I       21     REGORDER ASSEMANTANIA     I     I     I       21     REGORDER ASSEMANTANIA     I     I     I       21     REGORDER ASSEMANTANIA <td< td=""><td></td><td></td><td></td><td></td><td></td></td<>						
34     IMK 61     CONSOLE (SPACE & WEIGHT)     1       34     IMK 64     TORPEDO FIRINS PAREL (SPACE & WEIGHT)     1       35     CLOSE IN WEAPONDE SYSTEM REMOTE CONTROL PANEL (SPACE & WEIGHT)     1       34     BADIO PHONE TRUNERD SYSTEM RASO     1       34     TORPEDO FIRE CONTROL PANEL (SPACE & WEIGHT)     1       37     TORPEDO FIRE CONTROL FANCE MK 300     1       30     EGUM, GET CONTROL FANCE MK 300     1       30     EGUM SET CONTROL FANCE MK 300     1       30     EGUM SET CONTROL FANCE MK 300     1       31     CONTROL MASSER CONTROL MASSER MK     1       32     CONTROL MASSER CONTROL MARKY 2007-10     1       32     CONTROL MARKY 2005-20     1       32     CONTROL MARKY 2005-20     1       33     CONTROL CONTROL CONSOLE MARKY 2005-31     1       34     REDUCTION LESSON 200     1     2       35     RADAR SET CONTROL CONSOLE CONSOLE MARKY 2						
31     INK 61     CONSOLE (SPACE 4 WEIGHT)     1       34     INK 49 TORPEDO FIRINS, PANEL (SPACE 4 WEIGHT)     1       35     CONSOLE IN MERCINS STEP REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       35     CONSOLE IN MERCINS STEP REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       36     CONSOLE IN MERCINS STEP REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       37     TORPEDO FIRINS TO THAT THAT					:	
21     MK 81 CONSOLE (SPACE 4 WEIGHT)     1       25     CLOSE IN VERADONS SYSTEM REMOTE CONTROL PANEL (SPACE 4 WEIGHT)     1       23     TORPEDD FIRE CONTROL PANEL (SPACE 4 WEIGHT)     1       23     TORPEDD FIRE CONTROL PANEL (SPACE 4 WEIGHT)     1       24     RADIO F-JONE TALKER CESS     1       25     SOKAS RECEIVING SET DIPLAY CONSOLE ANJURA: (MOD)     1       21     EGUI. (STATION FACTOR) SSERALY     1       25     COMMA SET C-7X402 WOC2:     1       26     ETRECOVER ASSERALY     1       27     ETRECOVER ASSERALY     1       28     FECCAVER ASSERALY     1       29     ETRECOVER ASSERALY     1       20     ETRECOVER ASSERALY     1       21     ESCINE ASSERALY     1       20     ETRECOVER ASSERALY     1       21     ESCINE ASSERALY     1       20     ETRECOVER ASSERALY     1       21     RECOVER ASSERALY     1       21     ESCINETON     1     1       21     RECENTERAL PRADOUT     0     1       21     ERECOVERASULT (SOKSOLE)     1     1						
21     MK & D CONSOLE (SPACE & WEIGHT)     1       24     MK & TORPEDO FIRING, PANEL (SPACE & WEIGHT)     1       25     CLOSE IN WEAPONS \$375TEM REMOTE CONTROL PANEL (SPACE & WEIGHT)     1       23     TORPEDO FIRE CONTROL PANEL MK 300     1       23     SOND PACELYING SET DI SPLAY, CONSOLE AN/UQR-1 (MOD)     1       24     RADIO PAONE TOROL PANEL MK 300     1       25     SOND PACELYING SET DI SPLAY, CONSOLE AN/UQR-1 (MOD)     1       21     EQUIT. TENT CARINET     1       22     ET RECOVER ASSEMENT, RO-3587A02-10     1       18     RECOVER ASSEMENT, RO-3587A02-10     1       17     FRECENZER/INDICATOR ASSEMENT, RO-3587A02-10     1       16     ACOUNTIC DISPLAY CONSOLE * AN/UYO-1     1       13     CONSOLE (SROWTH)     1       14     REV CONSTROL, CANTERD, CANTERS ES     1       16     ACOUNTIC DISPLAY CONSOLE * AN/GLQ-31     1       17     READER SET CONTROL, CONSOLE * AN/GLQ-31     1       18     RELONE CONSOLE * AN/GLQ-31     1       19     RADAR SET CONTROL, CONSOLE * AN/GLQ-31     1       10     FRADAR SET CONTROL, CONSOLE * AN/GLQ-31     1	OVER					
21     MK.61. CONSOLE (SPACE & WEIGHT)     1       25     CLOSE IN WEAPONS SYSTEM REMOTE CONTECL PANEL (SPACE & WEIGHT)     1       23     TORPEDD FIRES, PALKER EXAMPLE (SPACE & WEIGHT)     1       23     TORPEDD FIRES, PALKER EXAMPLE (SPACE & WEIGHT)     1       23     TORPEDD FIRES, PALKER EXAMPLE (SPACE & WEIGHT)     1       23     SOND R RECEIVER, WIGS SET OFFICE, PANEL MK 360     1       24     RADON R SET OFFICE, PANEL MK 360     1       25     SOND R RECEIVER, MISSON 56     1       26     DT RECONDER, ASSEMPTI ROTSSON 56     1       27     SOND RECEIVER ASSEMPTI ROTSSON 56     1       28     SOND RECEIVER ASSEMPTI ROTSSON 56     1       29     CONSTROL STATION LSESTALY     1       20     CONSTROL STATION LSESTALY     1       21     CONSTROL STATION LSESTALY     1       20     CONSTROL STATION LSESTALY     1     1       21     CONSTROL STATION LSESTALY     1     1       22     CONSTROL STATION LSESTALY     1     1       23     CONSTROL STATION LSESTALY     1     1       24     RADAR SET CONTROL CANAPS-LSS     1     1						
15     CLOSE IN VERSONS SUSTED REMOTE CONTROL PANEL (SPACE ( WEISHT)       12     RADDE POILS PANEL PAKEL MK 300       13     TORPEDD PRE CONTROL PANEL MK 300       14     REDUCK MS RECEVENTS STD STD STD STD STD STD STD STD STD S	27 MK BI CONSOLE (SPAC	CE & WEIGHT)			1	
1       SCOULD FLATTER LESK       PANEL MK 305         12       1       TORPEDO FLATE CONTROL PANEL MK 305         12       1       SON 27       PECTIVING SET D.SPLAY CONSCLE ANZUGE-1 (MOD)         1       1       TORPEDO FLATE CONTROL FOR STORE       1         20       ECTRECONCER ADDERTAR CONSCLETANZONS-ISA       1       1         20       ECTRECONCER ASSEMENT RO-3587/052-756       1       1         20       ECTRECONCER ASSEMENT RO-3587/052-756       1       1         10       FACOMER ASSEMENT RO-3587/052-756       1       1         11       ECONSOLE ANXIVO-11       1       1         12       RECONSOLE CATA RESONAL       1       1         13       COLOSSIC CONSOLE TAN/SUC-31       1       1         14       RPV CONSOLE CATA RECONSOLE AN/SUC-31       1       1         11       ELECTRONIC WARFARE CONSOLE TAN/SUC-31       1       1         12       REMOTE CONTROL CONSOLE TAN/SUC-31       1       1         11       ELECTRONIC WARFARE CONSOLE TAN/SUC-31       1       4         11       ELECTRONIC WARFARE CONSOLE TAN/SUC-31       1       1         11	25 CLOSE IN WEAPONS SY	STEM REMOTE CONTR	OL PANEL (SPA	ACE & WEIGHT)		
22     SURTY HECLIVING SET D.SPLAY CONSOLE, AN/UGR-1 (MOD)     1       20     ET RECONCER, NO.3268/350-56     1       20     ET RECONCER, NO.3268/350-56     1       20     ECOMM SET C.274402 WOG-2     1       18     RECONCER, ASSEMENT, RO.3582/05-36     1       17     RECEMER/INDIGATOR ASSEMENT, RO.3582/05-37     1       18     RECONSTRUCTOR SEGNALY     1       19     COMMISSION (STROL)     1       11     RECONSTRUCTOR ASSEMENT, RO.3582/05-36     1       11     RECONSTRUCTOR ASSEMENT     1       12     RECONSTRUCTOR APRIATE CONSOLE (SROWTH)     2       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     2       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     2       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     1       12     RADAR SET CONTROL CONSOLE (SROWTH)     5       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     5       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     5       11     ELECTRONIC WARFARE CONSOLE (SROWTH)     5       12     MARPSIC CONTROL CONSOLE (SROWTH)     5       13     WARFARE CONTROL CONSOLE (SPACE 1)///////////////////	23 TORPEDO FIRE CONTR	OL PANEL MK 309				
20     ET PECOLUER R.0-3268/30-56     I       9     COMM SET     C-74402/W02C-2     I       11     RECORDER ASSEMENT R0-358/A0S-13A     I       12     RECORDER ASSEMENT R0-358/A0S-13A     I       14     RPV CONSOLE * AN/VYC-11     I       15     IC STATION LS-537A     I       14     RPV CONSOLE (SROWTH)     I       13     CO POSITION     Z-3537A       14     RPV CONSOLE (SROWTH)     I       13     CO POSITION     Z-4477/SPC-55       14     RPV CONSOLE CONSOLE AN/SLQ-31     I       10     RADAR SET CONTROL AN/APS-125     I       11     EECTRONIC MAREARE CONSOLE AN/SLQ-31     I       12     RADAR SET CONTROL AN/APS-125     I       13     MR SET CONTROL CONSOLE CONSOLE (SPACE TWEIGHT)     I       14     STIR WEAPON CONTROL CONSOLE (SPACE TWEIGHT)     I       11     OPERATIONS SUMMARY CONSOLE CONSOLE (SPACE TWEIGHT)     I       12     HAPPON WEAPON CONTROL CONSOLE (SPACE TWEIGHT)     I       13     MR SU WEAPON CONTROL CONSOLE (SPACE TWEIGHT)     I       14     STIR WEAPON CONTROL CONSOLE (SPACE TWEIGHT)     I   <	21 EQUI SENT CABINET	T DISPLAY CONSOLE	AN/UQR-1 (MO	(0)		
18   PECOPOER ASSEMBLY   PO-358 /AOS-15A   1     17   RECEIVER/LINOCATOR ASSEMBLY   1     16   ACOUSTIC DISPLAY CONSOLE * AN/UYC-(1)   1     17   RECEIVER/LINOCATOR ASSEMBLY   1     18   REV CONSOLE (GROWTH)   1     12   RECONSTRUCT ON SOLE (GROWTH)   1     13   CO POSITION   STATE PERCONT     14   REV CONSOLE (GROWTH)   2     12   RECONTROL CONSOLE AN/SEC0.31   1     10   RADAR SET CONTROL AN/APS-125   1     11   ELECTRONIC WARFARE CONSOLE AN/SEC0.31   1     10   RADAR SET CONTROL AN/APS-125   1     11   BAPPI DISPLAY CONSOLE CO-104(VI3/UVA-4(V)   (INCLUDING TWO GROWTH)     12   RADAR SET CONTROL CONSOLE   1     13   MK SU WEAPON CONTROL CONSOLE   1     14   STIR WEAPON CONTROL CONSOLE   1     15   DATA SET CONTROL CONSOLE   1     16   ADDRESS CONTROL CONSOLE   1     17   YILL   YILL     18   PENDON CONTROL CONSOLE   1     19   PARTS AND MATERIAL LIST   1     10   PARTS AND MATERIAL LIST   1     11   OPERATIONS SUMMARY CONSOLE   1     12	20 BT RECORDER RO-326B/	1550-56 10C-2				
16     ACOUSTIC DISPLAY CONSOLE AN/UYC-11       17     11       18     IC STATION LS-537A       14     RPV CONSOLE (GROWTH)       13     IC OPSETTON       14     RPV CONSOLE (GROWTH)       15     IC REAMSET CONTROL       16     RECORDER CONSOLE AN/SEQ-31       17     RECONTROL       18     PPT DISPLAY CONSOLE OT-09447/SPS-55       19     RADAR SET CONTROL       10     RADAR SET CONTROL       11     RECONTROL       12     READAR SET CONTROL       14     RPT DISPLAY CONSOLE       15     DATA SET CONTROL       16     ADDRESS CONTROL INDICATOR C-90627U       17     VILEO DECOCER KY-761 (P) /UPA-3594/1       18     PPT DISPLAY CONSOLE       19     DATA SET CONTROL CONSOLE       19     DATA SET CONTROL CONSOLE       10     TABLEAPOON WEAPON CONTROL CONSOLE       11     OPERATIONS SUMMARY CONSOLE       12     HARPOON WEAPON CONTROL CONSOLE       14     STIP WEAPON CONTROL CONSOLE       15     DESCRIPTION       11     OPERATIONS SUMMARY CONSOLE       14 <td>18 RECORDER ASSEMBLY RO</td> <td>0-358/AOS-13A</td> <td></td> <td></td> <td></td>	18 RECORDER ASSEMBLY RO	0-358/AOS-13A				
14     RPV CONSOLE(GROWTH)       13     CO POSITION       14     REV CONSOLE(GROWTH)       13     CO POSITION       14     REV CONSOLE(GROWTH)       13     READAR SET CONTROL CARASET CONSOLE AN/APS-125       10     RADAR SET CONTROL COSTOLE COSTOLE AN/APS-125       11     READAR SET CONTROL COSTOLE COSTOLE AN/APS-125       11     READAR SET CONTROL COSTOLE COSTOLE (INDICATOR COSTOLE)       15     DATA SET CONTROL CONTROL CONSOLE       16     ADDRESS CONTROL CONTROL CONSOLE (SPACE   WEIGHT)       17     VIDEO DECODEC COSTOL CONTROL CONSOLE       18     DATA SET CONTROL CONSOLE (SPACE   WEIGHT)       19     AMR SUMEAPON CONTROL CONSOLE       11     OPERATIONS SUMMARY CONSOLE (SPACE   WEIGHT)       11     OPERATIONS SUMMARY CONSOLE       12     HARPOON WEAPON CONTROL CONSOLE       14     STIR WEAPON CONTROL CONSOLE       15     DATA SET CONTROL CONSOLE       16     DESCRIPTION       17     PARTS AND MATERIAL LIST       18     MARETON MERCONTROL CONSOLE       19     State of Land and the Control of Land and the Co	16 ACOUSTIC DISPLAY CON	JSOLE ANJUYO-()				
12   COMPACT LATA PERCOUL   0A-8337(V)2/UYA-4(V)   2     11   ELECTRONIC WARFARE CONSOLE AN/SLQ-3)   1     10   FRADAR SET CONTROL CONSOLE AN/SLQ-3)   1     11   FRADAR SET CONTROL AN/APS-125   1     2   RADAR SET CONTROL AN/APS-125   1     3   RADAR SET CONTROL CONSOLE OT-104(V)3/VYA-4(V)   (INCLUDING TWO GROWTH)     4   STIR WEAPON CONTROL CONSOLE OT-104(V)3/VYA-4(V)   (INCLUDING TWO GROWTH)     5   DATA SET CONTROL CONSOLE OT-104(V)3/VYA-4(V)   (INCLUDING TWO GROWTH)     4   STIR WEAPON CONTROL CONSOLE (SPACE I WEIGHT)   1     3   MK 92 WEAPON CONTROL CONSOLE   1     4   STIR WEAPON CONTROL CONSOLE   1     2   HAPPOON WEAPON CONTROL CONSOLE   1     1   OPERATIONS SUMMARY CONSOLE   1     1   OPERATIONS SUMMARY CONSOLE   1     1   OPERATIONS SUMMARY CONSOLE   01-197/UYA-4(V)   (GROWTH)     1   OPERATIONS SUMMARY CONSOLE   01-197/UYA-4(V)   (GROWTH)     1   OPERATIONS SUMMARY CONSOLE   01-197/UYA-4(V)   (GROWTH)     2   HAPOON WEAPON CONTROL CONSOLE   01-197/UYA-4(V)   (GROWTH)     1   OPERATIONS SUMMARY CONSOLE   01-197/UYA-4(V)   (GROWTH)     1   OPERATIONS SU	14 RPV CONSOLE (GROWTH	1)				
III   FLECTRONIC WARFARE CONSOLE AN/SLG-31     III   RADAR SET CONTROL AN/APS-125     III   RADAR SET CONTROL AN/APS-125     III   PPI DISPLAY CONSOLE OT-104(V)3/2VXA-4(V)     IIII   PPI DISPLAY CONSOLE OT-104(V)3/2VXA-4(V)     IIII   IIIIIII     IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	12 REMOTE DATA READOUT	0A-8337(V)2/UYA-41	<u>vi</u>		2	
9     RADAR SET CONTROL ANJAPS-125     1       8     PPI DISPLAY CONSOLE     01-194(V)3/UYA-4(V)     (INCLUDING TWO GROWTH)     5       7     VIDEO DECODER     KY-761(P)/UPA-594(A)     4       6     ADDRESS CONTROL INDICATOR C-9062/U     1       5     DATA SET CONTROL CONSOLE (SPACE 1 VEIGHT)     1       3     MK 92 WEAPON CONTROL CONSOLE (SPACE 1 VEIGHT)     1       2     HAPPOON WEAPON CONTROL CONSOLE     1       1     OPERATIONS SUMMARY CONSOLE (OI-197/UYA-Z(V)) (GROWTH)     1       1     OPERATIONS SUMMARY CONSOLE (OI-197/UYA-Z(V)) (GROWTH)     1       PCNO     DESCRIPTION     QTN       CMULA VIETA CALV       MODES S70000       CONTROL CONSOLE       CONTROL CONTROL CONSOLE       CONTROL CONTROL CONSOLE <td co<="" td=""><td>ID RADAR SET CONTROL C-</td><td>CONSOLE AN/SLQ-3</td><td>1</td><td></td><td>1</td></td>	<td>ID RADAR SET CONTROL C-</td> <td>CONSOLE AN/SLQ-3</td> <td>1</td> <td></td> <td>1</td>	ID RADAR SET CONTROL C-	CONSOLE AN/SLQ-3	1		1
7   VIDEO DECODER   KY-761 (P) / UPA-59A(A)   A     6   ADDRESS CONTROL INDICATOR C-9062/USG-59   1     1   DATA SET CONTROL CONSOLE (SPACE 1 WEIGHT)   1     3   MK 92 WEAPON CONTROL CONSOLE (SPACE 1 WEIGHT)   1     1   OPERATIONS SUMMARY CONSOLE (OJ-197/UYA-4 (V) (GROWTH)   0     2   MARK ANGELS   S. RHODES (S/30/8)   ROHR INDUSTRIES, INC.     2   OPERATIONS (OVERATION (OVERATIO	9 RADAR SET CONTROL A 8 PPI DISPLAY CONSOLE	N/APS-125 0J-194(V)3/11YA-4/V	(INCLUDING T	WO GROWTH	5	
S     DATA SET CONTPOL     C-9063/USQ-59       4     STIR WEAPON CONTPOL     CONSOLE       3     MK 92 WEAPON CONTROL     CONSOLE       2     HARPOON WEAPON CONTROL     CONSOLE       1     OPERATIONS SUMMARY CONSOLE     OJ-197/UYA-4 (V)     (GROWTH)       PCNO     DESCRIPTION     OT       PARTS AND MATERIAL LIST     CHULA VISTA CALIF       DER IS NOT MAINTAINED     UNISSIGNEE PECTINO       UNISSIGNEE PECTINO     CHULA VISTA CALIF       CHULA VISTA CALIF     CHULA VIS	7 VIDEO DECODER KY-76	1 (P) / UPA-59A(V)			A	
Image: State of the state o	5 DATA SET CONTROL C-	9063/USQ-59		······································		
I   OPERATIONS SUMMARY CONFICE CONSOLE   I   I     I   OPERATIONS SUMMARY CONSOLE   OJ-197/UYA-4(V)   (GROWTH)   I     DESCRIPTION   OT     PARTS AND MATERIAL LIST   OT       OCK IS NOT MAINTAINED   UNLESS OTHERWISE SPECIFIED     Image: Description   Image: Description   OT       OCK IS NOT MAINTAINED   UNLESS OTHERWISE SPECIFIED   S. RHODES       Image: Description   Image: Description       Image: Descrin   Image: Description	3 MK 92 WEAPON CONTROL	CONSOLE ISPALE WE	IGHT)			
PCNO   DESCRIPTION   QT     PARTS AND MATERIAL LIST   CHULA VIETA. CALL®     DESCRIPTION   CHULA VIETA. CALL®     DIMENSIONE ARE IN INCRESS   S. RHODES     TOLERANCES ON:   DESCRIPTION     DESCRIPTION   CHULA VIETA. CALL®     TOLERANCES ON:   DESCRIPTION     DESCRIPTION   CHULA VIETA. CALL®     TOLERANCES ON:   DESCRIPTION     DESCRIPTION   CHULA VIETA. CALL®     TOLERANCES ON:   DESCRIPTION     DESCRIPTION   Still     TOLERANCES ON:   DESCRIPTION     DESCRIPTION   COMBAT INFORMATION CENTER     X   XX   XX     X   XX   XX     TOTO   CAL #T LIN     MODEL NO:   MAIN DECK     MODEL NO:   MAIN DECK     MODEL NO:   MAIN DECK     MODEL NO:   MAINT DECK     TOTO   CAL #T LIN     INTO   INTER     INTO   INTER     INDUCTING   INTER     INTO   INTER     INTO   INTER     INTO   INTO     INTO   INTO     INTO   INTO     INTO   INTO     INTO   INTO     INTO   INTO <td>C HARPUON WEAPON CONT</td> <td>CONSOLE OJ-1977UYA</td> <td>-4(V) (GROW</td> <td>тн)</td> <td></td>	C HARPUON WEAPON CONT	CONSOLE OJ-1977UYA	-4(V) (GROW	тн)		
Directions   Directions   S. RHODES   S/30/8   ROHR INDUSTRIES, INC.     Directions   Directions   S. RHODES   S/30/8   ROHR INDUSTRIES, INC.     Directions   S. RHODES   S/2/2   COMBAT INFORMATION CENTER     ANGLES   S. S. STOCK   S. S. STOCK   COMBAT INFORMATION CENTER     MOREL NO.   S. S. STOCK   S. S. STOCK   COMBAT INFORMATION CENTER     MOREL NO.   MAIN DECK   S. S. STOCK   MAIN DECK     MOREL NO.   MAIN DECK   S. S. STOCK   S. STOCK     MOREL NO.   MAIN DECK   S. S. STOCK   S. STOCK     MOREL NO.   MAIN DECK   S. S. STOCK   S. STOCK     MOREL NO.   MAIN DECK   S. S. STOCK   S. STOCK     MOREL NO.   MAIN DECK   S. S. STOCK   S. S. STOCK     MOREL NO.   S. S. STOCK   S. S. S. STOCK   S. S	PCNO	DESCR	PIPTION		QTY	
OCK IS NOT MAINTAINED     UNLESS OT MERNISS SPECIFIED     S. RHODES     3/30/8     ROHR INDUSTRIES, INC.       DIRENSIONS ARE IN INCHES     TOLERANCES ON:     5/2/2/2     ROHR INDUSTRIES, INC.       DECIMALS     ANGLES     1/2/2     5/12/2/2     ROHR INDUSTRIES, INC.       DECIMALS     ANGLES     1/2/2     5/12/2/2     ROHR INDUSTRIES, INC.       DECIMALS     ANGLES     1/2/2     5/12/2/2     COMBAT INFORMATION CENTER       X X     XX     XXX     2/2     1/2/2     COMBAT INFORMATION CENTER       X 1     2/00     2/00     2/2     1/2/2     1/2/2     COMBAT INFORMATION CENTER       MODEL NO:     MAIN DECK     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2       MODEL NO:     MAIN DECK     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2     1/2/2<		PARTS AND	MATERIAL LIS	T ?		
Dimensional and the interfere   State of the interfere     December of the interfere   December of the interfere <td>OCK IS NOT MAINTAINED UNLESS OT</td> <td>THERWISE SPECIFIED</td> <td>HODES 3/30/76</td> <td></td> <td>CHULA VISTA, CALIF.</td>	OCK IS NOT MAINTAINED UNLESS OT	THERWISE SPECIFIED	HODES 3/30/76		CHULA VISTA, CALIF.	
DECIMALS   ANGLES     X   XXX     X   XXX <t< td=""><td>TOLERANC</td><td>CES ON:</td><td>5/2/24</td><td>ROHR INDUSTRIES,</td><td>, INC.</td></t<>	TOLERANC	CES ON:	5/2/24	ROHR INDUSTRIES,	, INC.	
ARRANGEMENT   ARRANGEMENT     GENERAL SPECIFICATION   MAIN DECK     MODEL NO.   JUNCLASSIFI     MAIN DECK   MAIN DECK     MODEL NO.   MAIN DECK     MODEL NO.   MAIN DECK     MODEL NO.   MAIN DECK     MODEL NO.   JUNCLASSIFI     MAIN DECK   MAIN DECK     MAIN DECK   MAIN DECK     MAIN DECK   MAIN DECK	DECIMALS .X J.XX	ANGLES	Jilman 5.12.76 (	COMBAT INFORMATI	ONCENTER	
MODEL NO.   MENT PMAL ABSY PMAL ASSY MASY Trom   CAL OT LIB MASY PMAL LAYOUT NO   CAL OT LIB LAYOUT NO   MAIN DECK     MODEL NO.   MENT PMAL ASSY MASY TOM   CAL OT LIB LAYOUT NO   PLI BUL- Striply   SIZE SCALE 1/2 'S''   DWG NO. LL 411001     TOM   OT V REGO   ITCLIAAN- Striply   Striply   SCALE 1/2 'S''   SHEET LOF L B-48	1.1 ± 03 GENERAL SPEC	1 ±.010 ±2" MULLER		ARRANGEME	<u>-</u> NT	
MODEL NO.       MET / MAAL SAL OT V RECO       CAL OT LEB       CAL OT LEB       CAL OT LEB       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       51563       LL 4/1001       CAL OT LEB       CODE (DEAT)       D       CAL OT LEB       CA			-	MAIN DECI	K	
TION OTVASCO LATOUT NO TICCIMUM SUBJECT OF I STATET I OF I Figure B.5-1 (U) UNCLASSIFI B-48	Y MODEL NO. MEXY PINAL CAL WY LOS		Burker 5.7.74	D 51563 4		
Figure B.5-1 (U) UNCLASSIFI B-48	ATION OTY REQU	100	5 (13 1) Sc	ALE1/2'51'		
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P. 475	22 PATCH PALIEL	5-355 27 37 P-3 MAR F 7 5-37207 5KR-	-3	
FWD	21 TELEMETRY P	ECENER P-1039/SKR-3		· 1
	20 DEMODULATOR	MD-8 / / 5/2-3		
	19 URE LOCAL CO	NTROL UNIT C-90597	URC	
SHIP PORT	17 FREQUENCY S	TANDARD AN JURG-23		
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	13 HE RECEIVER	ANZURR-67		
	12 FILTER LP-10			4
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	10 RE SWITCHING	UNIT 54-2000/WSC-	3	
	B TRANSCEIVED	SWITCH 64-1712 / CA		
	7 UHF LOGISAT	COM TPANSCEIVER	RT-1107/WSC-3	ī
	6 ANTENNA C	OUPLER CONTROL C	-3698/URA-38	4
	5 COUPLER ADA	PTER MX-4845/SR		
	3 HE RADIO SE	UNIT 54-10/0/08	3/URC	
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		GRP MGR MFG ENG QA DRB/CCB	SIZE CODE IDENT ND DWG NO 51553 HAVBEA	LB430001

(U) B.6 HULL INSULATION, SHEATHING, AND DECK COVERING SYSTEMS

(U) This section of Appendix B consists of 29 Sheets of Rohr Drawing No.
 LL635001, "Hull Insulation, Sheathing and Deck Covering Systems".
 This drawing describes the cited systems covered in the text in Section 2.3.6.

#### GENERAL NOTES

#### 1. INSULATION

- A. ALL INSULATION MATERIALS INSTALLED SHALL COMPLY WITH APPLICABLE GOVERNMENT SPECIFICATIONS OR SHALL BE EQUIVALENT TO PRODUCTS IDENTIFIED.
- B. IN ADDITION TO THE ABOVE, ALL FIRE, THERMAL AND ACOUS-TICAL INSULATION INSTALLED SHALL SATISFY THE REQUIRE-MENTS OF USCG INCOMBUSTIBILITY TEST 164.009.
- C . FIRE PROTECTIVE INSULATION SHALL BE ALUMINA/SILICA FELT OF FOUR-POUND DENSITY PER CUBIC FOOT (FIBRAFRAX OR EQUAL).
- D. THERMAL INSULATION SHALL BE FACED FIBROUS GLASS CON-FORMING TO MIL-1-742. ALTERNATELY, UNFACED FIBROUS GLASS MIL-1-742 SHEATHED WITH.032 INCH THICK ALUMINUM SHALL BE USED.,
- E. ACOUSTICAL INSULATION SHALL BE ONE-INCH THICK PERFO-RATED HARD SURFACE FIBROUS GLASS ACOUSTIC BOARD CON-FORMING TO MIL-A-2364 AND SHALL SATISFY THE RE-QUIREMENTS OF THE USCG INCOMBUSTIBILITY TEST. ALTER-NATELY ONE-INCH THICK, SOUND-ABSORBING, FIBROUS GLASS FELT MIL-1-22023, TYPE II AND SHEATHED WITH .032 INCH PER-FORATED ALUMINUM, MINIMUM 10% FREE AREA SHALL BE USED.
- F. CLIPS, ANGLE SUPPORTS & STAND-OFFS SHALL BE BONDED TO STRUCTURE TO ACCOMMODATE STANDARD PANEL FASTENER PATTERN (SEE SHEETS 26,27 8.28 ).
- G. PANEL BUTT & CORNER JOINTS SHALL BE SEALED BY COM-PRESSING 6 LB/FT<sup>3</sup> REFRACTORY FIBROUS FELT STRIPS INTO GAPS & COVERING WITH CRES FLASHINGS
- H. DECKS REQUIRING FIRE PROTECTION (GROUP I & GROUP II) SHALL HAVE .25 INCH THICK CERAMIC FIDER MOIST FELT INSULATION BONDED TO THEM, USING A CERAMIC CEMENT. THICKNESS DEFENDS ON FIRE LOADING.
- I. WHERE REQUIRED AS SHOWN ON INSULATION ARRANGEMENT PLANS, FIRE, THERMAL AND ACOUSTICAL INSULATION SHALL BE COMBINED IN VARIOUS THICKNESSES AND FABRICATED INTO S-FOOT WIDE PANELS
- J. THE INSULATION PANELS SHALL BE OF A SANDWICH TYPE CON-STRUCTION CONSISTING OF AN ALUMINUM BACKING SHEET.516 INCH THICK, COMBINATIONS OF FIRE, THERMAL AND ACOUSTICAL INSULATION IN THICKNESSES INDICATED IN LEGEND AND A FACE SHEET AND EDGE CLOSURES AS FOLLOWS:
  - IN MACHINERY SPACES (GROUP I FIRE HAZARD), THE FACE SHEET SHALL BE .012 INCH THICK CRES WITH CRES CHAN-NEL TYPE EDGE CLOSURES.
  - IN AREAS OTHER THAN MACHINERY SPACES **REQUIRING** THERMAL INSULATION OVER FIRE INSULATION. OR ONLY THERMAL INSULATION, THE FACE SHEET **SHALL BE .032** INCH THICK ALUMINUM. ALTERNATELY, THERMAL **INSU-**LATION SHALL BE HARD FACED INSULATION **BOARD** CON-FORMING TO MIL-I-742.
  - IN AREAS REQUIRING ACOUSTICAL INSULATION OVER FIRE
    INSULATION, THE INSULATION SHALL BE HARD SURFACE
    FIBROUS GLASS ACOUSTICAL BOARD CONFORMING TO MIL-A23054. ALTERNATELY, THE INSULATION AND FACE SHEET
    SHALL BE MIL-I-22023, TYPE II, SHEATHED .032 INCH PERFORATED ALUMINUM.

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#### GENERAL NOTES (CONTD)

PANEL LENGTHS 'SHALL BE AS FOLLOWS:

DECK	BULKHEADS	OVERHEAD
OI LEVEL	8'-7" L G	6-0"LG
MAIN DK	<b>7'- 7"</b> LG	<b>6'-0"</b> LG
2 ND D K	7'-7" LG	6'- 0" LG
3RD DK	7'-7" LĠ	<b>6'-0</b> " LG

- 2. EXTENT OF INSULATION
  - A INSULATION SHALL BE FITTED TO UNDERSIDE OF DECKS, BULK-HEADS AND STRUCTURAL MEMBERS AS INDICATED ON INSU-LATION ARRANGEMENT PLANS AND <u>THE FOLLOWING NOTES.</u>
  - B. INSULATION ON THE WARM SIDE OF THE VERTICAL SURFACES BOUNDING UPTAKE ENCLOSURES, MAGAZINES, AND FIRE INSULA-TION SHALL EXTEND FROM THE DECK TO THE OVERHEAD. IN ALL OTHER AREAS, THERMAL INSULATION ON VERTICAL SUR-FACES SHALL EXTEND FROM SIX INCHES ABOVE THE DECK TO THE OVERHEAD.
  - C. INSULATION SHALL NOT BE INSTALLED IN WAY OF SHOWER STALLS OR BUILT-IN FURNITURE, EXCEPT DOWN TO THE DECK AND ALONG THE DECK FOR A WIDTH OF NINE INCHES FROM THE WEATHER BOUNDARY OR TO THE BACK OF SUB-EASE, WHICH-EVER IS LESS.
  - D. WHERE ONLY A PARTIAL AREA OF A BOUNDARY REQUIRES IN-SULATION, THE INSULATION SHALL BE INSTALLED SUCH AS TO EXTEND 12 INCHES BEYOND THE AREA REQUIRING INSULATION.
  - E. BOUNDARIES ABUTTING INSULATED BOUNDARIES WHERE INSU-LATION IS NOT OTHERWISE REQUIRED, SHALL BE INSULATED FOR A DISTANCE OF 12 INCHES FROM SUCH INSULATED BOUNDARIES.

		the second s	
10	LSES PRESERVATIVE & COVERINGS SPEC	51563	L24630001
9	ACTIVE FIRE PROTECTION SYSTEM	51563	LB555001
8	LSES SYSTEM SPECIFICATION	51563	L01000001
7	AIR CONDITIONING, VENTILATION AND HEATING DESIGN CRITERIA MANUAL		0938 - 018 - 0010
6	INLET INSTL-LIFT SYSTEM	51563	LS567020
5	ARR-INTAKE SYS, COMBUSTION AIR P/S	51563	LL251001
4	LEEE GENERAL ARROMT - 3RD DECK	51563	LL802006
3	LSES GENERAL ARRGMT - 2ND DECK	51563	LL802005
2	LSES GENERAL ARRGMT - MAIN DECK	51563	LL802004
	LSES GENERAL ARRGMT - OI LVL & ABOVE	51563	LL802003
NO	TITLE	CODE	MFR OR CONTRINC
	REFERENCES		

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K. UNLESS C REQUIRE SPECIFIEE PLIED 10 REQUIRE

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> (A) PERF ATT GLAS UPON (b.) PERF

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#### GENERAL NOT S (CONT'D)

- 3. INSULATION PROTECTION
  - A INSULATION ON BULKHEADS OF COMMISSARY IN WAY OF HEAT-PRODUCING COMMISSARY EQUIPMENT AND VEGETABLE-PEELING MACHINES SHALL BE SHEATHED, INSULATION ON THE OTHER AREAS ADJACENT TO THESE FIXTURES WHICH MAY BECOME WET OR COATED WITH GREASE OR IN ANY AREA WHERE INSULATION IS SUBJECT TO DAMAGE OR EXPOSED TO HEAVY TRAFFIC. SHALL ALSO BE SHEATHED.

INSULATION BEHIND LAVATORIES, SERVICE SINKS. WATER CLOSETS, AND FOOD PREPARATION TABLES **SHALL** BE SHEATHED FROM THE DECK TO AT LEAST TWO FEET ABOVE THE WORKING SURFACE OF THE FIXTURES

- B. EXPOSED EDGES AROUND AIRPORTS, DOORS AND EXPOSED EDGES IN OTHER LOCATIONS WHERE SUCH EDGES ARE SUBJECT TO DAMAGE SHALL EE PROTECTED BY LIGHT Z OR FLAT BARS.
- C. EXPOSED EDGES OF INSULATION NOT SUBJECT TO DAMAGE SHALL BE PROTECTED WITH FIBROUS GLASS TAPE.
- D. INSULATION IN PASSAGEWAYS AND OTHER AREAS SUBJECT TO HEAVY TRAFFIC, SHALL BE SHEATHED FROM THE DECK TO AT LEAST 36<sup>47</sup>ABOVE THE DECK. SHEATHING SHALL BE CRES.019 AISH TY-304, FIN 4
- E. WHEN ATTACHING CRES SHEATHING IN WAY OF ALUMINUM STRUCTURE, ALL SUPPORT ANGLES AND COAMINGS TO BE INSU-LATED WITH DIELECTRIC TAPE.

#### **4 INSTALLATION**

- A. INSTALLATION PROCEDURE SHALL BE IN ACCORDANCE WITH THIS PLAN.
- 5. REPAIR
  - A WHERE PRACTICABLE, DAMAGED FACED FIBROUS GLASS BOARD SHALL BE COVERED WITH GLASS CLOTH AND CEMENT.
- 6. ANTISWEAT TREATMENT
  - A. ANTISWEAT TREATMENT TO BE APPLIED IN ACCORDANCE WITH PAINT SCHEDULE.
- 7. VAPOR BARRIER
  - A A VAPOR BARRIER COATING CONFORMING TO MIL-C-19993 OR EQUIV SHALL BE APPLIED TO THE EXPOSED SURFACE OF ALL INSULATION WITHIN LAUNDRIES, SCULLERIES, AND GALLEYS. ONE HUNDRED PERCENT COVERAGE SHALL BE PROVIDED BY ANY SINGLE COAT OF VAPOR BARRIER COATING SEE PAINT SCHEDULE FOR APPLICATION.
- 8. PAINTING
  - A STRUCTURE BEHIND HULL INSULATION SHALL NOT BE PAINTED UNLESS IT IS A WEATHER BOUNDARY OR BETWEEN AIR CONDI-TIONED AND NON-AIR CONDITIONED SPACES. SEE PAINT SCHED-ULE FOR FINISH PAINTING OF INSULATION.
  - B. FORWARD SIDE OF FIRE ZONE BULKHEADS SHALL RECEIVE TWO COATS OF THERMAL INSULATING (INTUMESCENT) PAINT, MIL SPEC MIL-C-46081.

#### & DECK COVERING

A. DECK COVERING AN RANGEMENT DRAWU TRATE THE INTEGR WITH THE DECK CO ING SPECIFICATION REGARDING DE'CK C

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- a UNDERLAY PC 20 88 DECK COVERING 15 AND UNDERLAY PC DECK SEAMS ARE T
- C. DECK COVERING SHA ELECTRONIC EQUIMA PANELS SEE DWG I MOUNTED EQUIPMEN

10. ACTIVE FIRE PROTECTION THE ACTIVE FIRE PR ARRANGEMENT DRA TRATE THE INTEGR PROTECTION SYSTEM PLETE INFORMATION SYSTEM

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Figure B.6-1

	CONTINUED	Off	SHEET	NO	5
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		МАТ	ERIA	L IDEN	ITIFICATION LIST		
ITEM NO	DESCRIPTION	QTY		HT-LES	MATERIAL	REF TO	SPECIFICATION
1	1/2" FIRE INSUL 4 LBS/CU FT	47,906	.166	7952	CERAMIC FBRS FELT		CARBORUNDUM FIBER-
2	I' FIRE INSUL 4 LBS/CU FT	15,836 SQ FT	.33 S0 FT	5,226	ERAMIC FBRS FELT		CARBORUNDUM FIBER- FRAX OR EQUIV
<sup>.</sup> 3	LBS/CU FT	37,467 SQ FT	.17 SQ FT	6,369	FIBROUS GLASS FELT		MIL-1-22023 TYPE I CL 5 OR MIL-A-23054
4	I' THERMAL INSUL	5169 SQ FT	1.39 SQ FT	2,016	FACED FIBROUS GLASS BOARD		MIL-1-742
5	2" THERMAL INSUL	2,062 SQ FT	.61 SQ FT	1,258	FACED FIBROUS GLASS BOARD		MIL-1-742
6	OI2 FACE SHEET	48,196 SQ FT	.48 SQ FT	23,134	CRES SH		QG-A-766 TY PE 304 FINISH 2B
7 <sup>.</sup>	OI6 BACK SHEET	8,9.6.7 S. FT	1 23 ISQ FT	20,692	AL_SH		QQ-A-250/8 5052-H32
8	.012" PANEL CLOSURE	82,535 LIN FT	.18 LIN FT	14,856	CRES SH		QQ-A-766 TYPE 304 FINISH 2B
9	54 MIL ACOUSTICAL SHEATHING	3,307 SQ_FT	.87 SQ FT	2,877	LEAD VINYL		SOUND FAB OR EQUIV
10	/2" THERMAL INSUL	2,144 SQ FT	.195 SQ FT	418	FACED FIBROUS GLASS BOARD		MIL-1-742
11	114" FIRE INSUL - DK 15 LBS/CU FT	17, 302 SQ FT	.31 SQ FT	5,364	CERAMIC FIBER MOIST FELT		REFRACTORY PROD CO WRP X AQ OR EQUIV *
12	ADHESIVE	17,302 SQ FT	.10 SQ FT	1,730	CERAMIC		CABORUNDUM QF-180 OR EQUIV
13	CLOTH	17,302 SQ FT	.08 SQ FT	1,384	FIBROUS GLASS		MIL-C-9084 TYPE II CLASS 2
14	RESIN	17,302 SQ FT	.10 SQ FT	1,730	EPOXY RM TEMP CURE		SHELL EPON 934 OR EQUIV
15	DECK TILE	8,815 SQ FT	1.10 SQ FT	9,701	VINYL ASBESTOS		MIL-T-   8830
16	RUG	3,732 SQ FT	.50 SQ FT	1,866	BETA FIBROUS GLASS	С	AROLINA NA RROW FABRIC CO OR EQUIV
17							
18	SLIP RESISTANT	22,624 SQ FT S	.25 50 FT	5,706 <b>E</b>	POXY PLUS AGGREGATE	ľ	MIL-D-23003 TYPE II
19	EPOXY COVERING	1,504 SQ FT	2.88 SQ FT	4,332	SOLVENT FREE POLY-		
20	UNDERLAY 1/8'TO	608 <u>  SC_FT</u>	1.75 * SQ F T	1,064	LATEX MASTIC * MEAN THICKNESS 1/4*	NOTE II	MIL-D-3135 TYPE I
21	UNDERLAY FEATHEREDGE	7,795 50 FT	1.0 * SQ FT	• 7,795	LATEX MASTIC	NOTE	MIL-D-3135 TYPE II
22	BOTTOM CHANNEL	6,922 LN FT	.463 LNFT	3,205	ALUMINUM 1 1 × 24 ×.090		QQ-A-200/8 6061-T6
23	SUPPORT CHANNEL	41,440	1.180	7,459	ALUM IX25XI C .062		QQ-A-200/8 6061-T6
24	SUPPORT CLIP	LN FT	1. 106	1,287	ALUMINUM 1 x.090		00-A-200/5 5086-H111
25	INSULATOR PAD	20,238	.017	344	1/2"FIRE INSULATION 4LBS/CUFT 242X6"LG		CARBORUNDUM FIBER- FRAX OR EQUIV
26	ANGLE <b>2× 3× .062</b>	61922	L.201	1,384	ALUMINUM COMPCOR		QQ-A-200/8 6061-T6
27	• I'x I'x.0235	10,443	LNFT	1,723	D235 CRES		QQ-A-766 TYPE 304 FINISH 2B

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Γ		MAT	ERIAL	IDEN	TIFICATION LIST		-
ITEM NO	DESCRIPTION	QTY	UNIT	HT LES	MATERIAL	REF TO	SPECIFICATION
28	SEALING STRIP 2 1/2 W	43,351 LN FT	.205 LNFT	8,887	.0235 CRES		QQ-A-766 TYPE 3 FINISH 2B
29	RIVET, BLIND	20,238	.0625	1,265	1/8" DIA CRES LO TO SUIT		;
30	ANGLE 4" 4" × .062THK	6,992 LN FT	.32 LN FT	2,215	ALUMINUM COMPCOR		QQ -A -200/8 6061-T6
31							
32	SPACER 38 DIA × 2" LG	20,238	,125	2,530	CERAMIC		
33							
34	CHANNEL I'x 2'x I'	6,922 LN FT	.329 LNFT	2,277	0235 THK CRES		QQ-A-766 TYPE 3 FINISH 2B
35	COAMING	6,922 LN FT	.588 LNFT	4,070	4"× 1/8" AL FLAT BAR		QQ-A-200 <b>/5</b> 5086-H111
36							
37	RIVET BLIND	13,834	0625	865	1/8 DIA CRES LO TO SUIT		
38							
39	DECK INSULATION	6,922 LN FT	.31 LNFT	2,146	CERAMIC FIBER MOIST FELT 1/4"THK × 3-1/4"W		REFRACTORY PROD WRP-X-AQ OR EQU
40							
41	ADHESIVE (RUG)	3,732 SQ FT	.10 SQ FT	373			3-M CO BLUEGLUE OR EQU
42	ADHESIVE (TILE)	9.701 SQ FT	.10 SQ FT	882			MIL-A-21016
43	.032' FACE SHEET (PERFORATED)	2.9,518 SQ FT	.384 SQ FT	11,335	ALUMINUM SHEET		QQ-A-250/8 5052~H32
44	ISOLATION STRIP	28,900	.016	462	RUBBER 1/8 THK		1x 2 2
45		6,922 LN FT	.132 LNFT	914	и и <sub>6</sub> тнк		34 WIDE
46	1/2' FIRE INSULATION 4 LBS/CU FT	43,351 SQ FT	.034 SQ FT	1,474	CERAMIC FIBROUS		CARBORUNDUM FIB
47	.032' FACE SHEET	12,254 SQ FT	.452 SQFT	5,539	ALUMINUM SHEET		QQ-A-250/8 5052-H32
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### <u>LEGEND</u>

#### FIRE HAZARD CATEGORIZATION

SPACES ARE CATEGORIZED THRU [4] ACCORDING TO THE ANTICIPATED FIRE LOADING AND POTENTIAL FIRE HAZARD OF THE SPACE FIRE LOADING IS DEFINED BY THE WEIGHT OF COMBUSTIBLES PER SQUARE FOOT (LBS/ SQ FT), SEE TABLE BELOW,

GROUP	DEGREE OF HAZARD	FIRE LOADING
	HIGH (MCHRY SPACES)	IO LBS/SQ FT
2	Moderate to high	5-10 LBS/SQ FT
3	MODERATE	3-5 LBS/SQ FT'
4	LOW	0-3 LBS/SQ FT

$$\triangle = \text{ACOUSTICAL CATEGORY} - \text{SEE SHEET 7}$$
  
() = THERMAL CATEGORY - SEE REF NO 7

ITEM NO	DECK COVERING	S
15	DECK TILE	₩
16	RUG	
18	SLIP RESISTANT COVERING	
19	EPOXY	

*	E FEFIRE, ASACOU	STICAL, T-1
ITEM	PASSIVE	FIRE P
NO	THICKNESS	MATERIA
1	1/2*	FIRE
2	۱*	INSULA
	.*	ACOUST
э		INSULA
4	1* 8HD	THERM
5	2" OVHD	INSULA
10	II 2 BHD	THFRM
4	IOVHD	INSULAT
		SHEATHI
1&3	** 1/2" F + 1"A	FIRE A
2&3	** I F+I A(MACH SP)	ACOUST
10&3	1/2 T+1 A (BHD)	THERMAL
483	** I″T'+I″A (OVHD)	ACOUST
3&4	** IT+IA(BHD)	THERMAL
3&5	** 2 T+I'A(OVHD)	ACOUST
022	و و و و و و و و و و و و و و و و و و و	LEAD VIN
900	16 LV + 1A	& ACOUST
1,3&9	1/2F+1/16 LV+ 1 A	FIRE
2,3&9	** 1 F+1/16 LV+1 A	AND ACOUS
		SUSPEND
		CEILING
н	1/4"	FIRE

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### SPACE/COMPARTMENT AIRBORNE NOISE CATEGORIE

Z LEVEL		ØT LEVEL		MAIN OECK		2ND DECK		JAD DECK
SPACE/COMP	CATE- GORY	SPACE/COMP	CATE- GORY	SPACE/COMP	CATE GORY	578.0F/034#	CATE- GORY	SPACE/COMP BT
AIRBORNE NOISE LE PILOT HOUSE AIRBORNE NOISE LE NOISE SIL CATEGORY VALUI A3 G4 A12 54 B NOME C NORE D NORE E 72 H SEE WI NOTE 1. THIS CATEGO GAS TURDINE BASIS FOR BASIS FOR ABOVE THRE BASIS FOR MA 2. THE SC VALUE S THE NOISE LI FOR EACH N APPLIES, THE CATAVE BAN THREE BAND	VELS (DI A12 A12 A12 A12 A12 A12 A12 A12 A12 A12	CHART FOOM HANGAR HEAD PASSAGE WAYS FAN ROOM SEA CABIN CENTRAL CONTROL STA RADAR EQUIP RM MELO LANG CONTROL STA FUEL AT SEA STA MACHINE ROOM FUEL AT SEA STA MACHINE ROOM SEA CABIN FUEL AT SEA STA MACHINE ROOM SEA COMMENT SEA COMMENT S	A3 A3 E B D H A3 A12 D E E E H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D E E H H A3 A12 D E E H H A3 A12 D E E H H A3 A12 D E E H H A3 A12 D E E H H A3 A12 D E E H H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D E E E H H A3 A12 D A12 D A12 D A12 D A12 D A12 D A12 D A12 D A12 D A12 D A12 A12 D A12 D A12 A12 D A12 A12 D A12 A12 A12 A12 A12 A12 A12 A12	COMM. CENTER COMM. CENTER CIC RADAR PRCS RODIA AVIATION OFFICE DATA PHOC. CENTER AVIATION WORKSHOP HANGAR PASSAGUWAYS FAN. BOOMS MX 46 TORPEDO MAGAZIME SCNGENDY MAGAZIMI AVIATION STORE- RODIS AGENTIC RODM RADIO XMIR ROOM SUPPLY OFFICE SD ISSUE RODM ELECTBORIC SFARE PARTS STAM SD GENUSTAN TDAS CUNTAOL CTR AVIATION STORE ROOMS ELECTBORIC SFARE PARTS STAM SD GENUSTAN TDAS CUNTAOL CTR AVIATION STORE ROOMS ELECTBORIC SFARE PARTS STAM SD GENUSTAN ELECTBORIC SFARE PARTS STAM SD GENUSTAN SD GENUSTAN ELECTBORIC SFARE PARTS STAM SD GENUSTAN SD GENUST	A3 A12 A3 B A3 B C D U U D D D D D D D D D D D D D D D D	DEPT OF FICE DATA A TECH LIPRARY EXEC OFFICE EXEC OFFICE EXEC OFFICE EXEC OFFICE EXEC OFFICE EXEC OFFICE EXEC OFFICE TO UNGE OF I OUNGE CPO I OUNGE CREW REC. RM COTW MESS RM COLLEY CREW REC. RM COTW MESS RM COLLEY CREW REC. RM COTW MESS RM COLLEY CREW REC. STRM DAY PROV. STRM DASSAGEWAYS CRILL STOREROOM FILL STOREROOM FILL STOREROOM FILL STOREROOM CO BAC RTM OFFICE AS SRS CO BATH CO STRM OFFICE AS SRS CO BATH CO STRM OFFICE AS SRS CO STRM ALY REPAIR TACAS SHIP CATE GEAR RM SEAL APP FA STRM UNASSIGNE O SHIP STORE CREW BAC. FLAX. ELC.STRM ARMONY FWD REPAIR	▲	AIRBORNE NOISE CATEGION ANCHUR WINDLASS RM ANCHUR WINDLASS RM ANCHUR WINDLASS RM ANCHUR WINDLASS RM ELEK GEN RMS PROP. FNG. RMS WATE REF PUMP RMS LIFT FAN ROOMS ROU STATIONS BOW SEAL MACH. RM LAUNDRY ROOM A. CATECORY A. SPACES TION MUST BE UNDER WITHOUT NELD FOR A ARE BASED UN APPROD EITHEN 3 FELT ON 12 WHEN THE EXTREME TA INCOMPANICATION CON EITHEN 3 FELT ON 12 WHEN THE EXTREME TA INCOMPANICATION CON C. CATEGORY B. SPACES THEIA QUARTERS IS T COMMUNICATION IS NOT I IS NOT PROVIDED, AM PRIMARY CONSI <sup>D</sup> UNER MIGH VOCAL EFORT ARC WINEMALLY AVAI A. CATEGORY M. NOISE LEVELS EXCED THE LEVELS EXCED THE LEVELS EXCED THE LEVELS EXCED THE

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Figure B.

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- (U) B.7 COMBAT SYSTEMS ARRANGEMENT DRAWINGS AND BLOCK DIAGRAMS
- (U) This section of Appendix B contains the combat systems arrangement drawings and block diagrams for the near term ANVCE SES. These arrangements are:

#### Figure Title

1

- B.7-1 Radar Processing Room, Main Deck
- B.7-2 Radar Equipment Room, 01 Level
- B.7-3 Electronic Equipment Room, Main Deck
- B.7-4 Mk 46 Torpedo Magazine
- B.7-5 Armament System Functional Block Diagram

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	13	IFF INTEPROSATOR ANJURY-25(V)	2
	12	TACAN TRANSPONDER	1
		TACAN ANTENNA CUNTROL UNIT	1
	10_	MK 140 CONSOLE (SPACE & WEIGHT)	
	9	IFF TEST SET ANJUPM-1376	
	8	WORK BENCH	
		MIN 62 CONSOLE (SPACE ! WEIGHT)	
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#### APPENDIX C

This appendix contains equipment data sheets for the near term SES  $C^3$  system and combat system elements.

Items marked with a  $\diamond$  are part of the C<sup>3</sup> system and those marked with a  $\diamond$  have navigation and IC related functions. All other elements not marked are part of the combat system.

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Weights, size and service requirements are shown for unit elements. The tables show the quantity required for the near term SES.

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Remote Data R/O OA-8337(V)2/UYA-4(V)	<b>45</b>	2					156			CIC	125	11 275	33 836	23 554	T
Intercom Station LS 537A/UYA-4(V)	A 6	3								CIC DPC	27	9 229	19 483	15 381	ſ
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				ELE	CTRI	CAL	POWE	R, W						Manhahara
INSTALLATION DATA					-						•	1		
EQUIPMENT	3S NO.	ΑΝΤΙΤΥ	V-10-60Hz	V-30-60Hz	V-30-60Hz	V-10-400Hz	V-30-400Hz		Ĕ	CATION	WEIGHT	неіснт	WIDTH	
	SWE	σN	115	115	450	115	115	a	ТҮР	го	lbs (N)	in (mm)	in (mm)	
Electrical NAV aids	422 A													
Masthead Light	AI	1	50							MAST	9 40			
Side Lights	42	2	50							PILOT HOUSE	9 40			
Stern Light	۵3	1	50							AFT	10 44			
Towing Lights	۵4	2	50							MAST	12 53			ſ
Task Lights	45	Ģ	450							MAST	13 58			ſ
Wake Lights	26	2	50							MAST	20 89			
Anchor Lights	47	2	50							MAST	8 36			
Speed Light	<u>۵8</u>	1	135		<u> </u>					Mast	20 89			
Blinking Light	49	2	180							AF1	116			
Search Lights	A 10	2	1,000							02 LVL	115 512			
Supply Control & Telltale Panel	۵ ۱۱	1								PILOT House	5C 249			
Supply & Control Panel	A12	1								PILOT HOUSE	34 151			T
Dimmer Panels	A 13	2								PILOT HOUSE	33 147			T
Range Light	۵14	1	50							MAST	2/40			Ţ
·· · · ·														
											1	1		T
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TED	red		COOL	ING	WATI	ER	Нү	′DR	A	IR	
HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	· · · ·
w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
											20 DT Light-White No range it unless 2nd mast installed
											10 pt. lights - green - s red - port
											12 pt light - white
											portable Red - white - red - 32 pt
											Two sets for full coverage
											Gred Bulbs Includes A/C warning It 3 White
											12/305
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				ELE	CTRI	CAL	POWE	ER, W						ليمن من تركيم من المركم من المركم الم
INSTALLATION DATA											۲ ۲			in the second
EQUIPMENT	3S NO.	ANTITY	V-10-60Hz	V-30-60Hz	V-30-60Hz	V-10-400Hz	V-30-400Hz		ň	CATION	WEIGH	HEIGH	MIDTH	DEPTH
	SWE	on	115	115	450	115	115	о С	171	Ę 	lbs (N)	in (mm)	in (mm)	li (m
Helo Landing Lights	422 B													and a star and
Edge Lights (Red) 256.1 256.7	BI	17_	38							LANDING PLATP	18 80			1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 - 1990 -
Lineup Lights (white) 260.1 356.9	82	20	45								16 17			do Mainte
Touchdown Lt (Green) 256.1 256.7	83	1	38								18 80			1.042 m 1.020
Vertrep Lineup Lights (White) 262.1 257.3	B4	15	90								14 62	9 229	6 152	2.5
Vertical Dicopline Lights (Red) 243.1	85	12	100								3 13			がたみ後
Extended lineup Lights (White)	B6	12	45								3			ta ta ta ta
Deck Surface Flooding Lights (Red or White)	87	8	150								15 67			a de la constante de la constan
Maint Flood Light (Red)	<b>B</b> 8	ł	300							ł	15 67			to reists in South
Hier Headine Lights (Red)	89	3	50							07 LVL	5 22			1 Association of the
Signal Wands	810	2									4			والمع وكالإلامات الحلته
Wave off Lights (Red)	вп	2	100							02 LVL	5 22			an a
Overhead Flood Lights (Red)	B12	B	300								15 67			interest of
Landing Signal Light Kit	813	1					•				5 22			1. Same
Homing Beacon (White) 258	B14	3	150								12 53			and a set
Rotary Beacon Signal System (Red Green Amber)	815	3	150								12 53			Contraction of the
DECK STATUS LIGHT (Red, Green, Amber)	B16		150								12 53			
y 4						·								
-														

		6		_					111/		محصب ۱۵	<sub>R</sub> T	
2-1.52 <u>4</u> 443		VTEL	ATEC	C	:00L			к	н ү ————————————————————————————————————				
HIDIH HIMIN	DEPTH	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDP	PRESSURE	FLOW	PRESSURE		
in (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
*													
	•												At least 4 per edge 120/12 XFMR 38W ea. 12V
terte forme													Turn on only 6 at a time
													120/6.5 XFMR 6.5V 45W
6	3										   		120/12 XFMR 38W ea. 12V
													120/6.5 XFMR 6.5V 45W ea.
													115/12 XFMR 100W 13V
													120/6.5 XFMR 6.5V 45W
													28V 120/30 XFMR
											ļ	ļ	
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		<u> </u>											Battery Powered
n Staff, newstrand of the						 					<u> </u>		
201-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-													Battery Powered
eratura a							 				 		115/32 XFMR 150W 32V
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			1	ELE		UAL	POWE	:к, W						
DATA														
			۲z	Ηz	Hz	2H0	ZHO				IGHT	IGHT	ОТН	РТН
	NO.	тітү	10-60	30-60	30-60	10-40	30-40			LION	WE	HE	MIC	DEI
EQUIPMENT	SWBS	JUAN	15V.	15V-:	50V-:	15V-	15V-:	Ŋ	ΥPΕ	OCA	tbs	in	in	in
Stabilized Glide Slope Ind	422	0									(N)	(mm)	(mm)	(mm)
	<u> </u>	1									2224			
Hydraulic Pump Assembly	·¢1	1			2100					HANGAR		28	26	17
Remote Panel Assembly	cz	1								HELO CONTROL STATION		15 381	12	6 152
Stable Platform Assembly	c 3	1								OZ LVL		25	25	28
Glide Slope Indic Assembly									•			13	13	26
Transformer Assembly	<u> </u>									OZ LVL		330 14	330 11	<u>66</u>
	cs									HANGAR		356	279	178
Electronics Encl Assembly	60		960							HANGAR		30 762	24	25
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DEPTH	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	TYPE	FLOW	PRESSURE	TEMP IN	НХДР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	· · ·
n m)	w	w		gpm {cm <sup>3</sup> /s}	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
2 2 8		-										Close to Glide Scope Indic & Platform Self Contained Hydraulics 2.7 A
	·											W/in 8' of Platform Base (914 mm)
4												10760 W total Helo Hq pwr 60 hz
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		·		ELE	CTRI	CAL	POWE	R, W							TED
INSTALLATION DATA															SSIPA
	NO.	ידודץ	10-60Hz	30-60Hz	30-60Hz	-10-400Hz	-30-400Hz			ATION	WEIGHT	неіснт	WIDTH	DEPTH	HEAT DI
EQUIPMENT	SWBS	QUAN	1154.	115V.	450V.	115V	115V	bc	ТҮРЕ	ГОСЛ	lbs (N)	in (mm)	in (mm)	in (mm)	,
Receiver R-1843/WRN-5	423 Al	I	400								150 667	13 330	19 482	30 762	40
Pre Amp AM-6603/WRN-5	A2	1								• • •	13 58	13 330	10	5	
Remote Display IP-1154/U	42		00								5	5	5	11 279	2
Headset H3/ARR-3	<u>Α4</u>	1	10								4				
Antenna CA-3086	A5	1								02 LVL	20 89	46	6.5 165	DIA DIA	
Omega AN/SPN-17	B														
Receiver/Computer OR-133 (V)/URN	BI	1						Ì		CHART ROOM	68 302	12 305	14 356	24 607	
Antenna AS-2960/SRN-17	B2	1									9 40	126	6 152	6 152	
Control Indicator C-9462/SRN-17	вз	1									17 76	14 356	10	9 229	
Interconnecting GP ON-128/WRN	64	,				415					33	10 254	9	11	3
Test Set TS-3389/URN	BS	,					<u> </u>				40	14	19	11	
	1											1,200			1
	1				1										the free described of
Echo Sounding System AN/UGN-4	424 A													†	
Indicator Display 1D-1566/UQN-4	AI	3	100								21 93	۲ 179	10	17	an a
Transmitter/Receiver RT-888/UQN-4	AZ	,	230	1	1	1					195	29	24	20	Technol Jack
Transducer f	<b>A</b> 3										131	8 203	15	DIA	di kanteri
				1			1				1				internet
	1		1	1	1			1			<u>†</u>	†		1	the second second
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DEPTH	HEAT DISSIPAT (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	- FLOW -	PRESSURE	VOLUME/FLOW	
in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (KPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
30 762	400											
5 127			-									
11 279	20											
DIA				1								Studs out to 13" (330 mm) diameter 38.25 (972 mm) max base dia
					1		1		1		1	
24									1			Powered via ON-128
6				{		1						
9				1								Powered via ON-128
11 11 110	220			1	-	1						
11	220									+		Powered via ON-128 420W 60Hz 415W 400Hz Total
<u>4.17</u>	03			-								
	<u>}</u>	<u> </u>		1	1	+	<u> </u>	1	-1	1		
	<b>†</b>				1	1				<u> </u>	1	
17	20	<u> </u>				†				+	-	
+22			<u> </u>	1			<u> </u>	1	+	+	+	
DIA DIA	<u>רן</u>			1			+	<u> </u>	-	+	$\uparrow$	530 W 60Hz
	<b>†</b>		+	-		1				+	1	
New York Commence				1	+	+	<u> </u>	╁──	-		+-	
net korres			+	- <del> </del>	1		+	+				
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ENTRODOMENT	Sauss (VV)	2.2.X.18.2.1.X	1.24 N 34 40 10 1	المتعادين والمعادين	400 / 31 41m	1 1 2 2 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2	() D. K. St. ALMAN	and a subscription of the		11.1.1.1.1.1.	F WIIGHT	1 HEIGHT	FTCHW =	
titrition with the	12.74	an signed and the second							- Land April Williams			t yeseriati Silan	( 1111) 1 1111)	i unun f
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And the interaction to adopt the							34. 621	nur Rater Ba			202) 2333 4773	The second secon	-3-14-	121
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CA HAMAN ANDAND I IN	×.						2		Carl - Landard Control		2/2	575	122	<u>19</u>
7740000077900 X-12224 XXX 1100 PANNON XLONDA PR BR 23	1944   1944   1946   19	- <b>.</b>							-	大王本	1日 1日 1日 1日 1日 1日 1日 1日 1日 1日 1日 1日 1日	(3   <u>222</u>  3	22 55) 12	2) 223 24 24
NCVA times inny R134	54 A		••••••••	n <b>n</b> 1	· · ·		· · · ·	ю	х н.	КТК	1940 40 414	<u> 4</u> (2) 11 12(2)	542 13 554	-124
BYTH ENVILLE RN 2011	6. <u>4</u>			·			-		÷	おてて	344 150 150	44 264	14 221	13.2
Antonia Az 2719	6.6		· •••		-			9-е на н 		931 E. (28 5.1) 831 E. (28 5.1)	244	49	49 1245	37 14a
Funital But NAV Right Conv SWBD	<u>6.1</u>		. s. sa sadara	1. attendent darge g		<b>.</b>		termina de transco	· · · ·	6167 1941	75 321 1620		in the first spectrum	
EM Log (Rimer & Wi)	â	· · · · · · · · · · · · · · · · · · ·	-6 - 6 - 10-20-00	1976 a. e		1 /had daw of us		ne ko		5 K 5 K	<u>40012</u> 281 983			
LLL TA (Russa & Wi)	3	•	• • • • • • • •						aa is si ahadi da		422	·	*****	
Ayn Map Blorau Linn	10	1	Westerformen (Stat. Sping Sa. 19. 2		aver allifoget at de				··· 4:	6 F	30 133			
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999 - 1999 - 2900 (s. 2000) - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 2000 - 200			*****	~~~~ <u>~</u>	*****			[	5- 1 A.M.A	99 mar Maanaa kasaan ing carkan ay gaa yaa ya		*** ****	• • • • • •	

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Sales de la company	TED	TED		:00L	ING V	NATE	ER	НҮ	'DR	A	IR	
	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	TYPE	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
n im)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
5 B1												1 Radar (W 3 Probos) 28 VDC 50 Watts ea.
1	217											2 Sensors on 95 PCT
	300											
4 10	000											
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3	\$495											
3	365											
6	49											
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				ELE	CTRIC									
DATA											L			
FOUIPMENT	S NO.	NTITY	V-10-60Hz	V-30-60Hz	V-30-60Hz	V-10-400Hz	V-30-400Hz		щ	CATION	WEIGHI	HEIGH	WIDTH	DEPTH
	SWB	QUA	115	115/	450'	115	115	DC	ТҮР	ΓO	ibs (N)	in (mm)	in (mm)	in (mm
Integrated C/D Unit	426									CR	30 133		-	and the second se
Radar Beacon (Space & Weight)	12									CR	40 17B			
NAV/CAS Control/Display Panel D/p Ship Cont Console	13										100 445			
Ship Water Speed Sensor SR301(M)	14													
														and the second se
												<u> </u>	<u> </u>	and the second se
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BOLLEN, MINISTER, J. J. Start, S. J. Start, Star							<u> </u>	 	 					
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		red	LED	(	COOL	ING V	NATE	R	ΗΥ	DR	A	R	
WIDTH	DEPTH	HEAT DISSIPA1 (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	ν <b>ε</b> .
In (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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INSTALLATION DATA						N					ł۲	łТ	<b>-</b>	Ŧ	DISSIPA'
FOLLIDMENT	s no.	NTITY	-10-60Hz	-30-60Hz	-30-60Hz	-10-400H	-30-400H			ATION	WEIGH	HEIGH	WIDTH	DEPTI	HEAT
	SWB:	QUA	115V	115V	450\	115\	115V	ğ	ТҮР	гос	lbs (N)	in (mm)	in (mm)	in (mm)	w
Inertial Nav System Gyro Type II (Space & Wt.)	427 Al						500			CHART RM	2B0 1245		•		300
Telephone Systems	432 A														
System Center Equipment	A1	1								SHIP ENTERTAINMENT ROOM	558 2482	י י 8ררו	24 610	27 686	
Diat Terminal Non W/T	A2	129								DIST	15 67	13 330	13 330	7 178	
Loud Speaker Ext	A3	29	25							DIST	10 45	12 305	10 254	8 203	
Handset	Δ4	90								DIST	1 4.5	11 279	4	5 127	
Headset	A5	80								DIST					
Speaker Phone (2-way)	A6	10								DIST					
Loudspeaker (1-way)	A7	10								DIST					
Extensions	AB	10								DIST					
					•										
·	<u> </u>														<b> </b>
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## UNCLASSIFIED HEAT DISSIPATED (WATER) AIR **COOLING WATER** HYDR VOLUME/FLOW PRESSURE PRESSURE PRESSURE TEMP IN FLOW FLOW НХDР ТҮРЕ gpm cm<sup>3</sup>/s ft<sup>3</sup>/mir psig gpm psi psi psi (cm<sup>3</sup>/s) °c NOTES W W (kPa) (kPa) (kPa) (kPa) m3/s 00 With Holder . • • 1000 $\sim$

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				ELE	CTRI	CAL	POW	ER, W	ι.					
INSTALLATION DATA														
EQUIPMENT	3S NO.	ANTITY	V-10-60Hz	V-30-60Hz	V-30-60Hz	V-10-400Hz	V-30-400Hz		ω	ATION	WEIGHT	НЕІСНТ	WIDTH	DEPTH
	SWE	on	115	115	450	115	115/	ä	ТҮР	Loc	ibs (N)	in (mm)	in (mm)	in (mm)
Announcing Systems	433 A													
Ampl OSC AN/S1A-123	AI	1	860							SHIP ENTERTAINMENT ROOM	270 1201	51 1295	20 508	13 330
Microphone Cont	<u>^2</u>	2									15 67	12 305	10 254	6 152
Loudspeaker LS-305/SIC	A3	90									7 31			
Loudspeaker LS-387/STC	Λ4	24									30 133			
Entertainment and Training Systems	434 A													
T.V. Entertainment	AI													
Control Site 1-1	A1.1	1	2000							SHIP ENTERTAINMENT ROOM	1300 5762	70	44	23 584
Uniplexor Site 1 - 3	A1.2	1									600	60	59	22
Color TV Revr	A1.3	5									90 400	22 559	25 635	21
VHF Dist Net	A1.4	1									50 222			
Audio Ent.	A2													
AM Revr	A2.1	1								SHIP ENTER TAINMENT ROOM	50 222			
System AN/SIN-7	A2.2	)	1100								415	66	7 <sup>1</sup> 533	14
Loudspeaker LS-444/WIH	A2.3	25									15 67	14	14 3560	8
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<b>7</b> <b>1</b>	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХДР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW				
n :m)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES			
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					ELE	CTRI	CAL	POWE	R, W						
iner s	DATA										i	-	4		
		NO.	тітү	10-60Hz	30-60Hz	30-60Hz	10-400Hz	30-400Hz			TION	WEIGH	HEIGH	WIDTH	
	EQUIPMENT	SWBS	QUAN	115V-1	115V-3	450V-3	115V-	115V-3	DC	ТҮРЕ	госа	tbs (N)	in (mm)	in (mm)	i (n
$\Diamond$	Alarm, Safety & Warning System	436 A													
$\diamond$	Indic, Order & Metering System	437 A													
$\diamond$	Integ Cont System	438 A													
$\Diamond$	Recording & TV System	439 A											 		
	An/UNQ-8 Recorder	AI										400			-
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HEAT DISSIPA	HEAT DISSIPA	TYPE	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
n) W	w	 	gµm (cm <sup>3</sup> )	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /mir m <sup>3</sup> /s	NOTES
				-							Ship Control System
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$\backslash$				ELE	CTRI	CAL	POW	ER, W					
INSTALLATION DATA											<b>—</b>	-	
EQUIPMENT	/BS NO.	JANTITY	5V-10-60Hz	5V-30-60Hz	0V-30-60Hz	5V-10-400Hz	5V-30-400Hz		PE	CATION	MEIGH	HEIGH	WIDTH
Radio Systems	<u>5</u>	<u>ਰ</u>	=	11	45	=	11	ă	7		lbs (N)	in (mm)	in (mn
HF XCVR GP	A									XMTR RM			
HF Radio Set AN/URC-81	AI	5				300	3000			RADIO XMTR BM	140 623		
HF Radio Set Cont C-9058/URC	A2	8								2 RADIO XMTR RM 4 COMM	75 334		
RF SW Unit SA-1070/UR	A3	1								RADIO XMTR RM	130 578		
XMTR Matrix Cont C-4787/SRA-34	Δ4	1								RADIO XMTR RM	60 267		
XMTR Temp Alarm	AS	1								COMM	29		
Dummy Load DA-242A/U	A6	l								RADIO XMTR RM	35 156	11 279	ד ורו
Coupler Adapter MX-4845/SR	A7	1								RADIO XMTE EM	75 334		
Broad Band Antenna 2-4MH <sub>2</sub>	AB	ł								OI LVL	120	35	f+ м
Broadband Ant 4-10MHZ	A٩	1								01 LVL	120 534	35 10.7	ft M
Broadband Ant 10-30MHZ	AID	1								OI LYL	120 534	35	ft M
Cabinet CY-()	A11	2								RADIO XMTR RM	275		
Multicoupler 2-6MH <sub>2</sub> CU-1179	A12	I									75 334		
Multicoupler 4-12MH <sub>2</sub> CU-1180	A13	1								RADIO XMTR RM	75 334		
Multicoupler 10-30MHz CU-1181	A14.	1									75 334		
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	INSTAL LATION DATA EQUIPMENT Radio Systems HF XCVR GP HF Radio Set AN/URC-81 HF Radio Set Cont C-9058/URC RF SW Unit SA-1070/UR XMTR Matrix Cont C-4787/SRA-34 XMTR Temp Alarm Dummy Load DA-242A/U Coupler Adapter MX-4845/SR Broad Band Antenna 2-4MH <sub>2</sub> Broadband Ant 4-10MHZ Broadband Ant 4-10MHZ Eroadband Ant 10-30MHZ Cabinet CY-() Multicoupler 2-6MH <sub>2</sub> CU-1179 Multicoupler 10-30MHz CU-1181	INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         INSTALLATION DATA         Redio Systems HF XCVR GP         AH         HF Radio Set AN/URC-81         AN/URC-81         HF Radio Set Cont C-9058/URC         C-9058/URC         RF SW Unit SA-1070/UR         XMTR Matrix Cont C-4787/SRA-34         A4         XMTR Temp Alarm         A5         Dummy Load DA-242A/U         A6         Coupler Adapter MX-4845/SR         MX-8845/SR         Broad Band Antenna 2-4MH2         A6         Broadband Ant 4-10MHZ         A9         Broadband Ant 10-30MHZ         Cabinet CY-()         A11         Multicoupler 10-30MHz         CU-1181         A14	INSTALLATION DATA EQUIPMENT S S S C Padio Systems HF Radio Set ANURC-81 HF Radio Set ANURC-81 HF Radio Set Cont C-9058/URC A2 B HF Radio Set Cont C-9058/URC A2 B H H H H H H H H H H H H H	INSTALLATION DATA EQUIPMENT Redio Systems HF Radio Set AN/URC-81 HF Radio Set AN/URC-81 HF Radio Set Cont C-9058/URC A2 RF SW Unit SA-1070/UR XMTR Matrix Cont C-4787/SRA-34 XMTR Temp Alarm Dummy Load DA-2422A/U A6 I Coupler Adapter MX-4845/SR A7 I Broad Band Antenna 2-4MH <sub>2</sub> Broadband Ant 4-10MHZ AB I Cabinet CY-(1) Multicoupler 2-6MH <sub>2</sub> CU-1179 A12 I Multicoupler 10-30MHZ A13 I Multicoupler 10-30MHZ A14 I Multicoupler 10-30MHZ A14 I A14 I A14 I A14 I A15 I A15 I A16 I A17 I A17 I A17 I A18 I A18 I A19 I A19 I A10 I A10 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A11 I A	INSTALLATION DATA       No.       H.         EQUIPMENT       S       S       S         Radio Systems       44/       A       S       S         HF Radio Set ANURC-81       A1       5       S       S         HF Radio Set ANURC-81       A1       5       S       S         HF Radio Set Cont C-9058/URC       A2       8       S       S         RF SW Unit SA-1070/UR       A3       1       S       S         XMTR Matrix Cont C-4787/SRA-34       A4       1       S       S         Dummy Load DA-2422/U       A6       1       S       S       S         Broadband Antenna 2-4MH2       A8       1       S       S       S         Broadband Ant 4-10MHZ M12       A9       1       S       S       S         Broadband Ant 4-10MHZ M-10-30MHZ CU-1179       A11       2       S       S         Multicoupler 2-50MH2 CU-1181       A13       1       S       S         Multicoupler 10-30MH2 CU-1181       A13       1       S       S         Multicoupler 10-30MH2 CU-1181       A14       1       S       S	INSTALLATION DATA         A         ELECTRI           INSTALLATION DATA         A         I         I           EQUIPMENT         S         S         S         S           Radio Systems         44/ HF XCH GP         A         I         S         I           HF Radio Set AN/URC-81         A1         S         I         I         I           MF Radio Set AN/URC-81         A1         S         I         I         I           MF Radio Set AN/URC-81         A1         S         I         I         I           MF Radio Set Cont C-9086/URC         A2         8         I         I         I           XMTR Matrix Cont C-4787/SRA-34         A4         I         I         I         I           Dummy Load DA-242A/U         A6         I         I         I         I         I           BroadBand Antenna 2-4MH2         AB         I         I         I         I         I           BroadBand Ant 10-30MHZ         A1D         I         I         I         I         I           Multicoupler 2-6MH2         A12         I         I         I         I         I           Multicoupler 10-30MH2         A12	INSTALLATION DATA         Image: Construction of the second s	INSTALLATION DATA         N         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H         H	INSTALLATION DATA         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N	INSTALLATION DATA         Image: Construct of the system         Image: Construct of	INSTALLATION DATA         Image: Construction of the second s	ELECTRICAL POWER, W           INSTALLATION DATA         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N         N	INSTALLATION DATA         ELECTRICAL POWER, W           INSTALLATION DATA         Image: Construction of the second o

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DEPTH	HEAT DISSIPATI (AIR)	HEAT DISSIPATI (WATER)	YPE	FLOW	PRESSURE	TEMP IN	HXDP	PRESSURE	FLOW	PRESSURE	OLUME/FLOW	
in ((mm)	w	w	<del>   </del>	gpm (cm <sup>3</sup> /s)	<del>psi</del> (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	> ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
	2300									·····		2 Local
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$\[b]{}$					ELE	CTRI	CAL	POWE	R, W						
	INSTALLATION DATA						Ν	N				Ŧ	ΗT		
		s no.	ΝΤΙΤΥ	-10-60Hz	-30-60Hz	/-30-60Hz	/-10-400Hz	/-30-400H <sub>1</sub>		٤IJ	ATION	WEIGH	HEIGF	WIDTH	DEPT
		SWB	aua	115V	115/	450\	115/	115/	ğ	ТҮР	гос	lbs (N)	in (mm)	in (mm)	in (mm)
	HF Radio KCVR GP	в						2400			RADIO				
	HF RCVR AN/URR-67	ві	4									75 334			
	RCVR Multiplxr Collins 512J2	82	1									39 175			
	Term Box J-3152/SRC	вз	1									50 222			
	Ant Whip AS-2537A/SR	B4	2								Y	120 534			-
	Local Cont Unit C-9058/URC	85	5								I RADIO XMTR RM 4 COMM	4 18			
	Filter LP-101C	B6	4								RADIO XMTR RM	275			
	Eqpt CAB CY-( ) 6518	87	1												
	651-5	88	1								V				
Ĺ	UHF Radio XCVR GP	с					·								
	UHF XCVR AN/URC-82	c1	6					600			RADIO XMTR RM	50			
	Local Cont Unit C-9059/URC	cz	9								I R XMTR R 4 COMM I CIC I PH	M 75 334			
	Remote XFR SWBD SB-1039/SRI	C3	1					<u> </u>			RADIO XMTR RM	19 85			1.000 E.000 E. 10.000 E.000 E. 10.000 E.000 E.
	Bandpass Filter F-1332/UR	C4	6				150					24 107	18 457	4 102	21 533
	UHF Multicplr TD-1046/URC	C5	2								V	150 667			
	UHF Antenna AS-1735/SRC	60	2								BELOW 108.5 fr 33.1 U PLATE	25	28 71	30 762	30 769
	Eqpt CAB CY-11	c7	3								RADIO KMTR RM	275 1223			New Market
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T WIDTH	DEPTH	HEAT DISSIP/ (AIR)	HEAT DISSIP/ (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in mm	in ) (mn	1) W	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
falle Extension		1000	1000	FW	1.5 94.6								
2 7 7													
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244													
• 		600											
		28											Helo Comt Sta - 1
4 22	21 533	150									-+		· · ·
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62	762												
-								-+					
											-+		
	M										1	<u>ک</u>	INCLASSIFIED 2 C-16

						UN	<u>CL/</u>	<b>ASS</b>	SIFI	ED				
					ELE	CTRI	CAL	POWE	ER, W					
	DATA	Ċ	τY	60Hz	60Hz	60Hz	400Hz	400Hz			NO	VEIGHT	неіснт	NIDTH
	EQUIPMENT	SWBS NO	QUANTI	115V-10-	115V-30-	450V-30-	115V-10	115V-30	DC	ТҮРЕ	LOCATI	lbs (N)	in (mm)	in (mm)
$\diamond$	UHF LOS/SATCOM XCVR Group	۵												
	UHF LOS/SATCOM XCVR RT-1107/WSC-3	DI	1	1500							XMTR RM	148 658		
	Control Indic. C-9351/WSC-3	DZ	1								Comm	3 13	6 152	8 203
	XCVR SW SA-1712/UR	D3	1								EADIO XMTE EM	4		
	RF SW Unit SA-2000/WSC	D4	1			396			 		KADIO XMTR RM	130 578		
	Ant Control C-3597/WSC-1	05	1				3				XMTE RM	80		
	Ampl Filter AS-6691/WSC-1	D6	2								OZ LVL	125 556	23 584	15 381
Y	Antenna AS-1018/URC (Mod)	107	1					ļ			93'-6" PLTF 208.5 IN	50 222	73	14 356
	Antenna AS-3018/WSC-1	128	2	250			 				02 LVL	325	54 <u>1372</u>	1270
	Interconnect Group ON-143(V)/USQ	P9	1	265							Comm	267		
	Recorder - Repro RD-396/U	Dio	1	265							20111	182		
	Recorder - Repro RD-397/U	DII	1			ļ					comm	41		
	Control Panel	D12	1	 							comm	75		
	Equipment Cabinot	D13	1			ļ					RTR	275		
	Computer AN/UYK-20	D 14		1000							comm	979		
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and all stores	TED	TED		COOL	.ING	WAT	ER	н	/DR		IR	
	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХДР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
	w	w		gpm {cm <sup>3</sup> /s}	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /mir m <sup>3</sup> /s	NOTES
Assessed as				ļ								
o de la constante	1100											
	40											
tilia di subbi	396											
all al state d	3											
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				EĻE	CTRI	CAL	POWI	ER, W						
INSTALLATION DATA					•							has		
EQUIPMENT	S NO.	NTITY	/-10-60Hz	/-30-60Hz	/-30-60Hz	V-10-400Hz	V-30-400Hz		ш	ATION	WEIGH.	HEIGH	WIDTH	DEPTH
	Swe	ση	115	115/	450	115	115	ğ	ТҮР	ГО	ibs (N)	in (mm)	in (mm)	in (mm)
UHF SATCOM BCST RCVRGP	E													and a fattered
Comb - Modulator MD - 900/SSR-1	E)	1	65							comm	84 373			tadi kini antikina
RF AMP AM-6334-SSR-1	E2	4								02 LUL	12 53	8 203	12 305	9 22 <b>9</b>
Antenna AS-2815/SSR-1	E3	4								02 LVL	13 58	36 914	31 787	31 787
Demultiplexer TD-1063/SSR-1	E4	1	24							Comm	72 320			
Fault Alarm IC/BSIA	65	}									B 36			
										-				
UHF Tel Data Gp (Helo)	F													
Telem Rcvr R·1893/SKR·3A	FI	1	1100							RADIO XMTR RM	465 2068	36 914	24 610	27 686
Ampl AM-6663/SKR-3A	F2	1								comm	2	2	5 127	3 76
Monitor Panel ID-1949/SKR-3A	F3	1								Comm	6 27	8 703	6	22 559
Demod MD-912/SKR-3A	F4	I								RADIO XMTR RM	350 1557	36	24	27
Test Set TS-3335/SKR-3A	F5	1	100							RADIO XMTR RM	15	19	12	12
RF AMPL AM 64 93/SKR3	FG	1								Mast	14			
Antenna AS-2743/SKR-3A	F7	1									3	19 483	3 76	
Test Antenna AS-2893/SKR-3A	F8	,									3	19 483	3 DIA 76	
Patch Panel Matrix SB-3721/SKR-3A	F9	1	1050							RTR	450	79	48 1219	8 203
Patch Panel Matrix SB-3720/SKR-3A	FID	)								RTR	20 89	11 279	10 254	10 254

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	TED	TED		COOL	ING	WATE	ER	Н	/DR	A	IR	
	HEAT DISSIPA (AIR)	HEAT DISSIPA' (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХБР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in Im	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpin cin <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
i Branchart	65											
2211												· · · · · · · · · · · · · · · · · · ·
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INSTALLATION DATA													4	
EQUIPMENT	VBS NO.	JANTITY	5V-10-60Hz	5V-30-60Hz	0V-30-60Hz	5V-10-400Hz	5V-30-400Hz	0	PE	DCATION	WEIGHT	HEIGHT	WIDTH	DEPTH
VHF Bridge-to-Bridge	SV	ă		1	45	11		ă	7		Ibs (N)	in (mm)	in (mm)	in: (mn
Group	G													
Transceiver, VHF AN/URC-80	GI	1				50				HOUSE	133	152	9 229	45
Control C-8980/URC	G2	1								PILOT HOUSE	3 13			
Antenna AS-2809/SRC	<b>G</b> 3	2									7. 31			
Transceiver, VHF AN/URC-86	<b>G</b> 4	1				50				PILOT HOUSE	40 178			
Wideband Secure Voice Group	н											 		
Secure Voice SW SA-2112(V)/STQ	Н	1								comm	60	12	19	12
Ampi Speaker AN-4453/U	H2	6								1 COMMA BEIG	21	8	13	9
Sec Tel Set TA-840/U	нз	ى								I HCS I COMM BEIE I RH	4	203	220	22
Plain Cipher SW SA-1711/UR	н4	2			•					Lonn	4			
Interconnect Box J-2910/UR	н5	2								Compl	2			
RCS Remote Channel Sei	Н6	10		*****		•				Comm				1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.
Analog - Digital Model CV-3333	HЛ	1												
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Signal Conditioning	J													tool Hickory
Telegraph Signal Converter CV-2460/SGC	21	2	20 40							Comm	25 111			and the second se
Telegraph Conv/Comparator AN/URA-170	<b>J</b> 2	1	70							Comm	65			iteraturi u
Telegraph Mux Terminal AN/UCC-1D(V)	<b>J</b> 3	l	154								144			
Telegraph MUX Terminal AN/UCC-1D T/R	J4	١	154			· · ·				C DMM	144			
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DEPTH	HEAT DISSIPAT	HEAT DISSIPAT	(WALER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХДР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in (mm)	w	W			gpm cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	(t <sup>3</sup> /mir m <sup>3</sup> /s	NOTES
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CHASSINED ELECTRICAL POWER, W INSTALLATION DATA HEIGHT WEIGHT DEPTH 115V-10-400Hz 115V-30-400Hz WIDTH 450V-30-60Hz 115V-10-60Hz 115V-30-60Hz LOCATION QUANTITY SWBS NO. TYPE EQUIPMENT 20 in in in lbs (N) (mm) (mm) (៣ភេ) Miscellaneous K 74 XMTR XFR SWBD COMM SB-2744/SRT(Mod) 329 3 KI 44 Revr XFR SWBD COMM SB-2727/SRR 196 62 3 Low Level DC XFR SWBD 44 COMM SB-2727/SRR/Mod) 196 3 К3 75 Low Level Power Supply COMM (±6VDC) OP-94S 334 3 K4 50 Low Level Power COMM 222 Dist PNI К5 3 XFR SWBD 1 COMM SB-3195/U 49 ł 46 XFR SWBD 19 COMM SB-1039 85 K٦ I. 23 Freq Std Amecon, COMM CTFS K٩ ł 15 102 16 **RF Dist Amp 1** COMM AM-2123A/U 59 71 t 100 -3 Alarm, Freq Std COMM 13 610 1 100 **Guard Rcvr** COMM KII ł 445 Antenna 120 CA-1128-1 K12 ł 534 Audio Ampl/Spkr 21 COMM AM-4453/U K13 3 93 Time Stamp 2 COMM **NA-18BG** KIA ł 9 Duplicator 60 COMM E-141U KI5 1 267 AM Ampl 30 COMM AM-6694/SR KIG 133 ſ -. · ø

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DEPTH	HEALT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (k Pa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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INSTALLATION DATA	Ń.	<b>ΙΤΥ</b>	0-60Hz	0-60Hz	0-60Hz	0-400Hz	0-400Hz			NOL	WEIGHT	НЕІСНТ	WIDTH	DEPTH
EQUIPMENT	SWBS N	QUANT	115V-10	115V-30	450V-3	115V-1	115V-3	СС	ТҮРЕ	LOCAT	tbs (N)	in (mm)	in (mm)	in (mm
Eqpt Cabinet	K17	10								сомм	275 1223			a description of the second
CW Keyer SB-315/U	K18	1								сомм				and the set
Radio Relay Cont C-4621/SR	K19	1								сомм	6 27			and the second
Switch SA-734/SG	K20	3								сомм	4			
Indicator ID-866/SG	K21	3												actives, is the
Antenna AS-3025/SRG	K22	1												and the fraction
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MF RCVR GP	L								1					
LF/MF RCVR AN/WRR-3B	LI	(	60		·					RADIO XMTR RM	70 311		1	
Antenna Group AN/SQA-17D	12	1									50			and
Filter AN/SRA-12B	13	1										1		
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	рертн	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
- 2	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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INSTALLATION DATA														
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	NO.	лттү	10-60Hz	30-60Hz	30-60Hz	10-400H	30-400H			TION	MEIG	HEIG	WIDT	DEPT
EQUIPMENT	SWBS	QUAN	115V-	115V-:	450V-	115V-	115V-	ğ	ТУРЕ	гось	lbs (N)	in (mm)	in (mm)	in (mm)
Underwater Systems	442													
UW Tel GP AN/WQL-2	A													
Revr - XMTR RT-876/WQC-2	AI	1	3450							SONAR	345 1535	59 1499	19 483	21 533
Comm Set C-7440/WQC-2	A2	1								c1C	10 45	B 203	14 356	10 254
Comm Set C-7441/WQC-2	A3	1								PILOT HSE	6 27	8 203	9 229	8 203
XDCR TR-232/WQC-2	۸4	1								SIDEWALL	440	13 330	22 559	DIA
XDCR TR-233/WQC-2	AS	1								SIDEWALL	100 445	18 457	12 305	DIA
										-				
Visual & Audible Gp	443													
Signal Flags	A	1								02 LVL	150			
Whistle	в	1								PILOT HSE	50 222			
Signal Search Lights (12")	c	2								02 LYL	25 111			
Teletype Eqt	445 A													
Teleprinter TT-624/UG	AI	1	350							COMM	265			
Teletype Set AN/UGC-48A	A2	3	240								267	39 991	36 914	24
Teletype Set AN/UGC-77	A3	,	80								52 231			
PAGE PRINTER AN/UGR-9	A4	2	120								40	10 254	17	12
PAGEPRINTER SET AN/UGR-10	A.5	,	375								576	72 1829	22	28 711
PERFORATOR TI-605/UG	AG	1	27								46 205	11	17	30
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	DEPTH	HEAT DISSIPA1 (AIR)	HEAT DISSIPA1 (WATER)	ТҮРЕ	FLOW .	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in im)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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EQUIPMENT	WBS	UAN	15V-	154	50V.	154.	15V.	ا ي ا	ΥPE	000	lbs	in	in	in
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Security Equipment TSEC/KG-36-4	446 AI	1						<u> </u>		comm	27			
TSEC/KY-8						[ '				comm	73 352			
KYB-G/TSEC	12	~								comm	36			11 and 12
11/0 0/7050 D 6		<u> </u>		[]	<b> </b>	'	<u> </u> '	<b> </b> '	<u>}</u> !	_	37			
HYP-2/13EU F.S.	43	2	130		<u> </u>	<b> </b> '	<b> </b> '	<b> </b> '	<u> '</u>	Comm	165			
TSEC/KWR-37	4	2	320		<u> </u> !	ļ'	ļ'	<sup>!</sup>	ļ!	Comm	663			
TSEC/KG-14	45	4	100							Comm	130 578			
TSEC/KW-7	46	4	85							Comm	74 329			
Plant Adapter KWX-11/TSEC	A7	4								comm	20 89			
Remote Fitn KWX-8/TSEC	84	3								Comm	3	5 127	ד 178	152
TSEC/KL-47	49	4	200							Comm	30			
TSEC/HL-1B	A10	1	350							Comm	50 222			
Security Equipment TSEC/KG-40	A 1)	1				60				cic	37	10 254	9 229	22 559
Remote Control KGX-40/TSEC	A 12	1								cic	4	5 127	G 152	8
Security Equipment OK-313(V)SC CSS	413	1								Comm				
Type 8 Safe	<b>Δ</b> 14	1								Comm	175 778			
Int Comp KIR-1A/TSEC	A15	2												
Trans Comp KIT-1A/TSEC	A16													
Crypto Key KIK-18/TSEC	417	1									1	<b> </b>		
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		ÊŪ	ED	C	COOL	ING V	VATE	R	ΗY	DR	A	R	· · ·
WIDTH	DEPTH	HEAT DISSIPAT (AIR)	HEAT DISSIPAT (WATER)	гүре	FLOW	PRESSURE	TEMP IN	НХDP	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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INSTALLATION DATA															ISSIPA
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EQUIPMENT	BS NO	TITNA	5V-10-6	5V-30-6	0V-30-(	5V-10-	5V-30-	Ö	/PE	DCATIO	> 		> 		r
	SW	б	1	11	45	<u>د</u>		<u> </u>	÷	<u>ت</u>	(N)	(mm)	(mm)	(mm)	W
Surveillance System (Surface)	450														
Surf Search Radar AN/SPS-55	451										10.5	0.7	70	1.0	
Antenna Assembly OE-172/SPS-55	٢	1								83'6" (25.5m) PLTF	867	686	18 1981	457	
Antenna AS-2953/SPS-55	1.1	1								PLTF	195				an a litter and
Antenna Pedestal AB-124/SPS-55	1.2									83-6"(25,5m <u>PLTF</u>	195 867				100 ALMAN
RADAR SET CONTROL C-9447/SPS-55	2	1								cic	25	16	19 483	178	3
Rcvr - Transmitter 1124/SPS-55	3	1	1150							Radar Eqpt FM	560 5491	73 1854	29 737	26	51
Safety SW SA-1963/SPS-55	4	1								83'-6' (255m) PLTF	5 22	7 178	7 178	5 127	and the star
Sync. Amp MK 27-8	5	1								Radar Egpt RM	65 289	15 381	20 508	10 254	3
					1										hand takanan
Air Search Radar AN/APA-171 -	452						28 Ku				6000 26.7	JAN N	SL Y	17	6
Antenna Group AN/APA-171	1	,								Pole Nast	3800 169k	10.7	24.5	DIA	ik o zaberad
Radar Set AN/APA-125	2	1								RADAR EQPT RM					a di manana di Katalan di Kata
Radar Control Panel	3	Ι,								CIC	7.5	11	6	6 152	i de transferio de la constante de la constante La constante de la constante de
Perf Monit AN/ASM-440	4	1							1	Radar Erpt Ran					Shirk and
Liquid Cooling Hx	5	   								Rodar Eart RM	1				and while the
Electric Cooling Subsystem	6	,			1					RODAR EGPT RM	1			·	il and a second
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DEPTH	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	TYPE	FLOW	PRESSURE	TEMP IN	нхрр	PRESSURE .	MOTE	PRESSURE	VOLUME/FLOW	
in nm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi {kPa}	ít <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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ELECTRICAL POWER, W INSTALLATION DATA WEIGHT HEIGHT DEPTH WIDTH 115V-30-400Hz 115V-10-400Hz 450V-30-60Hz 115V-10-60Hz 115V-30-60Hz LOCATION QUANTITY SWBS NO. EQUIPMENT TYPE 20 in in in lbs (N) (mm) (mm) (mm)Ident Syst (IFF) 455 23 27 63 500 Interrogator EER AN/UPX-25(V) 2 850 686 2224 1600 584 1 19 15 15 99 Transponder EER 2 483 AN/UPX-28(V) 381 2 300 381 440 1 93'-6" (28.5m) 7 7 7 20 Antenna AS-1778/UPX 179 3 179 508 4 PLTF 31 23 32 2 Z 190 **Test Set** 2 EER 285 AN/UPM-137A 559 4 845 584 813 12 8 10 8 **Control Monitor** 17 EER C-8430/UPX 2 5 34 53 203 254 203 **Decoder Group** 32 AN/UPA-59A (V) 3 75 CIC 6 142 12 6 17 32 Video Decoder KY-761(P)/UPA-59A(V) 152 ارم 75 305 3 CIC 142 432 Intra-Target Data Ind. 32 6.2 ID-1844/UPA-59A(V) 75 3 CIC 142 32 ٦ 5 3 Alarm Monitor 6.3 BZ-173/UPA-59A(V) 75 3 76 CIC 178 127 142 10 7 Cabinet 8 CY-6816/APX-72 EER 7 1 254 203 178 XMTR Set Cont ş ł C-6280/APX 7.1 EER 36 ۰.\* 4

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4 44		11717 (	goe Ictus	******	8 1 - 1994 1 - 1994 1 - 1994 1 - 1994	8	6.11-11 13 <sup>-3</sup> - 1	ры (kPa)	tr <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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7		an a		and the second			· · · ·		1.00	
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				9.00°- 16-1	. Color, channelse	21				Nu Power P/O CY-6816 2544W60 0 400 Hz
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INSTALLATION DATA														
FOLUPMENT	s no.	NTITY	/-10-60Hz	/-30-60Hz	/-30-60Hz	/-10-400Hz	/-30-400Hz		ш	ATION	WEIGHT	HEIGHT	WIDTH	DEPTH
	SWB	αUΔ	115/	115/	450/	115	115	DC	ТҮР	Ę	ibs (N)	in (mm)	in (mm)	in (mm)
Pessive Sonar	462													
Tactical Towed Array Sonar	6													
Winch, Array, Cable	<u>م</u> ۱	1								ETAS RM	15570 69.3k	86 2184	96 2438	80 2032
Levelwind, Fairlead, Bellows	42	1								ETAS RM	1300 5782	12 305	96 2438	24
Winch, Hydraulic Power	Δ3	}			22 K					ETAS RM	1700	36	24	1529
Winch Control	<b>A</b> 4	}								ETAS CONTROL RM	1000	48	24	24
Module Fill Station	45	1								ETAS Rm	300 1334	30 762	24	18 457
Storage Trough	16	,								ETAS RM	2660		7	480
Transformer 60Hz	47	3	50		1					ETAS RM	110	17	9	8
Power Dist Cab	48	1	270		1					ETAS RN1	175	36	24	4
Input Signal Conditioner (ISC)	49	1							1	EER	600		26	23
Advanced Signal Processor (ASP)	410	1							1	EER	214	57	21	18
Acoustic Computer AN/UYQ-L	A11	` I			1					EER	220	20	19	31
Display Console AN/UYO-L	412	,				4300				cie	950	61	29	40
Data Convecter AN/UYQ-L	Δ13	`	<u> </u>			4300		1		EEK	950	72	26	23
Transformer 400 Hz	Δ IA	3				218				TACTASS	30	6	8	7
Acoustic Sensor Data Dist	415		<b> </b>											
	Ť		<u> </u>		1							+		1
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REAL CIOSINA (AIR)	HEAT DISSIPA1 (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	HXDP	PRESSURE	FLOW	PRESSURE	VOLUME/F1. OW		
w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES	
<b>.</b>												
											208V30 WYE Type I 60 Hz 3500 W	
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		, i		ELE	CTRIC	CAL	POWE	R, W			·			
INSTALLATION DATA	NO.	лттү	10-60Hz	30-60Hz	30-60Hz	-10-400Hz	-30-400Hz	-		ATION	WEIGHT	HEIGHT	WIDTH	DEPTH
EQUIPMENT	SWBS	QUAI	1.i5V	115V	450V	115V	115V	DC	ТҮРЕ	гос	ibs (N)	i <del>n</del> (mm)	in (mm)	in (mm)
Active Passive Sonar	463													
Active Dipping Sonar 13-D-AN/AQS-12D	۵													
cevr Indic Assy Rovr R-1695/AQS-13B ndic IP-1045/AQS-13B	<u>۵</u> ۱	1				25				CIC	79 351	25 635	14 356	23 584
Nultiplex Processor Assembly	A2	1								SONAR	43	8 203	9	23 584
Bearing & Rge Indic Assembly ID-1751/AWS-13	43	1								CIC	29			
Recorder Assembly RO-358/AQS-13A	4	1								CIC	33 147	17 432	9 227	13 330
Dome Control Assembly	45	1								SONAR	5 22	5 127	5	7 178
aunch, Reel & Cable Assembly	20	1					4500			50~BR	213 947	36 914	44	26
Transducer Assembly	47	1					1000			SONAR	201	48	15 381	DIA
XDCR HSG & Funnel Assembly	84	1								SOLAR	41 182			
XDCR Cable Attitude Ind.	49	1												
APRAPS (Space & Weight)	Ð									50-42) CIC	9375 41·7 k	¥2		
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		TED	TED		COOL	ING	WATE	ER	Нү	′DR	A	IR	-
	DEPTH	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
Succession of the second													
in the second													
	23 584	135											
	23												28vdc 10a
		9								-			Contains RS & Beam Forming
	13	108											Network
	7												
	26	4500											B/U de Motor for Winch 80a, 28vdc
	660												12 757cm <sup>3/5</sup> gpm 2550 19.6MPa psig motor for winch
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ОЕРТН	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in Imm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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	·			ELE	CTRI	CAL	POWE	R, W						
INSTALLATION DATA												L		
	NO.	гітү	10-60Hz	30-60Hz	30-60Hz	10-400Hz	30-400Hz			TION	WEIGH.	ныдн	WIDTH	DEPTH
EQUIPMENT	SWBS	QUAN	115V-	115V-:	450V-:	115V-	115V-	DC	ТҮРЕ	госл	lbs (N)	in (mm)	in (mm)	in (mm)
PASSIVE ECM DESIGN-TO-PRICE WARFARE SYSTEM AN/SLO-3IV{2}	472 A													and the second
RF ANTENNA/RECEIVER SUBSYSTEM (MID/HIGH BAND)	AI	1	1200				8600			DIST	3045 13.5	*		a sta side is so
RF ANTENNA/RECEIVER SUBSYSTEM (LOW BAND)	A2	1												
IR SENSOR SUBSYSTEM	<u>A3</u>	ł												
AUTO SIGNAL PROCESSOR	A4	1								RER				
COMPUTER AN/UYK-20	<u>A5</u>	1								RER				
GRAPHIC DISPLAY UNIT WITH OPERATOR CONTROL	ALO	1								<u> </u>	ļ			
OFF BOARD DECOY LAUNCHER	A7	2									ļ		 	
BLANKER AN/SLA-10	в		170		<b> </b>					RER	ļ			
BLANKER VIDEO MIXER MX-7544	BI							• • • • • • • • • • • • • • • • • • • •						
BLANKING DISABLE CONTROL C-7132	52	1												
RADIO FREQUENCY SWITCH SA-1512 (60 MC)	63										 -{			
RADIO FREQUENCY SWITCH SA-1513 (160 MC)	в4	1	ļ								<u> </u>	ļ		
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	ED	ED	C	OOLI	NG V	VATE	R	HY	DR	AI	R	
DEPTH	HEAT DISSIPAT (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in nm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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INSTALLATION DATA												<b>L</b>			ISCIDATE
	s NO.	ΝΤΙΤΥ	·-10-60Hz	-30-60Hz		·-10-400Hz	'-30-400Hz		4.1	ATION	WEIGH	HEIGH	WIDTH	DEPTH	HEAT D
EQUIPMENT	SWB:	QUA	115V	115V	450V	115V	115V	DC	ТҮРЕ	FOC	lbs (N)	in (mm)	in (mm)	in (mm)	
FIRE CONTROL SYSTEM (NON-SONAR DATA BASE)	482														
FCS MK92-3	Α.														
COMBINED ANTENNA SYSTEM MK53/I	AI	ł	300		4000						1650 7339	131 3327	96 2438	DIA	
MAN ALOFT SWITCH MKI42/0	AZ	ı									5 22	-	7 178	8 203	ſ
WAVE GUIDE DRYER MKI3 MOD 0	A 3	1	1350							RPR	175 778	25 635	28	28 711	
RADAR XMTR T-1085/SPG-51D	A4		600					50 V 30 V	DC	RPR	1150	78 1981	<b>45</b> 1143	<b>33</b> 838	Ì,
POWER SUPPLY CONTROL C-7714/SPG-51D	A5	1	800					50V 130V	DC AC	RPR	925 4114	78	31	28 711	
RADIO FREQUENCY AMPLIFIER (CAS) MKI67/0	A6	1	250				4200			RPR	940 4181	66	36	32 813	ľ
RADAR RECEIVER - XMTR (CAS) MK69/I	A7		300				5000			RPR	1100	66 1676	36	32	┢
RADAR TEST SET MK574/0	A8	1	400							RPR	100	18 457	22	12	İ,
SERVO CONT' CAB' MKI60/I	A9	,	700				1800			RPR	2000	77	60	29	
WEAPON CONTROL CONSOLE (CAS) MKI06/I	A10	i	900				1800			CIC	1200	20	40	45	
GAS REGULATOR MK21/0		1	100				1000				77	22	21	16	ľ
WAVE GUIDE SW NAVIGATION SWITCH	A12										75	9	7	15	t
CHANNEL SET SWITCH	A13	1	800							KFK	85	36	26	14	
COMPUTER AN/UYK-7(V)	A11	1					2700			DPC	535	41	20	23	ľ
COMPUTER CONTROL C-8542/UYK-7(V)	A16						2			DPC	5	6	7	7	
TEST SET TS-2940/UYK-7(V)	A 16						د می ا			DPr	35	152 19 482	19	6	
I/O COMS (DEAC) 0J-172/UYK-7(V)	A 17	1	486				1900			DPC	470	63	30	34	
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n)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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2	350											· · · · · · · · · · · · · · · · · · ·
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2		4000		3.1	150					3.0	-015	
2		4000	LW	2.5	150	10	·		<u> </u>	3.0	1015	RADAR CABINET
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S NO.	ΝΤΙΤΥ	/-10-60Hz	-30-60Hz	/-30-60Hz	/-10-400Hz	/-30-400Hz		113	ATION	WEIGHT	неіснт	WIDTH	DEPTH
SWB	QUA	115/	115	450\	115/	115/	ğ	ТҮР	гос	lbs (N)	in (mm)	in (mm)	in (mm
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B5	1	900				4200				1100 4893			المعديدين (1) ويوسين المالية. المعديد التاريخ ويوسين
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в7	1	800					Sovac 130	I		925			ji dana
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B9	1	400			<u> </u>					100			
BIO	1					1140		I		500			
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Z       Z       MB2 NO.         B       1       1       1       1       1         B       1       1       1       1       1       1         B       1       1       1       1       1       1       1         B       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1	Image: state stat	No.       No.       No.       No.       No.         B       I       I       I       I       I         B       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 1       1       1       1       1       1         8       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1       1</td> <td><math display="block">\begin{array}{c c c c c c c c c c c c c c c c c c c </math></td> <td><math display="block">\begin{array}{c c c c c c c c c c c c c c c c c c c </math></td> <td><math display="block">\begin{array}{c c c c c c c c c c c c c c c c c c c </math></td>	ON       NO       NO       NO         8       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WIDTH	DЕРТН	HEAT DISSIPAT (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	Psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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DATA														
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$\mathbf{X}$		۲۲	60H2	60Hz	60H2	400F	400			NO	VEIG	HEIG	VIDT	DEPT
COLIIDMENIT	N S N	'NTI	-10-	/-30-(	/-30-	/-10-	/-30-		ш	ATH			>	
	SWB:	QUA	115V	115V	450	115\	115\	ЪС	ТҮРІ	roc	lbs	in	in	in
		-									(N)	(mm)	(mm) 	(mm)
FCS (SUNAR DATA BASE)	483										300			
TORPEDO FC PANEL MK309		1	1760								1334			<u>l</u> ı
MK48 WFCS (SPACE & WEIGHT)	в	1												
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	DEPTH	HEAT DISSIPAI (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDP	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
n m)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
		1700											
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				ELE	CTRI	CAL	POWE	ER, W						
INSTALLATION DATA		•									T	F		And the second
	NO.	TITY	10-60Hz	30-60Hz	30-60Hz	10-400Hz	30-400Hz			TION	WEIGH	HEIGH.	WIDTH	DEPTH
EQUIPMENT	SWBS	QUAN	115V-	115V-:	450V-	115V-	115V-	DC	ТУРЕ	госл	lbs (N)	in (mm)	in (mm)	in (mn
ELECTRONIC TEST MONITORING & CHECKOUT EQUIPMENT	491										२०० 891			and an addition of
FLIGHT CONTROL & INSTALLATION	492													the states of
AN/SRN-{ ) TACAN	4	1												a the transformed for
	۵١	1									100	10 254	52 . 1320	
TRANSPONDER	42	4	2000								500 2224	66 1676	22 559	20 60
ANTENNA CONTROL	43	1									100 445	21 534	19 483	12 39
STATUS INDICATOR	4	1							-		46	8 203	10 254	8 24
														in the second second
OPERATING FLUIDS	498										25 111			and the first of the
COMMAND & SURVEILLANCE REPAIR PARTS & TOOLS	499										1000			an adarbinate statistic
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HOW	DEPTH	HEAT DISSIPA	(AIR) HEAT DISCIDA	(WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
ln nm)	in (mm	) W		w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /mi m <sup>3</sup> /s	n NOTES
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	s no.	ΝΤΙΤΥ	/-10-60Hz	'-30-60Hz	-30-60Hz	/-10-400Hz	/-30-400Hz		444	ATION	WEIGHT	HEIGHT	WIDTH	DEPTH
	SWB	aua	115	115V	450	115/	115	DC	ТУРІ	ГОС	lbs (N)	in (mm)	in (mm)	in (mm)
LAUNCHING DEVICES	721													
VERTICAL MISSILE LAUNCHER	A													
LAUNCHER CANISTER	<b>A</b> 1	8								VERT MISL TRUNK	1150 5115	200 5080	31 787	30
BLAST DEFLECTOR	A 2	ප								VERT MISL	850 3781			1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1
MISSILE/LAUNCHER SEL.	Δ3	١	250							ELEV EAPT Room	200 890	38 %5	18 457	30 162
HARPOON CANISTER LAUNCHER	в						11,220					 		
CANISTER MK6/0	BI	8								OILVL	443 1970	 		100 P
HARNESS ASSEMBLY	B2	8								OILVL	100 445			Assts Perman
LAUNCHER RELAY ASSEMBLY	83	4								OILVL	48 214			last stratic
SUPPORT ASSEMBLY MKI40/0	84	4								OILVL	625 2780			C to be a set of the
HOIST/ROTATION BEAM ASSEMBLY	B5	١												and Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipatric Antipat
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red	red	(	COOL	ING	WATE	R	нү	DR	A	IR	-
HEAT DISSIPA (AIR)	HEAT DISSIPAT	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
			000	nei	[	ncia		anm	nzi	13/min	

			<u> </u>	]					[		[	Ĩ	
55	in			]	gpm	psi	[	psig	Psi	gpm	psi	ft <sup>3</sup> /min	
1	(mm)	w	W		(cm <sup>3</sup> /s)	(kPa)	°c	(kPa)	(kPa)	cm <sup>3</sup> /s	(kPa)	m <sup>3</sup> /s	NOTES
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in the second second	30 762	235											
Selection of the													
and the second second													MISSILE WARMUP - 910 WATTS PER MISSILE MISSILE ELECTRIC POWER 985 WATTS PER MISSILE
millelide													
Mary Links													
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all all the second													8000 WATTS 60 Hz II,220 WATTS 400 Hz
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				ELE	CTRI	CAL	POWE	R, W							TED
INSTALLATION DATA															SIPA
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	o.	₹	60Hz	60Hz	60Hz	400F	4001-			NO	NEIG	DIEH	VIDT	DEPT	EAT
EQUIPMENT	S N(	ITI	-10N	V-30-	V-30-	V-10-	V-30		μ	сати					<b>I</b>
	SWE	0N/	115'	115'	450	115	115	DC	ТҮР	гос	lbs (N)	in (mm)	in (mm)	in (mm)	W
GUNS	711														
CLOSE-IN-WEAPON SYSTEM															
		-2													
LAUNCHING DEVICES															
HARPOON CANISTER	121														
LAUNCHER CANISTER MK6/0	<u> </u>										443				
		8									1970				
LAUNCHER MKI40/0	42	4								DI LUL	2993				;
HOIST ROTATION BEAM ASSEMBLY	A 3	1									25 111				
TOOL KIT	4	1									25 11)				
HARNESS ASSEMBLY	A5	8								OILVL	100				
VERTICAL MISSILE LAUNCHER	в														
LAUNCH CANISTER	ві	8								LIFT FAN ROOM	1150 5115	200 5080	31 787	30 762	
BLAST DEFLECTOR	B2	8								LIFT FAN	850				
MISSILE/LAUNCHER SET	 		250							EER	200	38	18	30	22
	05	- <u>'</u>									890	765	431	/82	
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HEAT DISSIPAI (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
w	•	gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpin cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
<u>,</u>										MISSILE ELECTRIC POWER 785 WATTS PER MISSILE
										HEATER POWER 60 Ω 400 Hz
					 			<u> </u>	+	INCLUDE 4 LAUNCHER RELAY ASSEMBLIES
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				ELE	CTRI	CAL	POW	ER, W						Sec. Shinked and
INSTALLATION DATA											1	Ŧ		and a second second second second
EQUIPMENT	BS NO.	ΑΝΤΙΤΥ	5V-10-60Hz	5V-30-60Hz	0V-30-60Hz	5V-10-400Hz	5V-30-400Hz		PE	CATION	WEIGH	HEIGH	WIDTH	
	SW	au	11	11	45(	11	1	ă	Τ	۲۵	lbs (N)	in (mm)	in (mm)	( <b>1</b>
TORPEDO TUBES	751													Section 24
TORPEDO TUBE MK32	۵	2		5700 11400		1				TOPSIDE	2300 10.2 KN			Last of the Local Society
TORPEDO TUBE MK25 (SPACE & WEIGHT)	B	2												a service data
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		TED	TED	(	COOL	ING \	NATE	R	Нγ	′DR	A	IR	•
WIDTH	DEPTH	HEAT DISSIPA (AIR)	HEAT DISSIPA (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDP	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	P∍i (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>°</sup> , min m <sup>3</sup> /s	NOTES
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				ELE	CTRI	CAL	POWE	ER, W			Į	
INSTALLATION DATA			z	z	z	Hz	Hz				3HT	
EQUIPMENT	/BS NO.	JANTITY	5V-10-60H	5V-30-60H	0V-30-60H	5V-10-400	5V-30-400	0	PE,	DCATION	MEIO	
	MS 7(c)	ğ	11	11	45	11	11	Ď	Ţ	۲۵ ۲۰	IDS (N)	
TORPEDO ACCESSORIES	13											
PRESETTER MK437/0 Test set	13-1	1								HELO HOLGAR	25	
TORPEDO STARBOARD IN CONTAINER MK3I/0	13.2	S									30 133	
SUSPENSION BAND IN CARTON (SET)	13.3	2									14 62	
EXHAUST VALVE ASSEMBLY LD620105 TW88	13.4	2									1 4	
ARMING WIRING MK2/I	13.5	}									17	
NOSE GUARD	13.6	s		с.							9 40	1
PROP GUARD	13.7	2									29	
MK46 RECORD BOOK	13.8	20									1 4	
700/S AND ACCEL. SET MK46	13.9										25	
SMALL ARMS & PYRO STOWAGE	763											-
PYRO MAGAZINES	l	3										1
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	DЕРТН	HEAT DISSIPAT (AIR)	HEAT DISSIPAI (WATER)	TYPE	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW									
1 N)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES								
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INSTALLATION DATA											<b>L</b>	ī		
EQUIPMENT	3S NO.	ANTITY	V-10-60Hz	V-30-60Hz	V-30-60Hz	V-10-400Hz	V-30-400Hz		E	CATION	WEIGHT	HEIGHT	WIDTH	DEPTH
	SWE	Ŋ	115	115	450	115	115	ы В	176	<u>د</u>	lbs (N)	in (mm)	in (mm)	in (mm
AIRCRAFT WEAPONS HANDLING	782										ļ			
OVERHEAD ELECTRIC HOIST/TRACK	1	1								TORP RM	400			
MK45/I HANDLIFT TRUCK	2	S		L						TORP RM	128 569	45 1143	29 737	55
MK24/0 HANDLING DOLLY	3	1							<b> </b>	TORP MAG	200	610	22 559	238
MK28/I HANDLIFT TRUCK ADAPTOR	4	2								MK 46 TOEP MAG	22 98	10 254	406	4
MK99/0 WEAPONS HANDLING SLING	5	_1					 			TORP MAC	120			
TORPEDO SLING MKI02/0	G	2						ļ		TORP MACT	4			
TORPEDO SLING MKI06/0	7	2								TORP MAG	4			
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AIRCRAFT WEAPONS STOWAGE	783					ļ								
STOWAGE CHOCKS	1	40 5ETS								MAG	534	ļ		
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HIGIM	DEPTH	HEAT DISSIPA1 (AIR)	HEAT DISSIPA1 (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	нхор	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
in im)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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				ELE	CTRI	CAL	POWI	ER, W						
INSTALLATION DATA											-			
	s no.	NTITY	/-10-60Hz	·-30-60Hz	/-30-60Hz	/-10-400Hz	/-30-400Hz		ш	ATION	MEIGHI	HEIGHT	WIDTH	DEPTH
EddiFineIV1	SWB:	QUA	115V	115V	450	115/	115/	SC	ТҮР	гос	lbs (N)	in (mm)	in (mm)	in (mm)
SHIP AMMUNITION	F2)													
HARPOON MISSILE RGM-84-1	4	B								OI LVL	1530 6800			
STANDARD MISSILE RIM-66B	в	8									1373 6100			
SMALL ARMS AMMUNITION	c	-								AMMO LCKR	935 4700			
BT PROBES DC-14/SSQ-56	D	సెంం								TOCTOS EQPT RM	2			
TORPEDO MK46-I	ព	J									530 2357			
TORPEDO MK48	п	2									3600			
CLOSE-IN-WEAPONS SYSTEM AMMUNITION	ß										4000 17800			
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TORPEDO MK46-I	4	34									530 2357			
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	TED	TED		COOL	ING	WATE	R	нү	'DR	A	IR	
	HEAT DISSIPA (AIR)	HEAT DISSIPAT (WATER)	ТҮРЕ	FLOW	PRESSURE	TEMP IN	НХDР	PRESSURE	FLOW	PRESSURE	VOLUME/FLOW	
-China	w	w		gpm (cin <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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DATA													
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	Ŋ.	ודודע	10-60	30-601	30-601	10-40	30-40			NOIT	WEI	ΞH	MID
EQUIPMENT	SWBS	DUAN	115V-	15V-:	150V-;	115V-	115V-:	Ŋ	ГУРЕ	LOCA	lbs	in	in .
ORDNANCE DELIVERY SYSTEM					~	<b>*</b> -	-,				(N)	(mm)	(mm)
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in (mm)	in (mm)	w	w		gpm (cm <sup>3</sup> /s)	psi (kPa)	°c	psig (kPa)	psi (kPa)	gpm cm <sup>3</sup> /s	psi (kPa)	ft <sup>3</sup> /min m <sup>3</sup> /s	NOTES
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